# Fiammetta, Finite Element Method Applied to Heat Transfer

# – Tutorials –

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The six lectures on Finite Elements applied to heat transfer, of which this document constitutes the tutorial, deal respectively with conduction, convection and radiation, first in steady state, then, with the fourth lecture, in transient state; the third lecture describes the isoparametric elements, which make it possible to generalize to any geometry what has been described before on the simplest shape: a rectangle meshed by squares. The last lecture is devoted to the radiative exchanges.

The aim of this course is to explain in a simple and concise way the basis of the Finite Element Method for the study of thermal problems, including radiative exchanges, as in the case of buildings exposed to solar radiation, and finally to express the surface temperature field, such that it could be captured, in the real world, by a thermal camera placed in front of these buildings.

The tutorial presents short programs, written in Matlab<sup>©</sup>, which are progressively developed in conduction, convection, radiation and transient regime. Each step is completed by an exercise that will allow the reader becoming familiar with the main features presented in the lectures.

### 1. Tutorial I: Basic problem of thermal conduction

#### 1.1 Finite element model

In each sub-domain or finite element numbered *i*, a Rayleigh-Ritz is applied. The temperature  $\tau_i$  of element *i* is discretized by bilinear polynomial functions associated to four nodal temperatures  $T_{ij}$  of the vertices (*Figure 1*).

$$\tau_i = \sum_{j=1}^4 T_{ij} f_{ij} \left( x, y \right) \tag{1}$$

Explicitly, for a square of dimension *a*, we have:

$$\tau_{i} = T_{i1} \left( 1 - \frac{x}{a} \right) \left( 1 - \frac{y}{a} \right) + T_{i2} \frac{x}{a} \left( 1 - \frac{y}{a} \right) + T_{i3} \frac{x}{a} \frac{y}{a} + T_{i4} \left( 1 - \frac{x}{a} \right) \frac{y}{a}$$
(2)

This definition allows computing the conduction matrix of the square (*Figure 1*). This matrix does not depend on its size, but only on the conductivity coefficient k and the thickness e. The figure shows the square element and its degrees of freedom (*DOF*). The element nodes are always presented in the counterclockwise sequence of the figure.



Figure 1: A square element and its conductivity matrix

The contributions of the finite elements of the domain are added to build the discretized global functional I(T):

$$< I(T) = \sum_{i=1}^{nel} \left( \int_{\Omega_j} \frac{1}{2} k_i \, \vec{\nabla} \sum_{j=1}^4 T_{ij} f_{ij} . \, \vec{\nabla} \sum_{j=1}^4 T_{ij} f_{ij} \, d\Omega_i + \int_{S_{2i}} \overline{q}_n \, \sum_{j=1}^4 T_{ij} f_{ij} \, dS_i \right) >$$
(3)

After introducing the polynomial trial functions given in (2), we can write (3) in matrix form:

$$< I(T) = \sum_{i=1}^{nel} \begin{bmatrix} T_i \end{bmatrix}^T \begin{bmatrix} K_i \end{bmatrix} \begin{bmatrix} T_i \end{bmatrix} + \begin{bmatrix} T_i \end{bmatrix}^T \begin{bmatrix} F_i \end{bmatrix} >$$
(4)

The last term  $[F_i]$  of (4) is the vector of generalized heat loads.

In the next step, we have to express the continuity of the temperature field across the domain. At each interface between two elements, it must be stated that the nodal temperature field is identical, which means that the nodal temperatures of the elements sharing a same node are the same. In the mesh of *Figure 2*, the third node of element 3, the fourth of element 4, the second of element 5 and the first of element 6 are assigned to the global node 8.



Figure 2: Node and element numbering

The temperature gradients are obtained by derivation of the element temperature field *Figure* l, but now, we extend the shape to a rectangle of dimensions  $a \ge b$ :

$$\tau = T_1 \left( 1 - \frac{x}{a} \right) \left( 1 - \frac{y}{b} \right) + T_2 \frac{x}{a} \left( 1 - \frac{y}{b} \right) + T_3 \frac{x}{a} \frac{y}{b} + T_4 \left( 1 - \frac{x}{a} \right) \frac{y}{b}$$
(5)

\_ \_ \_

It is easy to derive this polynomial expression:

$$\begin{bmatrix} \frac{\partial \tau}{\partial x} \\ \frac{\partial \tau}{\partial y} \end{bmatrix} = \begin{bmatrix} \frac{1}{a} \left( \frac{y}{b} - 1 \right) & \frac{1}{a} \left( 1 - \frac{y}{b} \right) & \frac{y}{ab} & -\frac{y}{ab} \\ \frac{1}{b} \left( \frac{x}{a} - 1 \right) & -\frac{x}{ab} & \frac{x}{ab} & \frac{1}{b} \left( 1 - \frac{x}{a} \right) \end{bmatrix} \begin{bmatrix} T_1 \\ T_2 \\ T_3 \\ T_4 \end{bmatrix}$$

$$\begin{bmatrix} \frac{\partial \tau}{\partial x} \\ \frac{\partial \tau}{\partial y} \end{bmatrix} = \frac{1}{ab} \begin{bmatrix} y - b & b - y & y & -y \\ x - a & -x & x & a - x \end{bmatrix} \begin{bmatrix} T_1 \\ T_2 \\ T_3 \\ T_4 \end{bmatrix}$$
(6)

In the center (x = a/2, y = b/2) of the rectangular element we obtain:

$$\frac{\partial \tau}{\partial x} = \frac{1}{2a} \left( \left( T_2 + T_3 \right) - \left( T_1 + T_4 \right) \right)$$

$$\frac{\partial \tau}{\partial y} = \frac{1}{2b} \left( \left( T_3 + T_4 \right) - \left( T_1 + T_2 \right) \right)$$
(7)

The gradients are sensitive to the dimension of the object or of the element because they depend on the metrics. The heat flow is deduced from the gradient by the Fourier law.

$$\begin{bmatrix} q_x \\ q_y \end{bmatrix} = -k \begin{bmatrix} \frac{\partial \tau}{\partial x} \\ \frac{\partial \tau}{\partial y} \end{bmatrix}$$
(8)

The heat flow  $(Wm^{-2})$  is in the opposite direction of the gradient and, in homogeneous isotropic mediums, proportional to the conductivity coefficient  $k (WK^{-1}m^{-1})$ .

#### 1.2 Innovative handling of the Dirichlet boundary conditions

The Matlab<sup>©</sup> procedure of *Table 1* exhibits a basic finite element program. In the first example, we impose constant temperatures on the nodes located on both horizontal sides. The size of the domain is  $l \ge h \ge 2 m \ge 1 m \ge 2 m \ge 1 m$ . To run this example, we write that the concerned nodal temperatures are equal to some value. We have thus as many restraints as imposed temperatures which are added to the system with Lagrange multipliers.

The system of constraints is:

$$\begin{bmatrix} N \end{bmatrix} \begin{bmatrix} T \end{bmatrix} = \begin{bmatrix} \overline{T} \end{bmatrix}$$
(9)

In this expression [T] is the uni-column matrix (or vector) of nodal temperatures and [N] a matrix with as many lines as fixed nodes and the same number of columns as the size of [T]. Each line contains only zero and one in the column corresponding to the fixed node. With the matrix of constrains we define a new term (blue) in the functional thanks to the Lagrange multipliers  $[\Lambda]$ :

$$< I(T) = [T]^{T} [K] [T] + [\Lambda]^{T} ([N] [T] - [\overline{T}])$$
<sup>(10)</sup>

The Euler equations are obtained by derivations of the functional with respect to  $[\Lambda]$  and [T]:

- 1. derivative with respect to the Lagrange multipliers is restoring equation (9)
- 2. derivative with respect to [*T*]:

$$[K][T] + [N]^{T} [\Lambda] = [0]$$
<sup>(11)</sup>

The second member of this equation is equal to zero because the von Neumann boundary conditions are not considered (there are not nodal loads). Combining (9) and (11), yields to the system:

$$\begin{bmatrix} K & N^T \\ N & 0 \end{bmatrix} \begin{bmatrix} T \\ \Lambda \end{bmatrix} = \begin{bmatrix} 0 \\ \overline{T} \end{bmatrix} \rightarrow [A] [B] = [G]$$
(12)

The uni-column matrix [G] contains a sequence with zero values of the same size as [T] followed by a sequence of the values of the imposed temperatures  $[\overline{T}]$ . The unknown vector [B] contains the full set of nodal temperature including the imposed ones and the Lagrange multipliers which represent the generalized heat flows through the nodes. Unlike the matrix [K], the matrix [A] is nonsingular if the restraints are independent.

#### Matlab<sup>©</sup> procedure *Fiammetta.m*

```
r=1 ;nx=1*r;ny=2*nx;ii=0;nn=(nx+1)*(ny+1);xy =zeros(nn,2);CPU=tic;
                                          % Geometry: definition of nodal coordinates
 2
    for j = ny + 1:-1:1
        for i=1:nx+1; ii = ii+1; xy (ii,1) = i-1; xy (ii,2) = j-1;end
 3
   end % ;if nn<20;disp([(1:nn)' xy]);end</td>% Display nodal coordinatesdisp(['Number of nodes: ',num2str(nn)])% End geometry definitionne= nx*ny; 1K = zeros(ne,4); m = 0;% Topology: mesh definition
 4
 5
 6
   ne
 7
    for j
                 = 1:ny
 8
         for i
                  = 1:nx
 9
            m = m+1;lK(m,1) = nn-nx-1+i-(j-1)*(nx+1); lK(m,2) = lK(m,1) + 1;
10
                          lK(m, 3) = lK(m, 2) - nx - 1
                                                                  ; lK(m, 4) = lK(m, 3) - 1;
11
         end
    end;disp(['Number of elements : ',num2str(ne)]) % End topology definition
```

```
n1
       = (nx/r) + 1; nf = 2*n1;
                                             % Dirichlet boundary conditions
14
   lfi = [nn:-1:nn-n1+1 1:n1];fT=[ones(1,n1)*270 ones(1,n1)*320];
15
   disp(['Numb. of fix. temp. : ',num2str(nf)]);
16
                                           % von Neumann boundary conditions
   gh = zeros(nn, 1);
17
   co = ones(ne,1);% co=mat cok(nx,ny);
                                           % Element thickness * conductivity
18 K = zeros(nn,nn); & Global conductivity matrix K initialization & assembly
                                                         % Loop on ne elements
19 for n
          = 1:ne
       Ke = co(n) * [4 -1 -2 -1; -1 4 -1 -2; -2 -1 4 -1; -1 -2 -1 4]/6;
20
21
     for i = 1:4; for j=1:4; K(lK(n,i), lK(n,j))=K(lK(n,i), lK(n,j))+Ke (i,j);
22
           end;end;
                          % End of assembling the ne conductivity matrices Ke
23
   end
24 N
          = zeros(nf,nn);G=[qh;zeros(nf,1)];% Initializing linear constraints
25
          = 1:nf;N(i,lfi(i))=1;G(nn+i)=fT(i);end % Building the equ. system
   for i
26
          = [K N';N zeros(nf,nf)];B = A\G;T = B(1:nn);
                                                                    % Solution
   А
27
   figure; for i=1:ne; fill(xy(lK(i,:),1)',xy(lK(i,:),2)',T(lK(i,:)));
28
       hold on; axis equal; end; colorbar; axis off
29 disp(['Dissipation .....: ',num2str(T'*K*T/2,3),' WK'])
30 disp(['CPU .....: ',num2str(toc(CPU),3),' sec. '])
31
   % figure;colormap(gra_cob);gra_ist(nx,ny,T,xy,[min(T) 2 max(T)])%Isotherms
32
   % colorbar;axis equal;axis off
     if ne < 100;gra mnl(xy,lK,[0 0 0]);axis equal;axis off;end
33
   2
```

Table 1: Matlab<sup>©</sup> procedure Fiammetta.m - Conduction problems

With the parameter r = 1, (*line 1* of *Table 1*), the result (*Figure 3*) is the exact solution, independent of the mesh.



Figure 3: Temperature levels obtained in a program using exclusively Matlab<sup>®</sup> functions

Disabling *lines 27 & 28* and enabling the use of function *gra\_cob.m* (*Table 2*) and *gra\_ist.m* (*Table 3*) in *line 31 & 32*, we get better colors (*Figure 4, left*). The use of the function *gra\_ist.m* instead of the Matlab<sup>©</sup> function *fill*, gives the graphics with isotherm lines (*Figure 4, right*).



Figure 4: Example with imposed temperatures producing a vertical gradient

If the difference of temperatures is equal to 50 K and if the temperatures are constant on both horizontal sides, the quantities of incoming heat on the top side and outgoing one in the base are identical and given by the heat flow integrated on a horizontal section:

$$le k \frac{\Delta T}{\Delta y} = k \frac{50}{2} = 25 \quad W \tag{13}$$

Added at the end of the procedure, the following line provides the input and output nodal generalized heat flows on the horizontal sides. The sum of the top flows is equal to the sum of the bottom ones and their modules are both equal to 25 W.

```
34 hl=B(nn+1:nn+nf);disp(['Heat input & output : ',num2str(hl'),' W'])
```

The input heat flows are the Lagrange multipliers of the top side, for instance the nx + 1 first terms of [ $\Lambda$ ], nx is the number of elements in the x direction.

In *Figure 4*, on the horizontal sides, each inner node links two element edges, but the outer ones only connect one. At the extremities of the sides, the second members are equal to half the others. Due to the homogeneity of the imposed temperatures, the nodal heat loads are equal to the total load computed in (9): 25 *W* divided by the number of elements 25/nx *W* for inner nodes and half this value for the others: 25/(2 nx) *W*.

If nx = 5, in Matlab<sup>©</sup> notation, the reactive generalized heat flows of the top horizontal side given by: disp(['hf = ', num2str(B(nn+1:nn+nf/2)')])

are: hf = 2.5 5 5 5 5 2.5 W

With Dirichlet boundary conditions (*lines 13 - 15*) we obtain the solutions shown in *Figure 5*.



Figure 5: Imposed temperatures on parts of the horizontal faces (nx = 30 & 50)

### 1.3 Matlab procedure for the basic conduction problem

To perform tests on conduction, we use the procedure of *Table 1*, first in a simplified presentation, and later in its definitive form. The acronym Fiammetta means: Finite Element Method and Isoparametric Meshing Applied to Transient Thermal Analysis.

In the beginning of this document, the finite element model is limited to a rectangle composed of squares (*Figure 2*). The temperature is always expressed in Kelvin (K).

The Matlab<sup>©</sup> procedure of *Table 1* is providing one single output: the visualization of the domain with colored temperature levels (*Figure 6*). This graphics is generated in the *lines* 27 - 16

29 of *Fiammetta\_33\_20210830.m*, using the standard Matlab<sup>©</sup> function *fill*. In *line 27*, to obtain a high-quality color bar, we are also using the function  $gra\_cob.m$  (*Table 2*), which is providing a very effective color bar at the right of *Figure 6*. The conductivity coefficients are specified in the vector *co* (*ne* components with *ne*, the number of elements) at *line 17* of the procedure. It is possible to define other distributions of conductivity (one per element).



The extra command described below can be inserted after running *Fiammetta.m* for drawing the border of the domain with thick black lines (*Figure 7, right*).

34 plot ([0 nx nx 0 0],[0 0 ny ny 0],'k','LineWidth',2);hold on;axis equal

N	Matlab <sup>©</sup> function <i>gra_cob.m</i>								
1	function	[bar] =	gra_cob						
2	bar=[ 0	0	0.5625						
3	0	0	0.6250						
4	0	0	0.6875						
5	0	0	0.7500						
6	0	0	0.8125						
7	0	0	0.8750						
8	0	0	0.9375						
9	0	0	1.0000						
10	0	0.0625	1.0000						
11	0	0.1250	1.0000						
12	0	0.1875	1.0000						
13	0	0.2500	1.0000						
14	0	0.3125	1.0000						
15	0	0.3750	1.0000						
16	0	0.4375	1.0000						
17	0	0.5000	1.0000						
18	0	0.5625	1.0000						
19	0	0.6250	1.0000						
20	0	0.6875	1.0000						
21	0	0.7500	1.0000						
22	0	0.8125	1.0000						
23	0	0.8750	1.0000						
24	0	0.9375	1.0000						
25	0	1.0000	1.0000						
26	0.0625	1.0000	0.9375						
27	0.1250	1.0000	0.8750						
28	0.1875	1.0000	0.8125						
29	0.2500	1.0000	0.7500						
30	0.3125	1.0000	0.6875						

31	0.3750	1.0000	0.6250
32	0.4375	1.0000	0.5625
33	0.5000	1.0000	0.5000
34	0.5625	1.0000	0.4375
35	0.6250	1.0000	0.3750
36	0.6875	1.0000	0.3125
37	0.7500	1.0000	0.2500
38	0.8125	1.0000	0.1875
39	0.8750	1.0000	0.1250
40	0.9375	1.0000	0.0625
41	1.0000	1.0000	0
42	1.0000	0.9375	0
43	1.0000	0.8750	0
44	1.0000	0.8125	0
45	1.0000	0.7500	0
46	1.0000	0.6875	0
47	1.0000	0.6250	0
48	1.0000	0.5625	0
49	1.0000	0.5000	0
50	1.0000	0.4375	0
51	1.0000	0.3750	0
52	1.0000	0.3125	0
53	1.0000	0.2500	0
54	1.0000	0.1875	0
55	1.0000	0.1250	0
56	1.0000	0.0625	0
57	1.0000	0	0];
58	end		

Table 2: Matlab<sup>©</sup> function  $gra\_cob.m$  - color bar

	Matlab <sup>©</sup> function <i>gra_ist.m</i> - isotherm drawing
1	<pre>function [] = gra_ist (nx,ny,z,xyz,gt)</pre>
2	<pre>no = (nx+1)*(ny+1);ii = 0; % Number of points of the grid</pre>
3	<pre>xx = zeros(ny+1,nx+1);yy = xx;tn = ones(ny+1,nx+1)*z(1); % Initializations</pre>
4	for i = 1:ny
5	<pre>for j = 1:nx+1; ii = ii+1; tn(i,j) = z(ii); end;</pre>
6	end
7	tn(ny+1,:) = z(ii+1:no); jj = 0;
8	for i = 1:ny+1
9	<pre>for j = 1:nx+1;jj = jj+1;xx(i,j) = xyz(jj,1);yy(i,j) = xyz(jj,2);end</pre>
10	end
11	colormap(gra cob); % Color map definition
12	<pre>[CS,H] = contourf(xx,yy,tn,(gt(1):gt(2):gt(3)),'b');hold on;axis equal</pre>
13	clabel(CS,H,[ 280 285 290 295 300 305 310 315 320]);
14	<pre>plot ([0 nx nx 0 0],[0 0 ny ny 0],'k','LineWidth',2);hold on;axis equal</pre>
15	end

*Table 3: Matlab<sup>©</sup> function gra\_ist.m - isotherm drawing* 

It is useful to remember some specifications of the variables: *B*, *G*, *T* are uni-column matrices, while, lfi and fT are uni-line matrices.

The drawings of *Figure 8* are obtained with a command calling *gra\_ist.m* (*Table 3*), which is more efficient to represent isotherms than the Matlab command *fill*.



*Figure 8: Temperature levels obtained with gra\_ipa.m Matlab<sup>©</sup> function (Table 69)* 

On the left of *Figure 8*, we see the isothermal curves for a 7 x 14 mesh. On the right, with the same Dirichlet boundary conditions, we have the result for a 20 x 40 mesh. As explained in *Table 72*, the number of fixed nodes is the same for both tests, which means that the temperature peaks are sharper in the finer mesh. Both drawings are obtained with the function  $gra\_ist.m$  (*Table 3*).

#### **1.4 Neumann boundary conditions**

To introduce the heat fluxes, we use the functional presented in the first lecture.

$$< I(\tau) = \int_{\Omega} \frac{1}{2} k \, \vec{\nabla} \tau . \, \vec{\nabla} \tau \, d\Omega + \int_{S_2} \overline{q}_n \, \tau dS > \min m m m$$
(14)

Limiting the demonstration to one element edge, we can write that the second term of the above functional corresponds to the sum of products of generalized nodal heat flows  $g_i(W)$  by temperatures  $T_i(K)$  and we can write it as follows:

$$\int_{S_{2edge}} \bar{q}_n \tau \ d \ S_{el} = g_1 T_1 + g_2 T_2 \tag{15}$$

We express the edge temperature in term of edge weight functions

$$\tau_{edge} = T_1 \left( 1 - \frac{x}{l} \right) + T_2 \frac{x}{l}$$
(16)

We can write the discretized functional:

$$\int_{S_{2edge}} \overline{q}_n \tau dS_{el} = \int_{S_{2edge}} \overline{q}_n \left( T_1 \left( 1 - \frac{x}{l} \right) + T_2 \frac{x}{l} \right) dS_{el}$$
(17)

In matrix form, we have:

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With: 
$$\begin{bmatrix} T \end{bmatrix} = \begin{bmatrix} T_1 \\ T_2 \end{bmatrix}$$
 we have:  $\int_{S_{2edge}} \overline{q}_n \tau dS_{el} = \int_{S_{2edge}} \overline{q}_n \left[ \left( 1 - \frac{x}{l} \right) \frac{x}{l} \right] \begin{bmatrix} T_1 \\ T_2 \end{bmatrix} dS_{el}$  (18)

We can now get the nodal temperatures out of the integral:

$$\int_{S_{2edge}} \overline{q}_n \tau dS_{el} = \int_{S_{2edge}} \overline{q}_n \left[ \left( 1 - \frac{x}{l} \right) \quad \frac{x}{l} \right] dS_{el} \left[ \begin{array}{c} T_1 \\ T_2 \end{array} \right]$$
(19)

Finally, we can write the prescribed second member in matrix form:

$$\begin{bmatrix} F_1 \\ F_2 \end{bmatrix}^T = \int_{S_{2edge}} \overline{q}_n \left[ \left( 1 - \frac{x}{l} \right) \quad \frac{x}{l} \right] dS_{el}$$
(20)

To run the example of *Figure 9*, we replace the *lines 13* to *15* in *Fiammetta.m* by the instructions of *Table 4*.

*Table 4: Instructions substituted to lines 16, 17 & 19 in Fiammetta\_33\_20210830.m* 

The high quality isotherms of *Figure 9* are obtained by running the instructions 34 to 36 of the procedure *Fiammetta.m*.

We have obtained the general method to build the second members of the heat transfer equations corresponding to the imposed heat flows. If the prescribed heat flow is constant on the edge, for an edge of length l and a thickness e, we obtain:

$$F_1 = \overline{q} \, \frac{el}{2} \quad ; \quad F_2 = \overline{q} \, \frac{el}{2} \tag{21}$$



Figure 9: Isocurves for the problem with prescribed heat flows

### **1.5 Matlab<sup>©</sup> procedure:** *Fiammetta.m* (*Table 1*)

*Line 1* : input data.

The variables nx and ny define the number of elements in the horizontal and vertical directions. The variable nx is imposed as a multiple of r.

*Lines* 2 - 5 : are providing the grid of (nx + 1)(ny+1) nodes.

*Lines* 6 - 12: localization matrix *lK* of the *ne* = *nx* x *ny* elements.

*Lines* 13 - 15 : Dirichlet boundary conditions: data for fixed temperatures.

In the examples proposed in this chapter, we fix some nodal temperatures on the horizontal sides, starting from opposite corners: left on the top, right in the bottom. The number *nf* of fixed temperatures is given by the relation: nf = 2 \* ((nx / r) + 1). Due to the definition of nx, nx / r is an integer. As a consequence, it is easy to impose the proportion of fixed nodes on the horizontal sides.

*Line 16* : von Neumann boundary conditions, nn terms of the second member may be imposed.

*Line* 17 : Material properties: thickness in *m* and conductivity in WK<sup>-1</sup>m<sup>-1</sup>.

*Lines* 18 - 23: Creation of the element conductivity of a square and assembly of the global conductivity matrix.

```
18 K = zeros(nn,nn);% Global conductivity matrix K initialization & assembly
19 for n = 1:ne % Loop on ne elements
20 Ke = co(n)*[4 -1 -2 -1;-1 4 -1 -2;-2 -1 4 -1;-1 -2 -1 4]/6;
21 for i = 1:4; for j=1:4; K(lK(n,i), lK(n,j))=K(lK(n,i), lK(n,j))+Ke (i,j);
22 end; end; % End of assembling the ne conductivity matrices Ke
23 end
```

The external loop is performed on the *ne* elements and the two internal loops are performed on the lines and columns of the element conductivity matrices. Each term (i, j) of element *n* is located at (lK (n, i), lK (n, j)) in the global *K* matrix according to the *lK* matrix computed in the sequence of *lines* 6 - 12.

*Line 20* : conductivity matrix of a square element (*Figure 1*)

Ke = [4 -1 -2 -1; -1 4 -1 -2; -2 -1 4 -1; -1 -2 -1 4]/6;

This matrix has to be multiplied by the thickness and the conductivity coefficient computed in *line 17* (vector *co*). This matrix is expressed in W.

*Lines* 24 - 26: Solution of the system of equations involving the linear constraints. Its dimension is nn + nf. The uni-column matrix *G* contains the *nn* loads (here equal to zero) and the *nf* imposed temperatures *fT*. *B* is the uni-column matrix of the *nn* unknown nodal temperatures *T* and the *nf* reactive flows.

*Line* 27 : Definition of a color bar with the Matlab function *gra\_cob.m* (*Table 2*).

*Line* 28 : Drawing the temperature levels with the Matlab function *fill*.

*Line* 29 - 30 : End of the drawing sequence. Display of global results and processing time.

*Lines 31 - 32* : Alternative visualization of the isotherms

*Line* 33 : Optional display of the mesh with node and element numbers (*Table 5*: *Localization matrix for the 2 x 4 mesh of Figure 2Table 5*).

					1 3
disp([(	1:8)'	lK]):			7 8
1	13	14	11	10	
2	14	15	12	11	
3	10	11	8	7	5 6
4	11	12	9	8	9
5	7	8	5	4	3 4
6	8	9	6	5	12
7	4	5	2	1	
8	5	6	3	2	1 2
					13 14 15

Table 5: Localization matrix for the 2 x 4 mesh of Figure 2

### 2. Tutorial II: Convection

In this chapter, we consider that the conductive model is immersed in a fluid, either liquid or gaz. Heat exchanges are assumed to act globally. In the previous chapter, the conductive medium was always limited by a perfectly reflecting surface (mirror) except where temperatures are imposed.

### 2.1 Formulation of the convection

The partial differential equations of the convective heat transfer problem come from the stationarity conditions of the functional:

$$< I(\tau) = \int_{\Omega} \frac{1}{2} k \, \vec{\nabla} \tau \, . \, \vec{\nabla} \tau \, d\Omega + \frac{1}{2} \int_{S_3} h \left(\tau - \tau_f\right)^2 dS + \int_{S_2} \overline{q}_n \, \tau dS > \text{minimum}$$
(22)

The Rayleigh Ritz procedure is the same as in the conduction problem, so we can directly examine how to compute the "*conductivity*" matrices of the convective elements.

Functional at element level: 
$$I_{el} = \frac{1}{2} \int_{S_3} h(\tau - \tau_f)^2 dS$$
 (23)

In (22) and (23), *h* represents the convection coefficient. The fluid temperature  $\tau_f$  is assumed uniform. We study an element edge that is a line segment of length *L*. We discretize the edge temperature as follows:

$$\tau = T_0 (1 - \frac{x}{L}) + T_1 \frac{x}{L}$$
(24)

In this expression x varies between 0 and L. Replacing in the functional (23), we obtain:

$$I_{el} = \frac{1}{2} \int_{0}^{L} h \left( \left[ 1 - \frac{x}{L} \quad \frac{x}{L} \right] \left[ \frac{T_{0}}{T_{1}} \right] - t_{f} \right)^{L} dx$$

$$= \frac{1}{2} h \int_{0}^{L} \left\{ \left[ T \right]^{T} \left[ \frac{1 - \frac{x}{L}}{L} \right] \left[ 1 - \frac{x}{L} \quad \frac{x}{L} \right] \left[ T \right] - 2 \left[ 1 - \frac{x}{L} \quad \frac{x}{L} \right] \left[ T \right] t_{f} + t_{f}^{2} \right\} dx$$

$$(25)$$

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With a new definition of the nodal temperatures vector including the fluid temperature, we obtain with the notation  $t_f = T_f$ , where we assimilate the fluid temperature to that of a virtual node<sup>1</sup>:

$$\begin{bmatrix} T_{el} \end{bmatrix} = \begin{bmatrix} T_0 & T_1 & T_f \end{bmatrix}^T$$
(26)

 $[T_{el}]$  is the vector containing the set of nodal temperatures related to one element. Replacing in (25), we obtain:

$$I_{el} = \frac{1}{2} h T_{el}^{T} \left( \int_{0}^{L} \left[ \begin{array}{c} 1 - \frac{x}{L} \\ \frac{x}{L} \\ -1 \end{array} \right] \left[ 1 - \frac{x}{L} \quad \frac{x}{L} \quad -1 \right] dx \right) T_{el}$$
(27)

Developing the expression:

$$I_{el} = \frac{1}{2}hT_{el}^{T} \int_{0}^{L} \left[ \begin{pmatrix} 1 - \frac{x}{L} \end{pmatrix}^{2} & \left( 1 - \frac{x}{L} \right) \frac{x}{L} & -\left( 1 - \frac{x}{L} \right) \\ \left( 1 - \frac{x}{L} \right) \frac{x}{L} & \left( \frac{x}{L} \right)^{2} & -\frac{x}{L} \\ -\left( 1 - \frac{x}{L} \right) & -\frac{x}{L} & 1 \end{bmatrix} dx T_{el}$$
(28)

After integrating and including the thickness e to ensure the coherence of units, we transform the functional (28) into an algebraic function of the nodal temperatures:

$$I_{el} = \frac{1}{2}h \ e \ T_{el}^{T} \begin{bmatrix} \int_{0}^{L} \left(1 - \frac{x}{L}\right)^{2} dx & \int_{0}^{L} \left(1 - \frac{x}{L}\right) \frac{x}{L} dx & -\int_{0}^{L} \left(1 - \frac{x}{L}\right) dx \\ \int_{0}^{L} \left(1 - \frac{x}{L}\right) \frac{x}{L} dx & \int_{0}^{L} \left(\frac{x}{L}\right)^{2} dx & -\int_{0}^{L} \frac{x}{L} dx \\ -\int_{0}^{L} \left(1 - \frac{x}{L}\right) dx & -\int_{0}^{L} \frac{x}{L} dx & \int_{0}^{L} dx \end{bmatrix} T_{el}$$
(29)

The integrals present in the discretized functional are easily computed:

$$\int_{0}^{L} \left(1 - \frac{x}{L}\right)^{2} dx = \int_{0}^{L} \left(1 - 2\frac{x}{L} + \frac{x^{2}}{L^{2}}\right) dx = L - L + \frac{L}{3} = \frac{L}{3}$$
(30)

$$\int_{0}^{L} \left(1 - \frac{x}{L}\right) \frac{x}{L} dx = \int_{0}^{L} \left(\frac{x}{L} - \frac{x^{2}}{L^{2}}\right) dx = \frac{L}{2} - \frac{L}{3} = \frac{L}{6}$$
(31)

<sup>&</sup>lt;sup>1</sup> The virtual nodes are not related to a position, they do not have any coordinate. However, to represent them like in *Figure 11*, we give them an arbitrary position, only for the drawing.

$$-\int_{0}^{L} \left(1 - \frac{x}{L}\right) dx = -L + \frac{L}{2} = -\frac{L}{2}$$
(32)

The final expression of the integral related to convection is then:

$$I_{el} = \frac{1}{2}h \ eL \ T_{el}^{T} \begin{bmatrix} \frac{1}{3} & \frac{1}{6} & -\frac{1}{2} \\ \frac{1}{6} & \frac{1}{3} & -\frac{1}{2} \\ -\frac{1}{2} & -\frac{1}{2} & 1 \end{bmatrix} T_{el} = \frac{1}{2}T_{el}^{T} \ K_{h} \ T_{el}$$
(33)

From this expression, we deduce the conductivity matrix for convection, so called because it is expressed in  $WK^{-1}$ .

$$K_{h} = \frac{ehL}{6} \begin{bmatrix} 2 & 1 & -3\\ 1 & 2 & -3\\ -3 & -3 & 6 \end{bmatrix}$$
(34)

As well as the pure conduction matrix, this matrix is singular. It means that, with or without convection, it is necessary to fix at least one node (real or virtual) in order to make the conductivity matrix positive definite. To solve a problem including conduction and convection, we have to compute two kinds of conductivity matrices. We call the first one  $K_k$  and the second one  $K_h$ . Later, both matrices have to be added. The second one carries additional degrees of freedom corresponding to the virtual convective nodes.

$$K = K_k + K_h \tag{35}$$

The convection virtual nodes may be free or fixed. The convection matrix defined in (34) is computed in the function *fem\_Kcv.m* (*Table 6*). The input is the matrix *xyz* of node coordinates, the localization matrix lc of the convective element and the coefficient *hh*, product of the thickness by the convection coefficient.

	Matlab <sup>©</sup> function <i>fem_Kcv.m</i> - <i>conduction-convection</i> matrix
1	<pre>function [K] = fem Kcv(xyz,lc,hh) % K integration on a line segment</pre>
2	Q = [xyz(lc(1), 1:3); xyz(lc(2), 1:3)];
3	L = norm(Q(2,:)-Q(1,:));
4	$K = [2 \ 1 \ -3; 1 \ 2 \ -3; -3 \ -3 \ 6] * hh*L/6;$
5	end

*Table 6: Matlab<sup>©</sup> function fem\_Kcv.m - convection matrix* 

The output is the 3 x 3 matrix of "conduction – convection" ( $WK^{-1}$ ). The length of a convection element is equal to L(m), its thickness to th(m), and the convection coefficient is  $h(Wm^{-2}K^{-1})$ . The nodal sequence of an element starts with the two real nodes pertaining to the mesh and ends with the virtual one related to convection.

### 2.2 Two convective and two adiabatic faces

```
...... 8. Standard rect. 1 rectangle .....
2
    ha = 2;xyz_cao = [0 0;1 0;1 ha;0 ha];car_cao =[1 2 3 4 ];nbo=4;
3
4
    disp('L 4, Standard rect. 1 rectangle: )
6
    cs=5;nnv=2;
    nni = 1;if nni<1;nni=1;end % Number nodes inserted on patches borders</pre>
26
        = .5;disp(['L 69, DT isotherms : ',num2str(pai), ' K'])
33
    pai
    nfi=2;fT =[300 270];lfi=[no+1 no+2];
                                          % Fix. of both virt. nodes
75
```

The above table shows the lines of Fiammetta enabled to run the test (*Figure 10*) on a rectangle (*Table 71*). It corresponds to a constant conductivity coefficient (*mat\_cok.m, Table 8*).



Figure 10: Isotherms orthogonal to both adiabatic boundaries. Biot number = 1



Figure 11: Nodes and elements numbering: heat flows with convective boundary conditions

In the case of two convective and two adiabatic faces, we want to know what happens if the values of the convective and conductive coefficients are significantly modified. It is proposed to express the difference of the fluid and the surface temperature as a function of the adimensional variable  $\beta = wh/k$  (w being the width of the domain, h and k respectively the convection and conduction coefficients) and to compare with the finite element model result. In this application, there is only one available characteristic length: w, which corresponds to the width (horizontal dimension) of the meshed domain.

This example deals with a very simple problem: evaluation of the temperature field in a wall submitted to convective heat transfers on both vertical sides. The horizontal sides are adiabatic. The solution is easily obtained explicitly. Let assume that the temperatures are defined as follows, from left to right:  $[t_0 \ t_1 \ t_2 \ t_3]$ . These variables correspond to the temperature  $t_0$  of the left virtual node, the surface temperature  $t_1$  of the left side, the surface temperature  $t_2$  of the right side and the temperature  $t_3$  of the right virtual node. Let assume that the convective coefficient is h, the conductive one k, the horizontal dimension of the domain w and the thickness, e. The continuity of the heat flux from left to right imposes the conditions:

The parameter w, which represents the width of the domain can be used as characteristic length L in the adimensional **Biot number** definition

$$\beta = \frac{h w}{k}, \qquad \beta (t_0 - t_1) = t_1 - t_2 = \beta (t_2 - t_3)$$
(37)

From the first relation, we deduce:

$$t_1 = \frac{\beta t_0 + t_2}{1 + \beta} \tag{38}$$

Now, we develop the second one:

$$\frac{\beta t_0 + t_2}{1 + \beta} - t_2 = \beta t_2 - \beta t_3$$
(39)

We obtain:

$$t_2 = \frac{t_0 + (1 + \beta)t_3}{2 + \beta}$$
(40)

Replacing (41) in (39), we have:

$$t_1 = \frac{\beta t_0}{1+\beta} + \frac{t_0 + (1+\beta) t_3}{(2+\beta) (1+\beta)} = \frac{t_0}{1+\beta} \left(\beta + \frac{1}{(2+\beta)}\right) + \frac{t_3}{(2+\beta)} = \frac{(1+\beta) t_0 + t_3}{(2+\beta)}$$
(41)

We also deduce the temperature gap in the wall as a function of the total temperature gap:

$$(t_2 - t_1) = (t_3 - t_0) \frac{\beta}{2 + \beta}$$
 (42)

With  $t_0 = 270$  and  $t_3 = 300$ , we obtain both with formulas (42) and (43) and with the *FEM* simulation the results of *Table 7*.

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Biot numb. <mark>B</mark>	-q <sub>x</sub> (Wm <sup>-2</sup> )	t1 ( <b>K</b> )	t <sub>2</sub> (K)	(t <sub>1</sub> -t <sub>0</sub> ) (K)	(t <sub>2</sub> -t <sub>1</sub> ) (K)	(t <sub>3</sub> -t <sub>2</sub> ) (K)	Dissip. Sol.
.5	6	282	288	12	6	12	3.6 <i>WK</i>
1	10	280	290	10	10	10	10 WK
2	15	277.5	292.5	7.5	15	7.5	22.5 WK
18	27	271.5	298.5	1.5	27	1.5	72.9 WK
20	27.3	271.36	298.64	1.36	27.3	1.36	74.4 WK

Table 7: Temperatures and heat flows as functions of Biot number

Basically, we are working with four nodes: two virtual ones with indices 0 (left side) and 3 (right side) and two nodes situated on the surface of the conductive zone: one on the left side and two on the right one. Their corresponding temperature are:  $t_0$ ,  $t_1$ ,  $t_2$ ,  $t_3$ . For  $\beta = 1$ , the gap between the virtual convective nodes and their corresponding surface temperatures are the same as the gap in the conductive zone. As expected, higher is the Biot number, higher is the temperature gap inside the conductive zone. Because the bilinear quadrilateral finite element model is able to represent the exact solution, this analytical solution is obtained independently of the mesh refinement.

In the test of *Figure 12*, with  $\beta = 18$ , the temperature gradient in the conductive zone is equal to 27 *K/m*. The heat fluxes in the conductive and convective zones are the same: 27 *Wm*<sup>-2</sup>. The quantity of heat crossing the virtual nodes is the product of the heat flux by the section of the vertical side: 27 *Wm*<sup>-2</sup> x 0.2 m<sup>2</sup> = 5.4 *W*. The ratio between the temperature gap in the solid and the total gap is equal to 27/30\*100 = 90 %.



Figure 12: Example of heat transfer through a wall with a high Biot number  $\beta = 18$ 

## 2.3 Material anisotropy

The *mat\_cok.m* function is subdivided into two sequences. In *Table 8*, the first one corresponds to horizontal strips (Ai=1), the second one to vertical strips (Ai=3). These sequences correspond to non-homogeneous materials. The coefficient applied to the conductivity coefficient is given by the variable *fa* defined in *line 1* of *Fiammetta*.

```
Matlab<sup>\odot</sup> function mat cok.m – non homogeneous conductivity
     function [co] = mat cok (Ai,nci,fa,xy,lK,deb)% Non uniform conductivity
1
2
         = 1 ;
                                                                                 % W/(m K)
     k
     nel = nci * nci;
3
                                                        % Number of elements per patch
4
     co = ones(nel,1)*k; % By default, the system is isotropic, k constant
5
     if Ai == 1
          if floor(nci/2) < ceil(nci/2)</pre>
                                                                             % nci is odd
6
              tr=1/nci:
7
              for i =floor(nci/2)*nci+1:floor(nci/2)*nci+nci;co(i)=k*fa;end% (n)
8
9
          else
10
              tr=2/nci;
                                                                            % nci is even
              for i =(nci/2-1)*nci+1:(nci/2*nci)+nci;co(i)=k*fa;end
11
                                                                                    8 (W)
          end
12
13
     end
     if Ai == 3
14
          if floor(nci/2) < ceil(nci/2)</pre>
15
                                                                             % nci is odd
16
              m = -nci; tr=1/nci;
17
              for j = 1:nci
                                      % Definition of 1 element wide vertical strip
18
                  m = m+nci;for i =((nci+1)/2):((nci+1)/2);co(m+i)=k*fa;end% (W)
19
              end
20
          else
21
              m = -nci; tr=2/nci;
                                                                           % nci is even
                                     % Definition of 2 elements wide vertical strip
22
              for j = 1:nci
23
                  m = m+nci; for i = (nci/2): (nci/2+1); co(m+i)=k*fa; end% (W)
2.4
              end
25
          end
     end
26
27
     if Ai == 4
          if floor(nci/2) < ceil(nci/2)</pre>
28
                                                                             % nci is odd
              m = -nci; tr=3/nci;
29
                                     % Definition of 3 elements wide vertical strip
30
              for j = 1:nci
                  m=m+nci;for i=((nci+1)/2-1):((nci+1)/2+1);co(m+i)=k*fa;end%(W)
31
32
              end
33
          else
34
              m = -nci; tr=4/nci;
                                                                           % nci is even
                                     % Definition of 4 elements wide vertical strip
5
              for j = 1:nci
36
                  m = m + nci; for i = (nci/2-1): (nci/2+2); co(m+i) = k*fa; end% (W)
37
              end
8
          end
39
     end
     if deb == 1
40
          figure;nu=0;% colormap(gra cob)
41
                                                                              % Isotherms
42
          for i=1:nel
43
              nu=nu+1; fill(xy(lK(i,:),1)', xy(lK(i,:),2)', co(nu)); hold on
44
          end
          colorbar;axis equal;axis off
45
46
     end
     disp(['Lm 47, Anis. index : ',num2str(Ai)])
47
     disp(['Lm 47, Amis. fmcen : , , num2str([k k*fa]), ' W/(m K)'])
disp(['Lm 48, k & coef*k : ', num2str([k k*fa]), ' W/(m K)'])
disp(['Lm 49, Thickn. ratio: ', num2str(tr)])
if nel < 50; disp(['Lm 26, Anis. vector : ', num2str(co')]); end</pre>
48
49
50
51
     end
```

Table 8: Matlab<sup>©</sup> function mat\_cok.m - non homogeneous conductivity

We now analyze a rectangular domain with part of the horizontal edges fixed at values of 320 K and 270 K. On these edges, *nnc* nodes are fixed. To identify the *DOF* of a patch edge, we use an instruction giving the number of the patch vertex, for instance *car\_cao (1,3)*, which means vertex 3 of patch 1, and the characteristic of the edge given in a line of the matrix *bor* prevised by the reference to matrix *pbo*, which is giving for each patch the number of the line of *bor* where its sides are stored. (Sequence corresponding to Di = 3 in *cad\_Dir.m*)



Figure 13: Isocurves in a rectangle with fixed DOF on horizontal edges, uniform k

It is now proposed to examine the effects of a modification of the conductivity coefficients. Let us try, for instance, to introduce a thermal bridge by increasing the conductivity along a vertical or an horizontal strip. This modification has to be performed by modifying the function  $mat\_cok.m$ . The elements are numbered from left to right and from bottom to top (*Table 8*). When we are using the function used to detect quantities along the boundary of a rectangular meshed domain is *cao\\_bou.m* (*Table 9*). To achieve this operation, we use the input matrices of the procedure *cad\\_bou.m*: *car\_cao* is the matrix of the input patches, *bor* and *pbo* are matrices created in *cad\_mes.m* to store the characteristics of the edges.

Ma	Matlab <sup>©</sup> function $cad\_bou.m$ – selection of nodal quantity $gh$ along the border								
1	<pre>function [gperi,li] = cad bou(car cao,bor,pbo,gh)% Loads on patch boundary</pre>								
2	a = [car cao(1,1) bor(pbo(1,1),5):bor(pbo(1,1),6) car cao(1,2)];								
3	b = [car cao(1,2) bor(pbo(1,2),5):bor(pbo(1,2),6) car cao(1,3)];								
4	$c = [car^{-}cao(1,3) bor(pbo(1,3),5):bor(pbo(1,3),6) car^{-}cao(1,4)];$								
5	d = [car cao(1,4) bor(pbo(1,4),5):bor(pbo(1,4),6) car cao(1,1)];								
6	li = $[a(1:size(a,2)-1) b(1:size(b,2)-1) c(1:size(c,2)-1)$								
7	d(1:size(d,2)-1)]; % List of the nodes from the 4 patch sides								
8	gperi = gh(li);								
9	end								

*Table 9: Matlab<sup>©</sup> function cad bou.m - nodal quantity along patch 1 boundary* 



Figure 14: Heat input and output for example of Figure 13 - boundary load: 15.3 W

Fiammetta_20211111	sipation: 275 WK, DOF: 2601
Standard 1 rect., Gi: 9	
L 4, Me, Di, Ne : 1 3 0	310
L 5, Connrnvn : 0 0 0	315
L 6, rc, ra, cs : 0 0 5	
L 7, CAD interf. : 4	300 - 310
L 9, N. pa., vert.: 1 4	
L 11, num. nod side: 49	300 - 305
L 13, num elem side: 50	
L 23, Domain area : 2 m2	- 300
L 26, Num. elements: 2500	000
L 28, Num. of DOF : 2601	205
L 59, Domain perim.: 6 m	295
L 61, Thickness : 1 m	
L 62, Conduction k : 1 W/(mK)	- 290
L 63, DT isotherms : 2 K	200
LD 23, N. fix. nodes: 10	285
L 89, Numb. r.nodes: 102	290
L 91, Rad. vertices: 2 3 4 1	- 280
L 96, Anis. index : O	
L 188, Total dissip.: 275 WK	275
L 191, Dis. in solid: 275 WK	280
L 192, DT in solid: 50 K	270
L 205, End Me=1, CPU: 1.13 sec.	2.0

Figure 15: Isocurves for isotropic material



Figure 16: Isocurves for material with vertical strip, 0.1 k (variable fa = .1)



Figure 17: Heat input and output for horizontal strip – heat load: 18.9 W



Figure 18: Boundary heat loads: 37.4 W - vertical strip of high conductivity



Figure 19: Isocurves for the vertical strip 2 elements wide, 16 x 16 mesh



Figure 20: Heat flows and temperature gradients for a vertical thermal bridge

The heat flows on top and bottom horizontal sides are progressing from 15.3 W (*Figure 14*) in the homogeneous case to 18.9 W in the case of the horizontal strip (*Figure 17*) and finally to 37.4 W in the case of the vertical one (*Figure 18*). In the example shown in *Figure 19*, we have tested the function on a domain involving a vertical strip in which the ratio of conductivities is equal to 10000. In *Figure 21*, we test the same mesh with a vertical strip of insulating material for which the conductivity is ten times smaller than the general one.



*Figure 21: Isocurves in presence of a vertical small conductivity strip (0.1 k)* 



Figure 22: Heat flows and temperature gradients (vertical strip with small conductivity)

It is possible to use two additional visualizations (*Figure 23*), the first concerns the anisotropy of material characteristics (conductivity coefficient and thickness): This illustration is created in *mat\_coK.m* (*Table 8*). The second represents scalars defined element by element, like the module of the heat flow.



Figure 23: Visualizations of scalars defined element by element

### 2.4 Thermal bridge

With respect to the example of *Figure 10*, we simply modify the function *mat\_cok.m* (*Table 8*). The effect of the thermal bridge is important, but here, the conductivity ratio is 1000. If this ratio falls to 10, the effect is still visible. This test shows the importance of thermal bridges in building design (*Figure 24 & Figure 25*).

We observe that the heat rate crossing the domain is equal to 3.6 W when the conductivity is uniform. It reaches the value of 9.4 W if the conductivity in the thermal bridge is 1000 times the conductivity in the other part of the domain. Specific data for this test are present in the next figures. Two tests are realized: with conductivity of 1000  $Wm^{-1}K^{-1}$  and 10  $Wm^{-1}K^{-1}$  in the horizontal thermal bridge.





L 96, Anis. index :	1
Lm 48, k & coef*k :	1 10 W/(m K)
Lm 49, Thickn. ratio:	0.058824
L 188, Total dissip.:	32.3 WK
L 191, Dis. in solid:	8.99 WK
L 192, DT in solid:	9.77 К
L 201, Fixed DOF :	325 326
L 202, Imposed temp.:	300 270 К
L 203, React. flows :	2.15 -2.15 W
L 205, End Me=1, CPU:	0.352 sec.

Figure 26: Isocurves with the presence of horizontal smooth thermal bridge (10 k)



Figure 27: Heat flows and temperature gradients (horizontal smooth thermal bridge)

### 3. Tutorial III: Structured mesh based on Coons' patch

Two authors contributed to the second generation of finite element models based on numerical integration techniques. The isoparametric element technique [Irons 1966] is based on the Coons patch developed in the frame of Computed Aided Design (CAD) [Coons 1967].

### 3.1 Numerical evaluation of the temperature gradient in a Coons patch

To simplify the subsequent development dedicated to the explanation on how to represent temperature gradients and heat flows, we limit ourselves to **two dimensions** by modeling elements and fields in the plane. We start by rewriting the nodes definition of the Coons patch (quadrilateral) in 2D. The patch is defined by its four vertices [Q].

$$\begin{bmatrix} Q \end{bmatrix} = \begin{bmatrix} Q_1 \\ Q_2 \\ Q_3 \\ Q_4 \end{bmatrix} = \begin{bmatrix} x_1 & y_1 \\ x_2 & y_2 \\ x_3 & y_3 \\ x_4 & y_4 \end{bmatrix} = \begin{bmatrix} X & Y \end{bmatrix}$$
(43)

Any point pertaining to the patch is expressed as a function of the four vertices [Q] and the blending functions f(s,t) stored in the vector [F]:

$$x(s,t) = [F][X] = [(1-s)(1-t) \quad s(1-t) \quad st \quad (1-s)t][X]$$
  

$$y(s,t) = [F][Y] = [(1-s)(1-t) \quad s(1-t) \quad st \quad (1-s)t][Y]$$
(44)



Table 10: Coons patch definition in Cartesian and parametric spaces

The barycenter of the four vertices is the point situated at  $s = \frac{1}{2}$ ,  $t = \frac{1}{2}$ .

$$x(s=1/2,t=1/2) = \begin{bmatrix} 1/4 & 1/4 & 1/4 \end{bmatrix} \begin{bmatrix} X \end{bmatrix} = (x_1 + x_2 + x_3 + x_4)/4$$
  

$$y(s=1/2,t=1/2) = \begin{bmatrix} 1/4 & 1/4 & 1/4 \end{bmatrix} \begin{bmatrix} Y \end{bmatrix} = (y_1 + y_2 + y_3 + y_4)/4$$
(45)

The derivatives of the x and y cartesian coordinates expressed in parametric coordinates s and t are:

$$\frac{\partial x(s,t)}{\partial s} = \frac{\partial [F]}{\partial s} [X] = [-(1-t) \quad (1-t) \quad t \quad -t] [X]$$

$$\frac{\partial x(s,t)}{\partial t} = \frac{\partial [F]}{\partial t} [X] = [-(1-s) \quad -s \quad s \quad (1-s)] [X]$$

$$\frac{\partial y(s,t)}{\partial s} = \frac{\partial [F]}{\partial s} [Y] = [-(1-t) \quad (1-t) \quad t \quad -t] [Y]$$

$$\frac{\partial y(s,t)}{\partial t} = \frac{\partial [F]}{\partial t} [Y] = [-(1-s) \quad -s \quad s \quad (1-s)] [Y]$$
(46)

For the bilinear element of equation (1.51), the Jacobian matrix [J] is equal to:

$$\begin{bmatrix} J \end{bmatrix} = \begin{bmatrix} \frac{\partial x}{\partial s} & \frac{\partial y}{\partial s} \\ \frac{\partial x}{\partial t} & \frac{\partial y}{\partial t} \end{bmatrix} = \begin{bmatrix} \begin{bmatrix} -(1-t) & (1-t) & t & -t \end{bmatrix} \begin{bmatrix} X \end{bmatrix} \begin{bmatrix} -(1-t) & (1-t) & t & -t \end{bmatrix} \begin{bmatrix} Y \end{bmatrix} \begin{bmatrix} -(1-s) & -s & s & (1-s) \end{bmatrix} \begin{bmatrix} Y \end{bmatrix}$$
(47)

Its determinant J is called the **jacobian of the transformation**. In the center of the square representing the patch in parametric coordinates, s = 0.5, t = 0.5, we have:

$$\begin{bmatrix} J \end{bmatrix}_{s=t=\frac{1}{2}} = \frac{1}{2} \begin{bmatrix} \begin{bmatrix} -1 & 1 & 1 & -1 \end{bmatrix} \begin{bmatrix} X \end{bmatrix} \begin{bmatrix} -1 & 1 & 1 & -1 \end{bmatrix} \begin{bmatrix} Y \end{bmatrix} \begin{bmatrix} -1 & -1 & 1 & 1 \end{bmatrix} \begin{bmatrix} -1 & -1 & 1 & 1 \end{bmatrix} \begin{bmatrix} Y \end{bmatrix}$$
(48)

Writing this relation explicitly in terms of the cartesian coordinates of the vertices, we obtain:

$$\begin{bmatrix} J \end{bmatrix}_{s=t=\frac{1}{2}} = \frac{1}{2} \begin{bmatrix} x_2 + x_3 - x_1 - x_4 & y_2 + y_3 - y_1 - y_4 \\ x_4 + x_3 - x_1 - x_2 & y_4 + y_3 - y_1 - y_2 \end{bmatrix}$$
(49)

At the barycenter of the element, the jacobian of the transformation, which is the scalar function corresponding to the determinant of the jacobian matrix, is then:

$$J_{s=t=\frac{1}{2}} = \frac{1}{2} \left( \left( x_2 + x_3 - x_1 - x_4 \right) \left( y_4 + y_3 - y_1 - y_2 \right) - \left( x_4 + x_3 - x_1 - x_2 \right) \left( y_2 + y_3 - y_1 - y_4 \right) \right)$$
(50)

Finally:

$$J_{s=t=\frac{1}{2}} = \frac{1}{2} \left( (x_2 - x_4) (y_3 - y_1) + (x_3 - x_1) (y_4 - y_2) \right)$$
(51)

The gradient of a scalar function, for instance the temperature  $\tau(s, t)$ , is computed as follows. After expressing it in parametric coordinates, it is converted in Cartesian ones (the real world).

$$\begin{bmatrix} \frac{\partial \tau}{\partial s} \\ \frac{\partial \tau}{\partial t} \end{bmatrix} = \begin{bmatrix} \frac{\partial x}{\partial s} & \frac{\partial y}{\partial s} \\ \frac{\partial x}{\partial t} & \frac{\partial y}{\partial t} \end{bmatrix} \begin{bmatrix} \frac{\partial \tau}{\partial x} \\ \frac{\partial \tau}{\partial y} \end{bmatrix} = \begin{bmatrix} J \end{bmatrix} \begin{bmatrix} \frac{\partial \tau}{\partial x} \\ \frac{\partial \tau}{\partial y} \end{bmatrix} = \begin{bmatrix} J \end{bmatrix} \vec{\nabla} \tau$$
(52)

After inverting (52), we obtain:

$$\vec{\nabla} \tau = \begin{bmatrix} \frac{\partial \tau}{\partial x} \\ \frac{\partial \tau}{\partial y} \end{bmatrix} = \begin{bmatrix} J \end{bmatrix}^{-1} \begin{bmatrix} \frac{\partial \tau}{\partial s} \\ \frac{\partial \tau}{\partial t} \end{bmatrix}$$
(53)

Because the temperature field is defined in the parametric coordinates with the same blending functions as the geometry: x(s, t) and y(s, t), these elements are named isoparametric:

$$\tau = \left[ (1-s)(1-t) \quad s(1-t) \quad st \quad (1-s)t \right] [T]$$
(54)

We can easily compute the temperature derivatives with respect to *s* and *t*:

$$\begin{bmatrix} \frac{\partial \tau}{\partial s} \\ \frac{\partial \tau}{\partial t} \end{bmatrix} = \begin{bmatrix} -(1-t) & (1-t) & t & -t \\ -(1-s) & -s & s & (1-s) \end{bmatrix} [T]$$
(55)

In the barycenter:

$$\begin{bmatrix} \frac{\partial \tau}{\partial s} \\ \frac{\partial \tau}{\partial t} \end{bmatrix}_{s=t=\frac{1}{2}} = \frac{1}{2} \begin{bmatrix} -1 & 1 & 1 & -1 \\ -1 & -1 & 1 & 1 \end{bmatrix} \begin{bmatrix} T \end{bmatrix}$$
(56)

The two components of the following equation correspond to the *lines 11 & 12* of the function *gra\_atg.m* (*Table 67*). They represent the temperature gradient

$$\vec{\nabla} \tau = \begin{bmatrix} \frac{\partial \tau}{\partial x} \\ \frac{\partial \tau}{\partial y} \end{bmatrix} = \begin{bmatrix} J \end{bmatrix}^{-1} \frac{1}{2} \begin{bmatrix} -1 & 1 & 1 & -1 \\ -1 & -1 & 1 & 1 \end{bmatrix} \begin{bmatrix} T \end{bmatrix}$$
(57)

Being able to calculate the temperature gradients, it is now possible to compute the conductivity matrices. The Matlab<sup>©</sup> function *fem\_Kco.m* (*Table 11*) allows computing the conductivity matrix [K] of an isoparametric quadrilateral element with a bilinear temperature field. To obtain the effective element conductivity matrix, the output of the function has to be multiplied by the conductivity coefficient *k* (expressed in  $WK^{-1}m^{-1}$  and stored in the vector *co* because it may vary from element to element) and the constant thickness *th*.

M	Iatlab <sup>©</sup> function <i>fem_Kco.m</i> - conductivity matrix of isoparamatric element
1	<pre>function [K] = fem Kco(xyz,lo) % Conductivity matrix K, 3D surf. 20211001</pre>
2	Q = [xyz(lo(1),:); xyz(lo(2),:); xyz(lo(3),:); xyz(lo(4),:)];
3	s = [.5-sqrt(3)/6 .5+sqrt(3)/6 .5+sqrt(3)/6 .5-sqrt(3)/6];% s 4 Gauss pts
4	t = [.5-sqrt(3)/6 .5-sqrt(3)/6 .5+sqrt(3)/6 .5+sqrt(3)/6];% t 4 Gauss pts
5	K = zeros(4,4); % area = 0.;
6	for i=1:4 % Loop on the 4 Gauss points
7	fs = [-(1-t(i)) (1-t(i)) t(i) -t(i) ]; % Derivative s
8	ft = [-(1-s(i)) -s(i) s(i) (1-s(i))]; % Derivative t
9	<pre>gra = [fs;ft]; % Gradient of the scalar bilinear function</pre>
10	ds = fs * Q; % Differencial in the s direction
11	<pre>dt = ft * Q; % Differencial in the t direction</pre>
12	<pre>% area = area + sqrt(dot(cross(ds,dt),cross(ds,dt)))/4;</pre>
13	J = [fs*Q(:,1) fs*Q(:,2);ft*Q(:,1) ft*Q(:,2)]; % Jacobian matrix
14	K=K+((J^(-1)*gra)'*J^(-1)*gra)*sqrt(dot(cross(ds,dt),cross(ds,dt)))/4;
15	end
16	<pre>% disp(['Patch area : ',num2str(area)])</pre>
17	end % Multiplied by k and the thickness, the K matrix is adimensional

*Table 11: Matlab<sup>©</sup> function fem\_Kco.m - element conductivity matrix* 

To compute a conductivity matrix, we need the matrix [xyz] of element coordinates (first argument of the function) and the localization *lo* of the element, for instance, the positions of its four nodes in the coordinate matrix (second argument of the function *fem\_Kco.m*). A direct Matlab evaluation of the conduction matrix of a square is given in *Table 12*, using explicit definitions of both the coordinates and the localization vector. As noted before in the explicit analytical calculation of the conductivity matrix, it is easy to check that the result does not depend on the scale of the geometry.

Matlab input	xyz = [0 [K] = fer	0 0;1 n_Kco	0 0;1 (xyz,1	1 0;0 0)*6	1 0];lo=[1 2 3 4];	
Matlab Output	K = 4 -1 -2 -1	-1 4 -1 -2	-2 -1 4 -1	-1 -2 -1 4		

Table 12: Numerically integrated conductivity matrix

To obtain the effective conductivity matrix, the result displayed in *Table 12* is multiplied by k *th* / 6, where k is the conductivity coefficient and *th* the thickness.

## 3.2 CAD model of the domain to be analyzed

The inputs of a CAD model involve three kinds of data. The  $xyz\_cao$  matrix contains the coordinates of the nodes,  $car\_cao$  is giving the patches definition and *nbo* is the number of interfaces limiting the patches. The size of the matrix  $xyz\_cao$  must be the maximum numbering of the nodes defined in the matrix  $car\_cao$ . Because these numbers represent *DOF*, they must all be present in the matrix  $car\_cao$ . For the example of *Figure 36*, we have, on the left of *Table 13*, the node numbering [(1: npv)' xyz\\_cao] and the matrix of 2D nodal coordinates and, on the right, [(1:np)' car\\_cao], the patch numbering and the patch matrix. The line numbering of both matrices appears in blue on the left. Note that npv is the number of patch vertices and np, the number of patches.

<pre>npv=size(xyz_cao,1);[(1:npv)' xyz_cao]</pre>					size(xy	z_cao,	1);[(1	l:np)'	car_cao]
1	2	2							
2	2	3							
3	1	2		1	1	2	4	2	
4	0	3		L	1	2	4	3	
5	0	0		2	3	4	5	6	
6	1	1		3	/	8	6	5	
7	3	0							
8	3	1							

Table 13: Instructions used to display input data of Figure 36

*Lines 16 - 19* of *Table 71* are generating the Coons patches displayed in *Table 13* and drawn in *Figure 36*.

# **3.3 Identification of the** *DOF* **pertaining to a patch side**

The introduction of fixations or distributed loads on a patch side needs the identification of the concerned *DOF*. This detection is obtained through a single instruction. In *Table 14*, we see the four instructions used to determine the *DOF* of the cavity of *Figure 28*. The cavity is defined by *lines 1 - 4* of *Table 71*. The four *CAD* patches and their related data are shown in *Figure 28*. The matrix *bor* corresponds to a mesh of 100 elements counting four nodes on each patch side.

							Labels & normals of the 4 patche(s)
with nni 1 2 3 4 5 6 7 8 9 10 11 12	= 4, [( 6 5 1 2 2 3 7 3 4 8 5 4	(1:size 5 1 2 6 3 7 6 4 8 7 8 1	e (bor, 1 1 1 2 2 3 3 4 4	1))' k 0 4 0 2 0 3 0 0 4 0 0 0	<pre>por] →     9     13     17     21     25     29     33     37     41     45     49     53</pre>	12 16 20 24 32 36 40 44 48 52 56	Labels & normals of the 4 patche(s)
12	1		1				
[(1:np)'	car_ca	10] →					[(1:np)' pbo] →
	1	6	5	1	2		1 1 2 3 4
	2	6	2	3	7		2 4 5 6 7
	3	7	3	4	8		3 6 8 9 10
	4	1	5	8	4		4 2 11 9 12

Figure 28: CAD data defining a domain surrounding a cavity

The matrix *car\_cao* defines the four patches, the matrix *pbo* indicates in which line of *bor* the sides of the patches are described. For instance, the second side of patch 1 connecting node 5 to node 1 is described in *line 2* of matrix *bor*. The cavity side of patch 1 is connecting nodes 6 (*car\_cao (1,1)*) to node 5 (*car\_cao (1,2)*), it is the first side (*pbo (1,1)*) of the patch and its description is in *line 1* of *bor* (columns 5 and 6 are giving the sequence of side nodes). In the *line 50* shown in *Table 14*, we select the nodes of the second side of the third patch (*Figure 28*). According to the second column of *line 3* of *pbo*, the side is described in *line 8* of matrix *bor*. The result is displayed in *Figure 29*.

The sequence for selecting DOF along a patch side is:

- 1: *car\_cao* (patch number, numbering of first vertex of the concerned side),
- 2: *bor* (*pbo* (patch number, side number), 5),
- 3: *bor* (*pbo* (patch number, side number), 6),
- 4: *car\_cao* (patch number, number of second vertex of the side).



Table 14: Instructions to identify nodes along patch sides



*Figure 29: Finite element mesh corresponding to the CAD definition of Figure 28* 

## 3.4 Cavity with adiabatic hole



Figure 30: Heat flow around an adiabatic cavity

# 3.5 C shaped domain

The *Fiammetta.m* procedure starts generating the *CAD* model: shrunk *CAD* mesh with nodes and patches labels (function *gra\_mel.m* of *Table 65 & Figure 31*). Hereafter, the same domain will be defined with different *CAD* models: the long or the short horizontal parts of the model are trapezoidal in *Figure 34*, the domain is only composed of rectangular patches in *Figure 35* and, finally, it is composed of three trapezoidal patches. In these four situations, the dissipative function is respectively equal to 0.993 *WK*, 0.991 *WK*, 0.987 *WK* and, finally, 0.979 *WK*. Due to the convergence property of a pure conduction model with Dirichlet boundary conditions, the lowest value of the dissipative function is the best one [Debongnie, Zhong & Beckers 1995]. With the last model, it converges to 0.979 *WK* when we have 8241 *DOF*. So, the dissipation is decreasing when the mesh is finer [Debongnie & Beckers 2001]. The Matlab<sup>©</sup> functions

gra\_mel.m (Table 65) and gra\_mnl.m (Table 66) enable the visualization of the finite element mesh (*Figure 32*).



Two functions are fundamental in *Fiammetta.m: cad\_mes.m* (*Table 15*) and *cad\_edg.m* (*Table 16*), which is called in *cad\_mes.m*. They allow defining the topology of the *CAD* model through the construction of matrices *bor* and *pbo* that describe the patch interfaces.

C Matlab function cad mes.m function [xyc,lK,bor,pbo] = cad mes(xyc,lca,ni,nbo) 1 % Number of CAD patches 2 nec = size(lca,1); 3 ndo = size(xyc,1);nd = ndo; % Number of CAD nodes 4 [bor, pbs] = cad edg(lca, nbo); % Compute the nbo patch sides in bor matrix 5 == 1 % ni = 1 : one node generated on the interfaces if ni 6 7 lai = zeros(1,nbo); % List of border edges 8 for i = 1: nbo 9 = nd + i; lai(i) 10 bor(i,5) = lai(i); 11 bor(i,6) = bor(i,5); 12 xyc(nd+i,:) = (xyc(bor(i,1),:)+xyc(bor(i,2),:))/2; 13 end 14 else % More than 1 node have to be generated on the interfaces 15 k = nd; 16 for i = 1 : nbo % nbo is the number of interfaces 17 bor(i,5) = nd + (i-1)\*ni+1; = nd + i\*ni; 18 bor(i, 6)= 1 : ni 19 for i 20 = xyc(bor(i,1),:);B = xyc(bor(i,2),:); Α = k + 1;21 k 22 xyc(k,:) = A + (B-A)\*j/(ni+1); % coord. of the inerface nodes 2.3 end 24 end 25 end 26 pbo = sign(pbs(:,:)).\*pbs; 27 = ndo + nbo\*ni; % Numb. of nodes after interfaces gen. nna = zeros(nec\*(ni+1)^2,4);nu = 0; 28 1 K 29 = 1:nec % Loop on the CAD patches ... for n 30 = zeros(ni+2,ni+2); % Gen. to = list of nodes matrix to = lca(n,1); 31 to(1,1) % Start with the 4 patch vertices to(1,ni+2) = lca(n,2); to(ni+2,ni+2) = lca(n,3)32 33 to(ni+2,1) = lca(n,4); % End patch vertices 34 if bor(pbo(n,1),3) == n % Line 1 of patch matrix to (2:ni+1) = bor(pbo(n, 1), 5):bor(pbo(n,1),6); 35 to(1 36 else ,2:ni+1) = bor(pbo(n,1),6):-1:bor(pbo(n,1),5); 37 to(1 38 end 39 if bor(pbo(n, 3), 3) == n % Line ni+2 of patch matrix to 40 to(ni+2,2:ni+1) = bor(pbo(n,3),6):-1:bor(pbo(n,3),5);41 else 42 to(ni+2,2:ni+1) = bor(pbo(n,3),5) :bor(pbo(n,3),6);

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```
43
        end
44
        if bor(pbo(n, 4), 3) == n
                                      % Side 4 = first column of matrix to
45
           to(2:ni+1,1) = bor(pbo(n,4),6):-1:bor(pbo(n,4),5);
46
        else
47
            to(2:ni+1,1) = bor(pbo(n,4),5)
                                          :bor(pbo(n,4),6);
        end
48
49
        if bor(pbo(n,2),3) == n
                                       % Side 2 = column ni+2 of matrix to
           to(2:ni+1,ni+2) = bor(pbo(n,2),5) :bor(pbo(n,2),6);
50
51
        else
           to(2:ni+1,ni+2) = bor(pbo(n,2),6):-1:bor(pbo(n,2),5);
52
53
        end
54
        % Generation of internal nodes if ni > 0 .....
55
        x1 = xyc(to(1,1),:); x2 = xyc(to(1,ni+2),:);
                                                      % Patch vertices
        x3 = xyc(to(ni+2,1),:);x4 = xyc(to(ni+2,ni+2),:);
56
                         = 1 : ni % ni x ni new nodes inside the patch
= 1: ni
57
        for k
58
            for j
59
                          = k/(ni+1);t=j/(ni+1);% disp([s t])
               s
60
                          = nna+1;
               nna
61
               to(j+1,k+1) = nna;
                                                   % Interior of the patch
62
               xyc(nna,:) = x1*(1-s)*(1-t)+x2*s*(1-t)+x3*(1-s)*t+x4*s*t;
63
            end
64
        end
        % End of generation of the internal nodes .....
65
66
        for i = 1:ni+1% Mesh generation: (ni+1) (ni+1) elements per patch .....
67
            for i
                       = 1:ni+1
                     = nu+1;
68
               nu
               lK(nu,:) = [to(i,j) to(i+1,j) to(i+1,j+1) to(i,j+1)];
69
70
            end
71
        end % End of mesh generation .....
    end % End of loop on the CAD patches.....
72
73
    end
```

Table 15: Matlab<sup>©</sup> function cad\_mes.m - construction of the CAD mesh topology

### Matlab<sup>©</sup> function *cad edg.m*

```
function [bor,pbo] = cad_edg(lca,nbo)
1
 2
    nec = size(lca,1);
                                                     % nec = number of elements
 3
    bor = zeros(nbo,8);boe=zeros(nec,8);pbo = zeros(nec,4);% bor = patch sides
    for ie = 1:nec
                                                    % Loop ie on the nec patches
 4
        boe(1,1) = lca (ie,1); boe(1,2) = lca (ie,2); boe(1,3) = ie;
 5
        boe(2,1) = lca (ie,2); boe(2,2) = lca (ie,3); boe(2,3) = ie;
 6
        boe(3,1) = lca (ie,3); boe(3,2) = lca (ie,4); boe(3,3) = ie;
 7
 8
        boe(4,1) = lca (ie,4); boe(4,2) = lca (ie,1); boe(4,3) = ie;
 9
        if ie == 1
10
            bor(1:4,:) = boe(1:4,:);
11
            pbo(1, 1:4) = 1:4;
                       = 4;
12
            nbo
13
        else
                       = 1 : 4
            for i
                                                        % Loop on the new sides
14
                flag = 0;
15
                 for kl = 1:nbo
16
                                               % Loop on the yet detected sides
                    if flag == 0
17
18
                        if boe(i,2)
                                           == bor(k1,1)
                             if boe(i,1) == bor(kl,2)
19
20
                                 bor(kl, 4) = ie;
                                                         % Side detected before
                                 pbo(ie,i) = -kl; % 2d occurence of a bor line
21
22
                                           = 1;
                                 flaq
23
                            end
24
                        end
25
                    end
26
                end
27
                if flag
                               == 0
28
                               = nbo +1;
                    nbo
                    bor(nbo,:) = boe(i,:);
29
30
                    pbo(ie,i) = nbo;
                end;
31
32
            end
33
        end
34
    end
35
    end
```

Table 16: Matlab<sup>©</sup> function cad edg.m - CAD mesh interfaces



Figure 33: CAD models with diagonal on the long horizontal side



Figure 34: CAD models with diagonal on the short and the long horizontal side

In the next test, we avoid the distorted shapes of the first patches by replacing them by 3 squares.

```
xyz_cao = [2 2;2 3;1 2;1 3;0 2;0 3;0 0;0 1;1 0;1 1;3 0;3 1];%CAD geometry
car_cao = [1 2 4 3;3 4 6 5;3 5 8 10;10 8 7 9 ;10 9 11 12];nbo=16; % patch
8
31
              = .1; disp(['Thickness
                                                    : ',num2str(th), ' m'])
     th
55
     lfi=[car_cao(1,1) bor(pbo(1,1),5):bor(pbo(1,1),6) car_cao(1,2)...
56
           car_cao(5,3) bor(pbo(5,3),5):bor(pbo(5,3),6) car_cao(5,4)];
57
     nfi
            = size(lfi,2); % Dirichlet boundary conditions .....
     if nfi > 2 ; fix = [ones(1,nfi/2)*300 ones(1,nfi/2)*310 ]
58
                                                                         ;end
69
     gh = zeros(ndK,1);
                               % Second member initialization always necessary
83
          h = 18; hh = h*th; nec = nni+1;
              = zeros(ndK,ndK);% co = mat_cok (nni+1,nni+1); % Initializations
122
     Κ
123
     со
              = ones(1,nel)*th;
```

The result is given for two meshes:





Figure 35: CAD model fully based on rectangular patches

E,T	Lammetta_20211111						
С	C shape, 3 patches, Gi: 3						
L	4, Me, Di, Ne :	1	6	0			
L	5, Co nnr nvn :	0	0	0			
L	6, rc, ra, cs :	0	0	5			
L	7, CAD interf. :	1	0				
L	9, N. pa., vert.:	3	8				
L	11, num. nod side:	4	9				
L	13, num elem side:	5	0				
L	23, Domain area :	6	m2				



Figure 36: CAD model based on 3 patches, 7500 elements, CPU: 7 sec.

In the next test (Figure 37), with the linear constraints, we have 10353 unknowns.



Figure 37: CAD model based on 4 patches, 10000 elements

## **3.6 Boundary conditions**

We show here how we can introduce Dirichlet, von Neumann and convective boundary conditions. For Dirichlet boundary conditions, we have only to give a list and the values of the fixed nodes. For the second, we give a list of nodes and the values of the corresponding second members of the equations. In the case of convection, we give the localizations of the 3 x 3 convective matrices (34) and for each element the convection coefficient (uni-line matrix *he*).

```
Matlab<sup>©</sup> function cad_Dir.m – Dirichlet boundary conditions
```

```
function [lfi,fT] = cad Dir(Di,no,nvn,car cao,bor,pbo,nni)
    % disp(['LD 2, num. nod side: ',num2str(nni)])
2
    % General data .....
3
    % nnc = 5 ;
                              % Number of fixed nodes on the horizontal sides
4
5
    % disp(['L
               25, N.fix h.-side: ',num2str(nnc)])
 6
   if Di == 0
        lfi(1)=0;fT(1)=0;nf=0;
7
8
    end
    if Di == 1
9
        lfi = [car cao(3,2) bor(pbo(3,2),5):bor(pbo(3,2),6) car cao(3,3)];
10
        nf = size(lfi,2);fT = ones(1,nf)*300;
11
    end
12
```
13 if Di == 2 14 fT =[280 300];lfi=[no+1 no+2];nf=2; % Fixation of two virtual nodes disp(['LD 15, Fixed nodes : ',num2str(lfi)])
disp(['LD 16, Fix. temper. : ',num2str(fT),' K']); 15 16 17 end if Di == 318 19 nnc = 5;% nnc = the number of fixed nodes on the horizontal sides if nni < nnc;nnc = nni;end</pre> 20 a = [car\_cao(1,3) bor(pbo(1,3),5):bor(pbo(1,3),6) car\_cao(1,4)]; b = [car\_cao(1,1) bor(pbo(1,1) 5):bor(c) (1,1) 5); 21 = [car cao(1,1) bor(pbo(1,1),5):bor(pbo(1,1),6) car cao(1,2)]; 2.2 23 nx = min(nnc,nni+3);lfi=[b(nni+3-nx:nni+2) a(nni+3-nx:nni+2)]; 24 nf = size(lfi,2);fT = [ones(1,nf/2)\*270 ones(1,nf/2)\*320]; 25 disp(['LD 23, N. fix. nodes: ',num2str(nf)]) end 26 27 if Di == 4 28 lfi = [[car cao(1,3) bor(pbo(1,3),5):bor(pbo(1,3),6) car cao(1,4)]'; 29 [car cao(3,2) bor(pbo(3,2),5):bor(pbo(3,2),6) car cao(3,3)]']'; nf = size(lfi,2);fT = [ones(1,nf/2)\*270 ones(1,nf/2)\*300]; 30 31 end 32 **if** Di == 5 33 lfi=[car cao(1,1) bor(pbo(1,1),5):bor(pbo(1,1),6) car cao(1,2)... 34 car cao(4,3) bor(pbo(4,3),5):bor(pbo(4,3),6) car cao(4,4)]; nf = size(lfi,2); 35 36 if nf > 2 ;fT = [ones(1,nf/2)\*300 ones(1,nf/2)\*310 ];end 37 end 38 **if** Di == 6 39 lfi=[car\_cao(1,1) bor(pbo(1,1),5):bor(pbo(1,1),6) car\_cao(1,2)... car cao(3,1) bor(pbo(3,1),5):bor(pbo(3,1),6) car\_cao(3,2)]; 40 41 nf = size(lfi,2); if nf > 2 ;fT = [ones(1,nf/2)\*300 ones(1,nf/2)\*310 ];end 42 43 end if Di == 7 44 45 fT =[300 280];lfi=[no+1 no+2];nf=2; % Fix. of both virt. nodes end 46 47 if Di == 8 lfi=[car\_cao(1,3) bor(pbo(1,3),5):bor(pbo(1,3),6) car\_cao(1,4)]; 48 49 nf = size(lfi,2);fT = ones(1,nf)\*270; % Dirichlet boundary conditions 50 end 51 if Di == 9 52 fT =[280 300];lfi=[no+1 no+2];nf=2; % Fix. of 2 virt. nodes disp(['LD 53, Fixed nodes : ',num2str(lfi)])
disp(['LD 54, Fix. temper. : ',num2str(fT),' K']); 53 54 55 end 56 if Di == 10 fT =[270 270 300];lfi=[no+1 no+2 no+3];nf=3; % Fix. of 3 virt. nodes 57 disp(['LD 58, Fixed nodes : ',num2str(lfi)])
disp(['LD 59, Fix. temper. : ',num2str(fT),' K']); 58 59 60 end if Di == 11 61 62 fT =[300 280];lfi=[no+1 no+2];nf=2; % Fixation of two virtual nodes disp(['LD 63, Fixed nodes : ',num2str(lfi)])
disp(['LD 64, Fix. temper. : ',num2str(fT),' K']); 63 64 end 65 66 if Di == 12 67 fT =300;lfi=no+1 ;nf=1; % Fixation of one virtual nodes disp(['LD 68, Fixed nodes : ',num2str(lfi)])
disp(['LD 69, Fix. temper. : ',num2str(fT),' K']); 68 69 70 end 71 if Di == 13 72 fT =[300 270];lfi=[no+1 no+2];nf=2; % Fixation of two virtual nodes disp(['LD 73, Fixed nodes : ',num2str(lfi)])
disp(['LD 74, Fix. temper. : ',num2str(fT),' K']); 73 74 75 end 76 % if nfi < 7;disp(['L 73, fix. top side: ',num2str(lfi)]);end % bc = [[car cao(1,1) bor(pbo(1,1),5):bor(pbo(1,1),6) car cao(1,2)]; 77 [car\_cao(2,4) bor(pbo(2,4),5):bor(pbo(2,4),6) car\_cao(2,1)]; 78 8 79 [car cao(3,4) bor(pbo(3,4),5):bor(pbo(3,4),6) car cao(3,1)]; 80 [car cao(4,2) bor(pbo(4,2),5):bor(pbo(4,2),6) car cao(4,3)]]; % disp(['L 78, n.fix. cavity: ',num2str(size(bc))]) 81 = zeros(1,no); lfi = zeros(1,no); 82 % fT if Di > 1283 84 if nvn == 0% lfi = uni-line matrix, fT = uni-line matrix lfi = [[car cao(1,3) bor(pbo(1,3),5):bor(pbo(1,3),6) car cao(1,4)]'; 85 86 [car cao(3,2) bor(pbo(3,2),5):bor(pbo(3,2),6) car cao(3,3)]']'; nf = size(lfi,2)/2;fT=[ones(nf,1)\*270;ones(nf,1)\*300]; 87 88 2 mfi = [car cao(3,2) bor(pbo(3,2),5):bor(pbo(3,2),6) car cao(3,3)]; 89 end

```
90
      if nvn == 1
 91
            lfi = [car cao(1,3) bor(pbo(1,3),5):bor(pbo(1,3),6) car cao(1,4)]';
     2
 92
            nfi=size(lfi,2);fT=ones(1,nfi)*280;
 93
     % % DOF of the 1. Standard cavity
     % bc = [[car cao(1,1) bor(pbo(1,1),5):bor(pbo(1,1),6) car_cao(1,2)];
 94
 95
              [car_cao(2,4) bor(pbo(2,4),5):bor(pbo(2,4),6) car_cao(2,1)];
     8
 96
              [car_cao(3,4) bor(pbo(3,4),5):bor(pbo(3,4),6) car_cao(3,1)];
     8
              [car cao(4,2) bor(pbo(4,2),5):bor(pbo(4,2),6) car cao(4,3)]];
 97
     응
 98
 99
     end
                                     % Dirichlet boundary conditions for convection
100
     % if nvn == 2
101
           fT =[270 300];lfi=[no+1 no+2]; % Fixation of 2 virtual nodes
102
     % end
103
     if nvn == 3
          fT=[270 285 300];lfi=[no+1 no+2 no+3]; % Fixation of 3 virtual nodes
104
105
     end
106
     nfi = size(lfi,2);disp(['LD106, N. fix. nodes: ',num2str(nfi)])
107
     if nfi > 0
          if nfi < 15
108
              disp(['LD109, Numb. fix. N.: ',num2str(nf)])
disp(['LD110, Fixed nodes : ',num2str(lfi)])
disp(['LD111, Fix. temper. : ',num2str(fT),' K']);
109
110
111
112
          end
113
     end
114
     end
115
     end
```

Table 17: Matlab<sup>©</sup> function cad Dir.m - Dirichlet boundary conditions

```
Matlab<sup>©</sup> function cad Neu.m – von Neumann boundary conditions
    function [gh,bos] = cad Neu(Ne,dK,car cao,pbo,bor,th,xyz cao)
 1
 2
    %...... Neumann boundary conditions
 3
    if Ne == 1
        gh = zeros(dK, 1);
 4
                                                 % second member initialization
        lg = [car cao(3,2) bor(pbo(3,2),5):bor(pbo(3,2),6) car cao(3,3)];
 5
 6
        nh = size(lg,2);np=nh-1;g(1)=1/(2*np);g(nh)=g(1);g(2:nh-1)=1/np;
 7
        gh(lg(1:nh)) = g(1:nh) / sum(g);
 8
        bos = (xyz_cao(2,1)-xyz_cao(1,1))*th;
                  9, Loaded area : ',num2str(bos),' m2'])
 9
        disp(['N
10
    end
11
    if Ne == 11
12
        gh = zeros(dK, 1);
        lg = [car_cao(3, 3) bor(pbo(3, 3), 5):bor(pbo(3, 3), 6) car_cao(3, 4)...
13
14
             car_cao(1, 1) bor(pbo(1,1),5):bor(pbo(1,1),6) car_cao(1,2)];
15
        nh = size(lg, 2)/2;
                                             % Loaded nodes lg for CAD model 11
        lq = [car cao(3,2) bor(pbo(3,2),5):bor(pbo(3,2),6) car cao(3,3)];
16
    8
          nh = size(lg, 2);
17
    8
                         = 1:nh; gh(lg(1,i),1) = 2; end % Weights right side
18
        for i
                       = 1 ; gh(lg(1,nh),1) = 1;
19
        gh(lg(1,1),1)
20
        gh(lg(1:nh))
                        = gh(lg(1:nh))/sum(gh(lg(1:nh)));
                         = nh+1:2*nh;gh(lg(1,i),1) = 2; end% Weights left side
21
        for i
2.2
        gh(lg(1,nh+1),1) = 1; gh(lg(1,2*nh),1) = 1;
23
        gh(lg(nh+1:2*nh)) = gh(lg(nh+1:2*nh))/sum(gh(lg(nh+1:2*nh)));nh = 2*nh;
24
        qh=qh/2;
25
        bos = (xyz_cao(2,1)-xyz_cao(1,1)+xyz_cao(7,1)-xyz_cao(8,1))*th;
        disp(['N 26, N. load. nod.: ',num2str(size(lg,2))])
26
27
    end
28
    if Ne == 0
       qh = zeros(dK,1);bos=0; % 2d member initialization always necessary
29
30
    else
31
        if nh < 10
           disp(['N 32, Loaded nodes : ',num2str(lg)])
disp(['N 33, Loads weights: ',num2str(gh(lg)')])
32
33
        end
34
35
    end
36
    end
```

Table 18: Matlab<sup>©</sup> function cad\_Neu.m - von Neumann boundary conditions

 Matlab<sup>©</sup> function cad\_con.m - convection boundary conditions

 1
 function [lc,hv]=cad\_con(car\_cao,bor,pbo,h,dK,nes,deb,nvn,cs,Co)% 20210929

 2
 npa = size(car\_cao,1);% npa = number patches ; nes number of elem per side

 3
 disp(['c. 03, Numb. var. dK: ',num2str(dK)]) % nes = n. elem/side

 4
 disp(['c. 04, N.virt c.nod.: ',num2str(nvn)]);

if Co == 5  $bt = [[car_cao(1,2) bor(pbo(1,2),5):bor(pbo(1,2),6) car_cao(1,3)];$ 6 7 [car cao(1,4) bor(pbo(1,4),5):bor(pbo(1,4),6) car cao(1,1)]]; 8  $hv = ones(\overline{1}, nvn*npa*nes)*h;$ 9 end 10 if Co == 211 bt = [[car cao(1,1) bor(pbo(1,1),5):bor(pbo(1,1),6) car\_cao(1,2)]; 12 [car cao(2,4) bor(pbo(2,4),5):bor(pbo(2,4),6) car cao(2,1)]; [car\_cao(3,4) bor(pbo(3,4),5):bor(pbo(3,4),6) car\_cao(3,1)]; [car\_cao(4,2) bor(pbo(4,2),5):bor(pbo(4,2),6) car\_cao(4,3)]]; 13 14 15  $a = ones(\overline{1}, nes);$ 16 hv = [a\*h a\*h a\*h a\*h];17 end if Co == 318 bt = [[car cao(1,2) bor(pbo(1,2),5):bor(pbo(1,2),6) car cao(1,3)];19 20 [car cao(2,2) bor(pbo(2,2),5):bor(pbo(2,2),6) car cao(2,3)]; 21 [car cao(2,4) bor(pbo(2,4),5):bor(pbo(2,4),6) car cao(2,1)]; 22 [car\_cao(1,4) bor(pbo(1,4),5):bor(pbo(1,4),6) car\_cao(1,1)]]; hv = ones(1, nvn\*npa\*nes)\*h; 23 24 end 25 if Co == 426  $\texttt{bt} = [[\texttt{car}\_\texttt{cao}(1,2) \ \texttt{bor}(\texttt{pbo}(1,2),5):\texttt{bor}(\texttt{pbo}(1,2),6) \ \texttt{car}\_\texttt{cao}(1,3)];$ [car cao(2,2) bor(pbo(2,2),5):bor(pbo(2,2),6) car\_cao(2,3)];]; 27 28 hv = ones(1, nvn\*npa\*nes)\*h; 29 end 30 if Co > 4if npa == 1 31 % The domain contains a single patch if nvn == 2 32 % 2 convective sides 33 bt = [[car cao(1,2) bor(pbo(1,2),5):bor(pbo(1,2),6) car cao(1,3)];[car cao(1,4) bor(pbo(1,4),5):bor(pbo(1,4),6) car cao(1,1)]]; 34 35 hv = ones(1, nvn\*npa\*nes)\*h; end 36 37 if nvn == 3% 3 convective sides bt = [[car cao(1,2) bor(pbo(1,2),5):bor(pbo(1,2),6) car cao(1,3)];38 39 [car\_cao(1,3) bor(pbo(1,3),5):bor(pbo(1,3),6) car\_cao(1,4)]; [car cao(1,4) bor(pbo(1,4),5):bor(pbo(1,4),6) car\_cao(1,1)]]; 40 41 hv = ones(1,nvn\*npa\*nes)\*h; 42 end 43 end 44 if npa == 2 % The domain contains two patches if nvn == 3 45 % 3 convective sides 46 bt = [[car cao(1,2) bor(pbo(1,2),5):bor(pbo(1,2),6) car cao(1,3)];47 [car cao(2,2) bor(pbo(2,2),5):bor(pbo(2,2),6) car cao(2,3)]; [car cao(2,3) bor(pbo(2,3),5):bor(pbo(2,3),6) car\_cao(2,4)]; 48 [car\_cao(2,4) bor(pbo(2,4),5):bor(pbo(2,4),6) car\_cao(2,1)]; 49 50 [car cao(1,4) bor(pbo(1,4),5):bor(pbo(1,4),6) car cao(1,1)];]; 51 hv = ones(1,nvn\*npa+2\*npa)\*h; 52 end 53 end 54 if cs~=5 55 if npa > 2% The domain contains more than two patches 56 if nvn == 1 % 1 convective side 57 bt =  $[[car_cao(4,2) bor(pbo(4,2),5):bor(pbo(4,2),6) car cao(4,3)];$ [car cao(3,1) bor(pbo(3,1),5):bor(pbo(3,1),6) car cao(3,2)]; 58 59 [car cao(3,2) bor(pbo(3,2),5):bor(pbo(3,2),6) car cao(3,3)]; [car\_cao(3,3) bor(pbo(3,3),5):bor(pbo(3,3),6) car\_cao(3,4)]; [car\_cao(5,2) bor(pbo(5,2),5):bor(pbo(5,2),6) car\_cao(5,3)]]; 60 61 62 a = (1:nes); hv = [a\*0 a\*0 a\*0 a\*h a\*0];63 if deb == 1 64 65 a=1;hw = [a\*0 a\*0 a\*0 a\*h a\*0];disp(['c. 64, Conv. coeff. : ',num2str(hw),' W/(m2K)']) 66 67 end 68 end 69 if nvn == 2 % 2 convective sides  $bt = [[car_cao(4,2) bor(pbo(4,2),5):bor(pbo(4,2),6) car_cao(4,3)];$ 70 71 [car cao(3,1) bor(pbo(3,1),5):bor(pbo(3,1),6) car cao(3,2)]; 72 [car cao(3,2) bor(pbo(3,2),5):bor(pbo(3,2),6) car cao(3,3)]; 73 [car cao(3,3) bor(pbo(3,3),5):bor(pbo(3,3),6) car cao(3,4)]; 74 [car\_cao(5,2) bor(pbo(5,2),5):bor(pbo(5,2),6) car\_cao(5,3)]; [car\_cao(5,4) bor(pbo(5,4),5):bor(pbo(5,4),6) car\_cao(5,1)]; 75 76 [car cao(1,3) bor(pbo(1,3),5):bor(pbo(1,3),6) car cao(1,4)]; 77 [car cao(1,4) bor(pbo(1,4),5):bor(pbo(1,4),6) car cao(1,1)]; 78 [car cao(1,1) bor(pbo(1,1),5):bor(pbo(1,1),6) car cao(1,2)]; 79 [car cao(4,4) bor(pbo(4,4),5):bor(pbo(4,4),6) car cao(4,1)]]; 80 a = (1:nes); hv = [a\*0 a\*0 a\*h/2 a\*h a\*0 a\*0 a\*h a\*h/2 a\*0 a\*0];81

82 if deb == 183 a=1;hw = [a\*0 a\*0 a\*h/2 a\*h a\*0 a\*0 a\*h a\*h/2 a\*0 a\*0]; disp(['c. 82, Conv. coeff. : ',num2str(hw),' W/(m2K)']) 84 85 end 86 end if nvn == 3 % 3 convective sides - Exercice n° 4 87 88 bt = [car cao(2,1) bor(pbo(2,1),5):bor(pbo(2,1),6) car cao(2,2);89 car cao(2,2) bor(pbo(2,2),5):bor(pbo(2,2),6) car cao(2,3); car\_cao(2,3) 90 bor(pbo(2,3),5):bor(pbo(2,3),6) car\_cao(2,4); car cao(5,1) 91 bor(pbo(5,1),5):bor(pbo(5,1),6) car cao(5,2); 92 car cao(5,2) bor(pbo(5,2),5):bor(pbo(5,2),6) car cao(5,3); 93 car cao(5,3) bor(pbo(5,3),5):bor(pbo(5,3),6) car cao(5,4); car cao(8,1) bor(pbo(8,1),5):bor(pbo(8,1),6) car\_cao(8,2); 94 95 car\_cao(8,2) bor(pbo(8,2),5):bor(pbo(8,2),6) car\_cao(8,3); 96 car cao(8,3) bor(pbo(8,3),5):bor(pbo(8,3),6) car cao(8,4)]; a = (1:nes); 97 hv = [a\*h a\*h a\*h a\*h a\*h a\*h a\*h a\*h a\*h a\*h];98 99 **if** deb == 1 100 a=1;hw = [a\*h a\*h a\*h a\*h a\*h a\*h a\*h a\*h a\*h]; 101 disp(['c. 94, Conv. coeff. : ',num2str(hw),' W/(m2K)']) 102 end 103 end 104 end 105 end 106 end 107 nec = (nes) \* size(bt, 1);% There are nec convective elements lc = zeros(nec,3);nco = 0;% Localization matrix lc of convective elements 108 109 for ic 110 for ie = nco+1;lc(nco,1) = bt(ic,ie);lc(nco,2) = bt(ic,ie+1); 111 nco 112 end end 113 114 if deb==1;disp(['c.112, N. conv. ele.: ',num2str(nco)]);end if nvn == 1 115 % 1 convective side = 1:size(lc,1) 116 for i 117 lc(i, 3) = dK;% Convective virtual node numb. = numb. of dof 118 end 119 else 120 if nvn == 2 % 2 convective sides k1 = [1 npa\*nes+1 ]; 121 k2 = [npa\*nes (2\*npa)\*nes]; 122 123 end 124 if nvn == 3 % 3 convective sides k1 = [1 nco/3+1 2\*nco/3+1];125 126  $k2 = [nco/3 \ 2*nco/3 \ nco];$ 127 end 128 %if nvn > 1, generation of the conv V. numb. for i = 1:nvn 129 for j = k1(i):k2(i)lc(j,3) = dK+i-nvn;130 end 131 132 end 133 end if deb==1;disp(['c.132, conv v.N numb: ',num2str(dK-nvn+1:dK)]);end 134 135 end

*Table 19: Matlab<sup>©</sup> function cad con.m - localization of convection elements* 

# 3.7 Basic isotherm drawing

In a Coons patch, the isolines of a scalar quantity of a finite element solution are displayed in the  $gra_ipa.m$  function (*Table 69*). Another method for drawing the levels of a scalar function consists in working independently in each element with the function  $gra_lin.m$  (*Table 70*). The gradient of the temperature in the barycenter of the elements (the barycenter corresponds to a low integration with only 1 Gauss point) are computed in  $gra_atg.m$  (*Table 67*). According to the property of super convergence of the Gauss integration points [Barlow 1976], we state that the gradient evaluated at this point is suitable for the representation using arrows symbol. To obtain the heat flow, the gradient is multiplied by -  $k \ge th$ , with k, the element conductivity stored in the vector *co* and *th* the global thickness. The function  $gra_atg.m$  (*Table 15*).

#### 3.8 Thermal bridge in a trapezoidal domain

Now, we modify the shape of the rectangular domain analyzed in *Figure 10* and check the consequence of introducing an horizontal thermal bridge.

The dissipation D in the solid is computed from the temperature gradient average, the conductivity coefficient and the volume V of the mesh:

$$D = \frac{1}{2} k \left( \nabla \tau \right)_{average}^2 V \tag{58}$$

D

 $= 1/2 * 1 Wm^{-1}K^{-1} * (23.3)^{2} K^{2}m^{-2} * V m^{3}$ = 0.5 Wm^{-1}K^{-1} \* 576 K^{2}m^{-2} 0.075 m^{3} = 20.3584 WK.



Figure 38: 2 imposed temperatures, 2 adiabatic faces in a trapezoidal domain





Figure 39: Non homogeneous trapezoidal domain



The introduction of non-homogeneous material is performed using the definition, element by element, of the conductivity coefficient. This function is written with the hypotheses that the numbers of elements in the x and y directions satisfy certain conditions that can be checked in the listing (*Table 8*). The heat flow picture is dominated by the arrows in the central zone, while in the gradient one the same zone of high flows is disappearing due to the small value of the gradients.

### 4. Tutorial IV: Transient heat transfer

To carry out the transient studies, new physical quantities are introduced, such as the density of the material and its heat capacity. The specific heat capacity  $(Jkg^{-1}K^{-1})$  corresponds to a system defined per unit of mass (kg) of a compound (the term 'specific heat' is sometimes used). The thermal capacity  $C(JK^{-1})$  is an extensive scalar quantity.

The thermal diffusivity  $\alpha$  of a material, expressed in  $m^2 s^{-1}$ , represents its tendency to facilitate the heat diffusion.

$$\alpha = \frac{k}{\rho c_p} \tag{59}$$

Useful references: [Lee & Jackson 1976], [Lee 1977], [Lee & Mason 2008], [Siemens 2017].

#### **4.1 Solution of the transient problem**

To introduce the time variation in the heat equations, a new matrix  $[C] (JK^{-1})$  is introduced.

$$\left(\left[C\right] + \theta \ \Delta t \ \left[K\right]\right) \left[T^{n+1}\right] = \left(\left[C\right] - (1 - \theta) \ \Delta t \ \left[K\right]\right) \left[T^{n}\right] + \Delta t \ \left(\theta \left[f^{n+1}\right] + (1 - \theta) \left[f^{n}\right]\right)$$
(60)

The value  $\theta = 1$  corresponds to the implicit scheme, which is considered as unconditionally stable. We write:

$$\left(\left[C\right] + \Delta t \ \left[K\right]\right) \left[T^{n+1}\right] = \left[C\right] \left[T^{n}\right] + \Delta t \ \left[f^{n+1}\right]$$

$$(61)$$

The uni-column matrix [*T*] is divided into two parts:

- 1. the unknown nodal temperatures  $T_l$  and
- 2. the fixed and therefore, constant temperatures  $T_f$

$$\begin{bmatrix} T \end{bmatrix} = \begin{bmatrix} T_1 \\ T_f \end{bmatrix}$$
(62)

Equation (62) becomes:

$$\begin{pmatrix} \begin{bmatrix} C_{11} & C_{1f} \\ C_{f1} & C_{ff} \end{bmatrix} + \Delta t \begin{bmatrix} K_{11} & K_{1f} \\ K_{f1} & K_{ff} \end{bmatrix} \end{pmatrix} \begin{bmatrix} T_1^{n+1} \\ T_f^{n+1} \end{bmatrix} = \begin{bmatrix} C_{11} & C_{1f} \\ C_{f1} & C_{ff} \end{bmatrix} \begin{bmatrix} T_1^n \\ T_f^n \end{bmatrix} + \Delta t \begin{bmatrix} f^{n+1} \\ r^{n+1} \end{bmatrix}$$
(63)

The superscripts *n* and n+1 indicate the iteration number. The variable  $f^{n+1}$  expressed in *W*, represents the heat loading at step n+1, while  $r^{n+1}$  represents the reactions on the fixed *DOF* at the same step. The first group of (63) is:

$$\begin{pmatrix} \begin{bmatrix} C_{11} & C_{1f} \end{bmatrix} + \Delta t \begin{bmatrix} K_{11} & K_{1f} \end{bmatrix} \end{pmatrix} \begin{bmatrix} T_1^{n+1} \\ T_f^{n+1} \end{bmatrix} = \begin{bmatrix} C_{11} & C_{1f} \end{bmatrix} \begin{bmatrix} T_1^n \\ T_f^n \end{bmatrix} + \Delta t \begin{bmatrix} f^{n+1} \end{bmatrix}$$
(64)

Developing this relation gives:

$$\left(\begin{bmatrix} C_{11} \end{bmatrix} + \Delta t \ \begin{bmatrix} K_{11} \end{bmatrix}\right) \begin{bmatrix} T_1^{n+1} \end{bmatrix} = \begin{bmatrix} C_{11} \end{bmatrix} \begin{bmatrix} T_1^n \end{bmatrix} + \Delta t \left(\begin{bmatrix} f^{n+1} \end{bmatrix} - \begin{bmatrix} K_{1f} \end{bmatrix} \begin{bmatrix} T_f \end{bmatrix}\right)$$
(65)

If fixations are present, the solution of this equation is:

$$\begin{bmatrix} T_1^{n+1} \end{bmatrix} = \left( \begin{bmatrix} C_{11} \end{bmatrix} + \Delta t \begin{bmatrix} K_{11} \end{bmatrix} \right)^{-1} \quad \left\{ \begin{bmatrix} C_{11} \end{bmatrix} \begin{bmatrix} T_1^n \end{bmatrix} + \Delta t \left( \begin{bmatrix} f^{n+1} \end{bmatrix} - \begin{bmatrix} K_{1f} \end{bmatrix} \begin{bmatrix} T_f \end{bmatrix} \right) \right\}$$
(66)

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Without fixation:

$$\begin{bmatrix} T^{n+1} \end{bmatrix} = \left( \begin{bmatrix} C \end{bmatrix} + \Delta t \begin{bmatrix} K \end{bmatrix} \right)^{-1} \left\{ \begin{bmatrix} C \end{bmatrix} \begin{bmatrix} T^n \end{bmatrix} + \Delta t \begin{bmatrix} f^{n+1} \end{bmatrix} \right\}$$
(67)

If there are no loads nor fixations, we can remove the indices and we obtain the very simple relation:

$$\begin{bmatrix} T^{n+1} \end{bmatrix} = \left( \begin{bmatrix} C \end{bmatrix} + \Delta t \begin{bmatrix} K \end{bmatrix} \right)^{-1} \begin{bmatrix} C \end{bmatrix} \begin{bmatrix} T^n \end{bmatrix}$$
(68)

The second line of (64), where the unknowns are the outgoing heat flows  $[r^{n+1}]$ , is decomposed as follows:

$$\left( \begin{bmatrix} C_{f1} & C_{ff} \end{bmatrix} + \Delta t \begin{bmatrix} K_{f1} & K_{ff} \end{bmatrix} \right) \begin{bmatrix} T_1^{n+1} \\ T_f \end{bmatrix} = \begin{bmatrix} C_{f1} & C_{ff} \end{bmatrix} \begin{bmatrix} T_1^n \\ T_f \end{bmatrix} + \Delta t \begin{bmatrix} r^{n+1} \end{bmatrix}$$

$$\left[ r^{n+1} \end{bmatrix} = \frac{1}{\Delta t} \begin{bmatrix} C_{f1} \end{bmatrix} \left( \begin{bmatrix} T_1^{n+1} \end{bmatrix} - \begin{bmatrix} T_1^n \end{bmatrix} \right) + \begin{bmatrix} K_{f1} \end{bmatrix} \begin{bmatrix} T_1^{n+1} \end{bmatrix} + \begin{bmatrix} K_{ff} \end{bmatrix} \begin{bmatrix} T_f \end{bmatrix}$$

$$(69)$$

# 4.2 Element capacity matrix

The capacity matrix [*C*] is a function of the density  $\rho$  of the material, its heat capacity  $c_p$  and its volume *V*.

$$\tau = T_1 \left( 1 - \frac{x}{a} \right) \left( 1 - \frac{y}{b} \right) + T_2 \frac{x}{a} \left( 1 - \frac{y}{b} \right) + T_3 \frac{x}{a} \frac{y}{b} + T_4 \left( 1 - \frac{x}{a} \right) \frac{y}{b}$$
(70)

$$\tau = [F][T]$$

$$[F] = \left[ \left(1 - \frac{x}{a}\right) \left(1 - \frac{y}{b}\right) \frac{x}{a} \left(1 - \frac{y}{b}\right) \frac{x}{a} \frac{y}{b} \left(1 - \frac{x}{a}\right) \frac{y}{b} \right]$$

$$[T]^{T} = [T_{1} \quad T_{2} \quad T_{3} \quad T_{4}]$$
(71)

$$[C] = \int_{V} \rho c_{p} [F]^{T} [F] dV$$
(72)

To show the process of integration, we compute the term  $C_{33}$  of the capacity matrix [C]. The volume V is the product of the area *ab* by the thickness *e*.

$$C_{33} = e_{0}^{a} \left( \int_{0}^{b} \rho c_{p} \frac{x^{2} y^{2}}{a^{2} b^{2}} dy \right) dx$$
  
=  $\rho e c_{p} \int_{0}^{a} \frac{b^{3} x^{2}}{3a^{2} b^{2}} dx = \rho e c_{p} \frac{b}{3} \int_{0}^{a} \frac{x^{2}}{a^{2}} dx = \rho e c_{p} \frac{ab}{9} = \frac{\rho V c_{p}}{9}$  (73)

In (74), we observe that the sum of the terms is equal to 36, and, therefore, that, concentrated in one point, the capacity is equal to  $\rho V c_p$ . Matrix *C* is expressed in  $JK^{-1}$ .

$$[C] = \frac{\rho V c_p}{36} \begin{bmatrix} 4 & 2 & 1 & 2 \\ 2 & 4 & 2 & 1 \\ 1 & 2 & 4 & 2 \\ 2 & 1 & 2 & 4 \end{bmatrix}$$
(74)

The capacity matrix of an element given by its localization vector *lo* and the set of nodal coordinates *xyz* is computed in the Matlab<sup>©</sup> function *fem Cae.m* (*Table 20*).

	Matlab <sup>©</sup> function <i>fem_Cae.m</i> - element capacity matrix	
1	<pre>function [C] = fem Cae(xyz,lo) % Element capacity matrix</pre>	
2	Q = [xyz(lo(1), 1:3); xyz(lo(2), 1:3); xyz(lo(3), 1:3); xyz(lo(4), 1:3)];	
3	s = [.5-sqrt(3)/6 .5+sqrt(3)/6 .5+sqrt(3)/6 .5-sqrt(3)/6]; % 4 Gauss pt	3
4	t = [.5-sqrt(3)/6 .5-sqrt(3)/6 .5+sqrt(3)/6]; % 4 Gauss pt	3
5	C = zeros(4, 4);  area = 0.;	
6	for i=1:4 % Loop on the 4 Gauss point	3
7	f = [(1-s(i))*(1-t(i)) s(i)*(1-t(i)) s(i)*t(i) (1-s(i))*t(i)];	
8	fs = [-(1-t(i)) (1-t(i)) t(i) -t(i) ]; % Derivative	3
9	ft = [-(1-s(i)) - s(i) s(i) (1-s(i))]; % Derivative	ī.
10	ds = fs * Q;	
11	dt = ft * Q;	
12	$C = C + f' * f^* \operatorname{sqrt} (\operatorname{dot} (\operatorname{cross} (\operatorname{ds}, \operatorname{dt}), \operatorname{cross} (\operatorname{ds}, \operatorname{dt}))) / 4;$	
13	end	
14	end	

*Table 20: Matlab<sup>©</sup> function fem\_Cae.m – element capacity matrix* 

*Table 21* shows Matlab© instructions allowing to compute element capacity matrices in various geometrical situations. To obtain the effective capacity matrix, the output of fem\_Cae.m has to be multiplied by the thickness th (m), the capacity cp (Jkg-1K-1) and the specific mass ro (kgm-3). The total capacity for the cases presented in Table 21 is equal to th (0.1) x cp (1000) x ro (2500) x sum (sum (C)) / 36 = 250000 JK-1 for the first case and 106 JK-1 for the second one (*Table 21*).

Matlab input	<pre>xyz =[0 0 0;1 0 0;1 1 0;0 1 0];lo=[1 2 3 4]; [C] = fem_Cae(xyz,lo)*36 sum(sum(C))</pre>
Matlab Output	$C = \begin{array}{ccccccccccccccccccccccccccccccccccc$
Matlab input	<pre>xyz =[0 0 0;2 0 0;2 2 0;0 2 0];lo=[1 2 3 4];[C] = fem_Cae(xyz,lo)*36 sum(sum(C))</pre>
Matlab Output	$C = 16 & 8 & 4 & 8 & 144 \\ 8 & 16 & 8 & 4 \\ 4 & 8 & 16 & 8 \\ 8 & 4 & 8 & 16 \\ \end{array}$
Matlab input	<pre>xyz=[0 0 0;2 0 0;2 .5 0;0 .5 0];lo=[1 2 3 4];[C]=fem_Cae(xyz,lo)*36 sum(sum(C))</pre>
Matlab Output	$C = \begin{array}{ccccccccccccccccccccccccccccccccccc$
Matlab input	<pre>xyz=[0 0 0;.5 0 0;.5 2 0;0 2 0];lo=[1 2 3 4];[C]=fem_Cae(xyz,lo)*36 sum(sum(C))</pre>
Matlab Output	$\begin{array}{cccccccccccccccccccccccccccccccccccc$

		2	1	2	4		
Matlab	xyz=[	0 0	0;1.5	0 0;1	1 0;.5	1 0];lo=[1	2 3 4];[C]=fem_Cae(xyz,lo)*36
input	sum(s	um (C	:))				
	C =	5	2.5	1	2	36.	
Matlab		2.5	5	2	1		
Output		1	2	3	1.5		
		2	1	1.5	3		

Table 21: Numerically integrated capacity matrix

# 4.3 Temperature evolution

The procedure *gra\_tev.m* (*Table 22*) is used to draw the time evolution of quantities that are functions of the time, like nodal temperatures of the model or any other quantity derived from the temperature field, which is the primary output of an analysis. These temperatures have to be collected at each iteration step and stored in vectors whose length is the number of iterations more one. An example of drawing produced with this procedure is given in *Figure 41*.

	Function Matlab <sup>©</sup> gra_tev.m – temperature evolution in transient applications
1	<pre>function [] = gra tev(ni,dt,re,tsmax,tsmin,tmoy) % Temperature evolution</pre>
2	<pre>tem = (0:ni)*dt/3600/ni; % Time steps for the graphics</pre>
3	<pre>st = size(tsmin,2);%nj = ni+1;</pre>
4	figure('Position',[100 100 600 300])
5	<pre>plot (tem,tsmax','r');hold on; % Plotting the 3 evolutive functions</pre>
6	<pre>plot (tem,tsmin','b');hold on;</pre>
7	<pre>plot (tem,tmoy ,'k');hold on;</pre>
8	ylabel( 'gra-tev: temp. evolution', 'fontsize', 15)
9	<pre>xlabel(['Number of iterations : ',num2str(ni),', re : ',num2str(re)],</pre>
10	'fontsize',15);grid on
11	<pre>legend('T maximum ','T minimum ','T average','Location','northwest')</pre>
12	<pre>title (['Final: Tmin: ',num2str(tsmin(st)*10/10,3),' K, Tmean: ',</pre>
13	<pre>num2str(tmoy(st)*10/10,3),' K, Tmax: ',num2str(tsmax(st)*10/10,3),</pre>
14	' K'], 'fontsize', 15); hold on; grid on
15	end

*Table 22: Matlab<sup>©</sup> function* gra\_tev.m – temperature evolution

### 4.4 Temperature homogenization in an insulated solid

A uniform temperature test is carried out on a domain of dimensions  $(2 m \times 1m \times 0.5 m)$  whose walls are adiabatic. Half the area is at 300 K, half at 290 K (*line 5* to *line 12* in *fem\_til.m*, *Table 58*, *Table 62*). The time evolution and the moment at which the temperature becomes uniform are examined. The homogenization process depends on the diffusivity.

Input data: conductivity coefficient =  $2 Wm^{-1}K^{-1}$ , specific capacity =  $1000 Jkg^{-1}K^{-1}$ , specific mass =  $2500 kgm^{-3}$ , the heat capacity of the domain is obtained with the Matlab<sup>©</sup> instruction: sum (sum (C)). For this example, it is equal to  $2.5 \ 10^6 JK^{-1}$  (verified with the explicit formula: cap = area\*th\*Cp\*ro \* 1e-6;). After 33.2 hours, the temperature gap is reduced by half: 5 K. Homogeneity of the temperature is obtained after 180 hours, when the temperature gap is equal to 0.1 K (*Figure 41*). At the displayed time step of 24, 48, 72 and 96 hours, the temperature gap is decreasing in the following sequence: 6.5 K, 3.3 K, 1.7 K, and finally 0.8 K. To ensure the coherence of the data with the mesh, it is mandatory to impose an even number of nodes per patch side. Here, the flag Gi = 17 is used in the function *fem\_til.m* (*lines 8* to 14) to specify these unusual initial conditions: half of the domain at 290 K and half at 300 K.



Figure 41: Smoothing process convergence in temperature homogenization



Figure 42: Evolution of the temperature field in a smoothing process

### 4.5 Heating of a solid at initial uniform temperature

The next example (*Figure 43*) relates to the heating of a solid immersed in a fluid at 300 K with convective heat exchanges on the four sides of the solid. At the beginning, the temperature of the solid is 280 K. After 100 h, the mean temperature is 296 K.



**Temperature** 290 T minimum Specific capacity : 1000 J/(kg.K) Taverage Specific mass : 2500 kg.m-3 285 Tot. cap.sum(sumI) : 500000 J/K Interv. Drawing ist : 100 h 280 Time step 2 h • 20 40 60 100 120 140 180 200 80 160 : 200 h Analyzed period Elapsed time (hours) 14.8 sec CPU

Figure 45: Evolution of max, min and mean temperatures in a heating operation: 200h

The quantity of exchanged heat is equal to the product of the temperature growth by the specific heat and by the mass of the solid.

#### 4.6 Periodic imposed heat flow

The problem addressed here is the heating of a domain from its upper horizontal border. The periodic heating function can be applied on any patch side (*Table 14*).



Figure 46 : Thermal loading over a period of 10 days (240 hours)

	Matlab <sup>©</sup> function <i>gra_hie.m</i> – vizualisation of a periodic heat load
1	<pre>function [] = gra hie(ni,dt,ga) % Evolution of incoming heat</pre>
2	<pre>tem = (0:ni)*dt/3600/ni; % Time steps for the time graphics</pre>
3	figure('Position',[100 100 700 300]);
4	<pre>plot (tem,ga*1.e-3','b');hold on;grid on</pre>
5	xlabel('Elapsed time (hours) ', 'fontsize', 15)
6	<pre>ylabel('Injected heat flow (kW)','fontsize',15)</pre>
7	<pre>title (['gra-hie: Total injected heat: ',num2str(sum(ga)*1.e-6,3),</pre>
8	' MJ'],'fontsize',15)
9	end

Table 23: Matlab<sup>©</sup> function gra\_hie.m – visualization of a periodic scalar field

The drawing of *Figure 46* is created only if the time step (variable *dth*) is equal to 1 hour (*line 233* in *Fiammetta.m*, *Table 58*). The function  $gra\_hie.m$  (*Table 23*) is called at *line 334* of *Fiammetta.m*. The time function f(t) used to weight the heat flow input is given by:

This function is adimensional, p is the period of the sinusoidal function and t the time, expressed in the same unit as the period p. Over the semi-period p/2, the average of the function is:

$$\frac{2}{p} \int_{0}^{p/2} \sin\left(\frac{2t}{p}\pi\right) dx = -\frac{2}{p} \left[\cos\left(\frac{2t}{p}\pi\right) \frac{p}{2\pi}\right]_{0}^{p/2} = \frac{-1}{2\pi} \left(-1 - 1\right) = \frac{2}{\pi} \approx 0.6366 \quad (76)$$

10

Then, over the period p, the average of the time weighting function f(t) is  $1/\pi$  or 0.3183. If the intensity of the imposed heat flow is  $i_h = 50 Wm^{-2}$  and if the time is expressed in seconds, the heat flow is:

$$\overline{q}_n = i_h f(t) \ Wm^{-2} = i_h \ \sin\frac{t \ \pi}{12*3600} \ Wm^{-2} = i_h \ \sin\frac{t \ \pi}{12*3600} \ Wm^{-2}$$
(77)

The area of the boundary where heat is injected is:

$$s_b = e \ge L = 0.1 * 3 = 0.3 \ m^2$$
 (78)

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In this expression, e is the thickness of the solid, L the length of the border and  $i_h$  is the imposed flow density. The imposed heat flow (W) is:

$$\overline{q}_{h}b_{s} = i_{h} \ e \ L f(t) \ W = i_{h} \ e \ L f(t) \ W = i_{h} \ e \ L \sin\frac{t\pi}{12*3600} \ W = i_{h} \ e \ L \ \sin\frac{t\pi}{43200} \ W$$
(79)

In one day, the injected heat is equal to  $h_d$ , now expressed in joules:

....

$$h_{d} = \int_{0}^{43200} \overline{q}_{n} b_{s} dt J = i_{h} e L \int_{0}^{43200} \sin \frac{t\pi}{43200} dt J = i_{h} e L \left[ -\frac{43200}{\pi} \cos \frac{t\pi}{43200} \right]_{0}^{43200} J$$

$$h_{d} = \frac{i_{h} e L 43200 * 2}{\pi} J = 0.2475 i_{h} MJ$$
(80)

With a heat flow density  $i_h = 50 \ Wm^{-2}$  and a loaded area  $eL = 0.3 \ m^2$ , the total incoming heat flow after 30 days is:  $h_d * 30 = 12.4 \text{ MJ}$ . The sequences of specific lines of the example shown in *Figure 53* are given in the following table.

```
..... 1. Standard cavity .....
                                               2
     xyz cao = [0 0;3 0;3 3;0 3;1 1;2 1;2 2;1 2];
3
     car cao = [6 5 1 2;6 2 3 7;7 3 4 8;1 5 8 4];nbo = 12; nvn=1;vc=[1.5 1.5];
4
     disp('L 5, 1. Standard cavity : ')
49
                                  ..... Neumann boundary conditions
     lg = [car cao(3,2) bor(pbo(3,2),5):bor(pbo(3,2),6) car cao(3,3)];
50
51
     nh = size(lg, 2);
52
     for I
                 = 1:nh;gh(lg(1,i),1) = 2;end% Weight functions on a CAD side
     gh(lg(1,1),1) = 1;gh(lg(1,nh),1) = 1;gh = gh/(nni+1)/2;
53
     if size(lg,2) < 12;disp(['List of loaded nodes: ',num2str(lg)]);end</pre>
54
     if size(lg,2) < 12;disp(['Loads nodal weights : ',num2str(gh(lg(1:nh))'...
55
56
            )]);end
         tcan= ones(1,no)*280;tmi=280; % Initial conditions transient analysis
117
119
        nit =720;dth=1;dtd=180; % Number iterations & delta tau per iteration
182
        pai
                = .5;
                                 %pai
                                          = (max(tcan)-min(tcan))/20;
                = [tmi pai 291]; %gt
184
                                          = [min(tcan) pai max(tcan)]; %
        qt
232
                = min(min(tcan),tmi);gt=[tmi pai 291];
         tmi
233
         figure; ip=0; a=-.1; b=-.09; ha=max(xyz(:,2));
         fill([a b b a],[0 0 ha ha],[280 280 291 291]);hold on;
           Table 24: Instructions for a test of time dependent heat loads
```

4.7 Interaction between spatial and temporal discretization



If we modify the mesh of the example shown in *Figure 43* to make it coarser (8 x 8 elements),

we obtain some strange results. We observe in *Figure 47* that, at the beginning of the process, the minimum temperature inside the mesh is decreasing, and that 9 iterations are needed for the temperature to become again greater than the initial one. According to the second law of

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thermodynamics, this behavior is not physically acceptable. However, the convergence is very similar to that of *Figure 44*; in both cases, the final temperature gap is equal to 7.8 *K*.



#### 4.8 Adiabatic cavity & imposed temperatures on the top

Figure 48: Adiabatic cavity, 1 month,  $T_{ini} = 280 \text{ K}$ ,  $T_{top} = 300 \text{ K}$ 

In *Figure 48*, we observe that the stored heat (t.81, Stored heat: 21.8 MJ), is, as expected, the product of (t.40, sum(sum(C)): 2 MJ/K) and (t.80, Tmean - Tini: 10.9 K). To display the evolution of the temperature field in the domain, it is mandatory to use the same color bar for all the drawings. It is obtained thanks to the definition and the display of the thin vertical bar at the left of the drawing. In *Figure 49*, all the illustrations correspond to the temperature gap: 280 - 300 K. To enforce the colorbar to act always between the initial temperature *tmi* and 300 K, we enable the Matlab<sup>©</sup> instructions 70 & 71 in *fem til.m*.



Figure 49: Adiabatic cavity, evolution of the temperature field

# 4.9 Convection in a square cavity

The interaction of the internal fluid contained in a cavity with the solid continuum is determined by the convection laws.





Figure 50: Isotherms, convection in the cavity, 1 month

The heat flow in the conductive medium appears more clearly in the element-by-element heat flows drawing. In *Figure 51*, the flow enters in the cavity essentially from above and leaves it on almost all of the other three sides. The arrows representing the flows are orthogonal to the isotherms and their lengths are inversely proportional to the distances between successive isothermal lines.



Figure 51: Two visualizations of the heat flow for a mesh of 100 elements

To compute the nodal contributions of the heat flow input equal to 50 x f(t)  $Wm^{-2}$ , we have to integrate the heat flow intensity over the side of the domain and to distribute it on the nodes. If we assume that the heat flow is constant on the side, and if the mesh is uniform (*n* elements on the side), the weight vector is: [.05 .1 ... .1 .05]/n, it contains (n+1) terms whose sum is equal to 1. For a thickness e = 1 *m* and a length L = 3 *m*, the weight vector has to be multiplied by e *L*. So, the nodal weights are equal to:  $[.05 .1 ... 1 .05]/n * 3 m^2$ . Multiplying by the heat input: 50  $Wm^{-2}$ , the sum of nodal input loads =150 f(t) W.



The loading is carried out by intoducing a sinusoidally varying heat flow over a half-period of twelve hours. During the following half-period the supplied heat is zero. Twenty-four hour cycles are built (*Figure 46*). The injected average power is therefore:  $150 / \pi W = 28.648 W$ . the mean heat flow is equal to  $28.648 / .8 = 35.81 Wm^{-2}$ . During each 24 *h* period, the domain is receiving  $150 / (\pi * 3600 * 24) = 4125.3 kJ$ . In a month (720 *h* or 30 days), the input is 4125.3 \* 30 = 123.759 MJ. If we multiply the difference between the final mean temperature (black curve 285.9 K) of the solid and the initial one (280 K) by the specific capacity (1000 J kg<sup>-1</sup>K<sup>-1</sup>), the specific mass (2500 kg m<sup>-3</sup>) and the volume of the solid (.8 m<sup>3</sup>), we obtain the heat quantity of 119 MJ.



Figure 53: Isotherms after 15 days (T gap = 11.5 K) and 30 days (T gap = 17.8 K)

The Matlab<sup>©</sup> function *fem\_tra.m* (*Table 25*) gives the solution of the iteration *it* of the transient problem when fixations are present.

	Matlab	<sup>©</sup> function <i>fem_tra.m</i> – linear transient problem
1	function [tca]	= fem_tra(K,C,dti,g,lfi,tcan)
2	dK	= size(K,1); % Size of matrices K and C
3	nfi	= size(lfi,2); % Number of fixed DOF
4	ntca	= dK - nfi; % Number of unknowns
5	ldv	= 1:dK; % ldv contains the sequence of node numbers
6	for k	= 1:nfi % Detection of the fixed DOF
7	ldv(lfi(k))	= -ldv(lfi(k));% In ldv, signs of fixed nodes are negative
8	end	
9	ldn	= zeros(1,dK);
10	ifi	= dK+1;
11	ili	= 0;
12	for k	= 1:dK
13	if ldv(k)	< 0
14	ifi	= ifi -1;
15	ldn(ifi	() = -ldv(k);
16	else	
17	ili	= ili+1;
18	ldn(ili	l) = ldv(k);
19	end	
20	end % Ve	ector ldn allows moving the fixed DOF at the end of the list
21	tca	$= \operatorname{zeros}(dK, 1);$
22	Kn	= zeros(dK,dK); Cn = Kn;
23	tcb	= zeros(dK, 1); $g2 = tcb;$
24	for k	= 1:dK % Dirichlet b.c. need shifts in: K, C, tcan & g
25	for 1	= 1:dK
26	Kn(k,1)	= K(ldn(k),ldn(l)); % Shifting lines and columns in K
27	Cn(k,1)	= C(ldn(k),ldn(l)); % Shifting lines and columns in C
28	end	
29	tcb(k)	= tcan(ldn(k)); % Shifting lines in tcan
30	g2 (k)	= g (ldn(k)); % Shifting lines in g
J⊥ 20	end	% End shifting DOF in K, C, tcan, g
32	ta (1 )	= ntca+1; % Compute the solution
33	tcb (l:ntca)	= (Cn(1:ntca,1:ntca) + dti*Kn(1:ntca,1:ntca))\

```
34 (Cn (1:ntca,1:ntca) *tcb (1:ntca,1) + ...
35 dti*(g2(1:ntca,1) -Kn (1:ntca,ta:dK) *tcb (ta:dK,1)));% Tu. p. 40, equ. 66
36 for kk = 1:dK % Restore right sequence of DOF in vector tca
37 tca (ldn(kk),1)=tcb(kk,1); % tca is the single output of this function
38 end
39 end
```

Table 25: Matlab<sup>©</sup> function fem tra.m – solution of the linear transient equations

# 5. Tutorial V: Radiosity

### 5.1 Theoretical background

This chapter refers to longwave radiative exchanges [Beckers 2013]. The variables are both radiosities and surface temperatures. In radiative heat transfers, the first step is to compute the topological and geometrical relations between radiating surfaces. The view factor or form factor  $F_{ij}$  represents the fraction of radiant energy leaving surface *I* and impinging on surface *j* [Goral *et al* 1984].

In 2D [Beckers 2011], the "*point – segment*" view factor relates a point to a segment (*Figure 54*) according to the formula:



Figure 54: 2D "point – segment" view factor [Beckers 2011]

The explicit expression of the view factor is computed via the Nusselt analogy (*Figure 54*) [Nusselt 1928, Beckers *et al*, 2009, Beckers & Beckers 2014]: it is the projection of the circular arc intercepted by the two rays on the base diameter of the semi-circle. This projection must then be divided by the area of the base circle or, here, by the length of the base diameter (= 2, because the radius of the circle = 1). When calculating the upper semicircle on a polygon spanning, the sum of the view factors is equal to the diameter of the semicircle. The view factor is therefore given by:

$$F_{dL-j} = \frac{1}{2} \left( \frac{x_1}{r_1} - \frac{x_0}{r_0} \right)$$
(82)

To obtain the view factors of the elements of a surrounding square from a differential element dL (*Figure 54*) situated on one of its sides, we perform a numerical integration on the other sides of the square. This is completed using Gaussian quadrature. The point-segment view factors are evaluated at the various Gauss points of the square sides, the number of which is determined by the desired precision. The weighted sum of these values constitutes the approximation of the integral. The *closure* condition expresses that the sum of the view factors is equal to 1 for each row of the matrix [F]:

$$\sum_{j=1}^{N} F_{ij} = 1 \qquad closure \tag{83}$$

The view factors must satisfy a second condition: the *reciprocity* 

$$A_i F_{ij} = A_j F_{ji} \qquad reciprocity \tag{84}$$

In (85), the terms  $A_i$  and  $A_j$  define the areas of the patches linked by the view factors (here, the lengths of the segments times their thicknesses). If the considered segment is not horizontal, the form factor is calculated with a generalization of formula (82) to the side on which the element dL is located. Let be  $\vec{r}_i / |r_i|$  the unit vector joining the studied segment to the extremities I = 0 and I = 1 of the target segments and  $\vec{t}$  the tangent to the studied segments. The "*point – segment*" view factor is:

$$F_{dL-j} = \frac{1}{2} \left( \frac{\vec{r}_1}{|\vec{r}_1|} - \frac{\vec{r}_0}{|\vec{r}_0|} \right) \cdot \vec{t}$$
(85)

The view factor  $F_{ij}$  is obtained by integrating this "point – segment" view factor over patch *i*:

$$F_{ij} = \frac{1}{A_i} \int_i F_{dL-j} dA_j \tag{86}$$

In this relation,  $dA_j$  is the product of the differential length dL of element *j* by its thickness while  $A_i$  is the product of the length of element *i* by its thickness.

The next development is based on [Lobo & Emery 1995], [Rupp & Péniguel 1999], [Coulon 2006], [Beckers 2020 a, b, c] and [van Eekelen 2012]. This formulation facilitates the transcription to *Matlab*<sup>©</sup> code. Capital letters represent vectors (seen as uni-column matrices) and capital letters between brackets represent matrices.

The equilibrium of the radiative heat exchanges on the surface of the solid expresses that the *radiosity B* ( $Wm^{-2}$ ) is the sum of the *exitance E* ( $Wm^{-2}$ ) and the *reflected irradiance* [R] J, [Goral *et al* 1984].

$$B = E + \begin{bmatrix} R \end{bmatrix} J \tag{87}$$

In (87), the diagonal matrix [*R*] contains the reflection coefficients. They satisfy the Kirchhoff' law which is relating, in each element *i*, the emissivity  $\varepsilon_i$ , the absorptivity  $\alpha_i$ , and the reflectivity  $\rho_i$ :

$$R_{ii} = \rho_i \quad ; \quad \varepsilon_i = \alpha_i \quad ; \quad \rho_i = 1 - \varepsilon_i \tag{88}$$

As shown in (87), the radiosity component  $B_i$  is the radiant flux leaving the surface *i* of the solid domain, it is the sum of the emitted  $E_i$  and the reflected  $\rho_i J_i$  fluxes. The incoming irradiance vector J is related to the other elements of the domain by the view factor matrix [F] defined in (86). When they are visible, it is also related to the sky by the sky view factor uni-column matrix  $F_{sky}$  and to the infinite horizontal plane assimilated to the ground, by the ground view factor uni-column matrix  $F_{gr}$  (nearby, we use magenta color for the quantities related to the sky and the ground):

$$J = [F]B + F_{sky}e_{sky} + F_{gr}e_{gr}$$
(89)

Introducing the incoming irradiance (89) in (87), we have:

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$$B = E + [R] \left\{ [F]B + F_{sky}e_{sky} + F_{gr}e_{gr} \right\}$$
(90)

We now compute the exitances as functions of the radiosities

$$E = B - [R][F]B - [R]F_{sky}e_{sky} - [R]F_{gr}e_{gr}$$
  
= {[I]-[R][F]} B - [R]F\_{sky}e\_{sky} - [R]F\_{gr}e\_{gr} (91)  
= [M]B - [R]F\_{sky}e\_{sky} - [R]F\_{gr}e\_{gr}

In (91), we have introduced the *radiosity matrix*:

$$[M] = [I] - [R][F]$$
(92)

From (91), we deduce:

$$B = [M]^{-1} \left\{ E + [R] F_{sky} e_{sky} + [R] F_{gr} e_{gr} \right\}$$
(93)

The *radiative load* vector  $Q(Wm^{-2})$  is obtained by subtracting the *income* flux vector  $J(Wm^{-2})$  to the *radiosity outcome* flux vector  $B(Wm^{-2})$ :

$$Q = B - J \tag{94}$$

Replacing in (94) J from (89), we obtain:

$$Q = B - [F]B - F_{sky} e_{sky} - F_{gr}e_{gr}$$
  
=  $\{[I] - [F]\} - B - F_{sky} e_{sky} - F_{gr}e_{gr}$  (95)

Replacing B from (93), we finally have:

$$Q = \{ [I] - [F] \} [M]^{-1} E + \{ [I] - [F] \} [M]^{-1} [R] \{ F_{sky} e_{sky} + F_{gr} e_{gr} \} - \{ F_{sky} e_{sky} + F_{gr} e_{gr} \}$$
(96)

This solution involves two contributions, the first one is related to E and the second one to  $E_{sky}$  and  $E_{gr}$ 

$$Q = \{ [I] - [F] \} [M]^{-1} E + \{ \{ [I] - [F] \} [M]^{-1} [R] - \lfloor I \rfloor \} \{ F_{sky} e_{sky} + F_{gr} e_{gr} \}$$
(97)

The exitances components,  $E_i$  ( $Wm^{-2}$ ), of the vector E introduced in (87) may be calculated as function of the surface temperature field of the boundary elements i, the emissivity  $\varepsilon_i$  and the Stefan-Boltzmann constant  $\sigma$  ( $Wm^{-2}K^{-4}$ ):

$$E \rightarrow E_i = \varepsilon_i \ \sigma \ T_i^4$$

$$\tag{98}$$

If present, the sky and ground exitances are obtained in the same way:

$$E_{sky} \rightarrow E_{sky} = \varepsilon_{sky} \ \sigma \ T_{sky}^4 = \sigma \ T_{sky}^4 \text{ (if sky emissivity = 1)}$$

$$E_{gr} \rightarrow E_{gr} = \varepsilon_{gr} \ \sigma \ T_{gr}^4 = \sigma \ T_{gr}^4 \text{ (if sky emissivity = 1)}$$
(99)

Throughout (93) to (96), Q is a function of the surface temperature of the radiating solid and can therefore be injected in the finite element model.

$$Q = \{ [I] - [F] \} [M]^{-1} E(\tau) + \{ \{ [I] - [F] \} [M]^{-1} [R] - \lfloor I \rfloor \} \{ F_{sky} e_{sky} + F_{gr} e_{gr} \}$$
(100)

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In (100), the vector  $E(\tau)$  is changing at each time iteration step. The last two terms of (99) correspond to the sky and ground radiations which have both imposed temperatures. These terms are classical second members of the system. In (100), all the quantities are expressed in variables resulting from a discretization based not on the finite element mesh, but on element interfaces (surfaces in 3D and edges in 2D).

To insert the relation (100) in the finite element model, we have to distribute the mid-edge loads on the adjacent nodes. This process is not trivial, except if the number of radiative nodes is equal to the number of radiative edges, which is the case if the radiative contour is closed.

In many other situations, we have more nodes than edges, as it is the case in 3D models (for instance, a cube has 6 faces and 8 vertices) and with open contours. In this situation we have to define a rule that allows a uniform distribution and respects the total flow.

We have thus to compute the nodal *radiant* fluxes on the two nodes (0 & 1) surrounding the element *i*:  $h_{0i}$  and  $h_{1i}$ . The fluxes satisfy the relation:  $h_{0i} + h_{1i} = a_i q_i$ , where  $a_i$  is the area of the edge *i* (length time thickness). Because these edges are on the boundary of the mesh, each side *i* appears only once and the connected nodes no more than twice. Finally, the nodal radiant fluxes  $h_i$  are weighted averages of the edge fluxes  $q_i$ . Formally, we can write:

$$H = \begin{bmatrix} W \end{bmatrix} Q \tag{101}$$

We have still to overcome a last problem: the vector E concerns surface elements involving temperatures  $T_i$  at the fourth power, with the consequence that the finite element problem is highly nonlinear. To overcome this problem, we replace the temperatures of iteration *it* by those of iteration *it*-1:

$$E_{i} = \varepsilon_{i} \sigma \left(\tau_{i}^{4}\right)_{it-1} \rightarrow \left(E\right)_{it-1}$$
(102)

For the sky and the ground, the relations are:

$$e_{sky} = \sigma \tau_{sky}^4 \qquad \& \qquad e_{gr} = \sigma \tau_{gr}^4 \tag{103}$$

Equation (99) becomes:

$$Q = \{ [I] - [F] \} [M]^{-1} (E)_{it-1} + \{ \{ [I] - [F] \} [M]^{-1} [R] - \lfloor I \rfloor \} \{ F_{sky} \sigma \tau_{sky}^4 + F_{gr} \sigma \tau_{gr}^4 \}$$
(104)

This relation exhibits three second member vectors that have to be introduced in the global finite element system after being expressed in nodal variable.

#### **5.2 View factor matrix**

*Table 26* gives the instructions for the generation of the list of nodes concerned with radiative heat exchange in three situations: cavity, street section and balcony located on the left side of the meshed domain. The vector *lv* provides the listing of the patch vertices while the vector *lcont* is giving the listing of the nodes involved in the radiative exchanges. Data of a rectangular cavity are shown in *Figure 55*.

Ν	Matlab <sup>©</sup> function <i>cad_ban.m</i> – Radiative nodes of cavity, street or balcony								
1	function	<pre>[lcont,lv] = cad_ban(car_cao,bor,pbo,nni,cs)</pre>	8 20210929						
2	if cs ==1		% Cavity						
3	c1	= $[car_cao(1,1) bor(pbo(1,1),5):bor(pbo(1,1),6)$	car_cao(1,2)];						
4	b1	= c1(size(c1,2):-1:1);							
5	c2	= $[car_cao(2,4) bor(pbo(2,4),5):bor(pbo(2,4),6)$	car_cao(2,1)];						
6	b2	= c2(size(c1,2)-1:-1:1);							
7	с3	= $[car_ao(3,4) bor(pbo(3,4),5):bor(pbo(3,4),6)$	<pre>car_cao(3,1)];</pre>						

= c3(size(c1,2)-1:-1:1); b3 9 c4 = [car cao(4,2) bor(pbo(4,2),5):bor(pbo(4,2),6) car cao(4,3)]; 10 = c4(size(c1,2)-1:-1:2); b4 lcont = [b1 b2 b3 b4]'; 11 % List of cavity boundary nodes 12 = [lcont(1) lcont(nni+2) lcont(2\*nni+3) lcont(3\*nni+4)];% Vert. lv 13 end 14 if cs ==2 % ..... 11. Street section - 3 patches = [car cao(1,1) bor(pbo(1,4),6):-1:bor(pbo(1,4),5) car cao(1,4)]; 15 с1 16 c2 = [car\_cao(2,1) bor(pbo(2,4),6):-1:bor(pbo(2,4),5) car\_cao(2,4)];  $= [car cao(3,1) bor(pbo(3,4),6):-1:bor(pbo(3,4),5) car_cao(3,4)];$ 17 c3 18 lcont = [c1 c2(2:size(c2,2)-1) c3]'; % List of street boundary nodes 19 lv = [lcont(1) lcont(nni+2) lcont(2\*nni+3) lcont(3\*nni+4)]; % Vert. 20 end if cs ==3 % List of balcony boundary nodes..... 21 22 = [[car cao(5,4) bor(pbo(5,4),5):bor(pbo(5,4),6) car cao(5,1)]; bt 23 [car cao(1,3) bor(pbo(1,3),5):bor(pbo(1,3),6) car cao(1,4)]; 24 [car cao(1,4) bor(pbo(1,4),5):bor(pbo(1,4),6) car cao(1,1)]; 25 [car\_cao(1,1) bor(pbo(1,1),5):bor(pbo(1,1),6) car\_cao(1,2)]; 26 [car\_cao(4,4) bor(pbo(4,4),5):bor(pbo(4,4),6) car\_cao(4,1)]]; 27 lcont = [bt(1,1:nni+2) bt(2,2:nni+2) bt(3,2:nni+2) bt(4,2:nni+2)... bt(5,2:nni+2)]'; % DOF concerned by radiative heat transfer 28 = [lcont(1) lcont(nni+2) lcont(2\*nni+3) lcont(3\*nni+4)... 29 lv lcont(4\*nni+5) lcont(5\*nni+6)]'; 30 % Vertices 31  $\operatorname{end}$ 32 if cs == 433 bt = [[car cao(2,4) bor(pbo(2,4),5):bor(pbo(2,4),6) car cao(2,1)];34 [car\_cao(1,4) bor(pbo(1,4),5):bor(pbo(1,4),6) car\_cao(1,1)]]; 35 lcont = [bt(1,1:nni+2) bt(2,1:nni+2)]'; 36 = [lcont(1) lcont(nni+2) lcont(2\*nni+4)]; lv 37 end 38 if cs ==5  $\$  Quadrilateral:!! previous version replaced by a new 20211021!! 39 bt = [[car\_cao(2,4) bor(pbo(2,4),5):bor(pbo(2,4),6) car\_cao(2,1)]; [car\_cao(1,4) bor(pbo(1,4),5):bor(pbo(1,4),6) car\_cao(1,1)]]; 40 8 lcont = [bt(1,1:nni+2) bt(2,1:nni+2)]'; 41 42 lv = [lcont(1) lcont(nni+2) lcont(2\*nni+3)]; Ŷ 43 bt = [[car\_cao(1,2) bor(pbo(1,2),5):bor(pbo(1,2),6) car\_cao(1,3)]; 44 [car\_cao(1,4) bor(pbo(1,4),5):bor(pbo(1,4),6) car\_cao(1,1)]]; 45 lcont = [bt(1,1:nni+2) bt(2,1:nni+2)]'; lv = [lcont(1) lcont(nni+2) lcont(nni+3) lcont(2\*nni+4)];46 end 47 48 end

*Table 26: Matlab<sup>©</sup> function cad\_ban.m – radiative nodes of cavity, street or balcony* 

### $\rightarrow$ a) Rectangular cavity

The function *geo\_vfs.m* (*Table 27*) allows computing the view factor matrix for a rectangle whose length and height are stored in the 2 x 1 uni-column matrix *Lel*.

```
Fiammetta_20211111
Rectangular cavity, Gi: 12
```

[(1:npv)'	xyz	cao]			1	0	0	
	_				2	3	0	
					3	3	6	Labels & normals of the 4 natche(s)
					4	0	6	
					5	1	1	
					6	2	1	4 3
					7	2	5	
					8	1	5	3
[(1:np)'	car c	ao]	1	6	5	1	2	
	_		2	6	2	3	7	
			3	7	3	4	8	
			4	1	5	8	4	
[(1:nbo)'	bor(	:,1:6)	]					
1	6	5	1	0	9	10		
2	5	1	1	4	11	12		
3	1	2	1	0	13	14		4 2
4	2	6	1	2	15	16		
5	2	3	2	0	17	18		
6	3	7	2	3	19	20		
7	7	6	2	0	21	22		
8	3	4	3	0	23	24		
9	4	8	3	4	25	26		
10	8	7	3	0	27	28		
11	5	8	4	0	29	30		
12	4	1	4	0	31	32		
[(1:np)'	pbo]		1	1	2	3	4	1 2
			2	4	5	6	7	
			3	6	8	9	10	•
			4	2	11	9	12	

Figure 55: Input data – Gi = 12, Rectangular cavity

	Matlab <sup>©</sup> function <i>geo_vfc.m</i>
1	<pre>function[F] = geo vfs(n,Lel,ns)% n is the numb. of elements on the 4 sides</pre>
2	xs = Lel(1); ys = Lel(2); % Lel = vector of the side lengths
3	no = n+1; % no is the number of nodes on each side
4	<pre>if ns == 4;n4=n*ns;else;n4=n*ns+2;end % VF mat.: ns sides or ns + sky</pre>
5	F = zeros(n4,n4); r0=zeros(1,n4); r1=zeros(1,n4); f = zeros(1,n4);
6	<pre>xc = zeros(1,n4) ;yc = zeros(1,n4);Le = yc; % Edges definition</pre>
7	<pre>xn = zeros(1,n4+1);yn = zeros(1,n4+1); % vertices definition</pre>
8	for i = 1:n % Ordered nodes in the street: from bottom-left, area left
9	$xn(i + 1) = xs/n^{i}; xn(no + i) = xs; xn(no + n+i) = xs-xs/n^{i};$
10	yn(i + no) = ys/n*i; yn(no +n+i) = ys; yn(3*n+1+i) = ys-ys/n*i;
11	end
12	for i = 1: n4;Le(i)=sqrt((xn(i+1)-xn(i))^2+(yn(i+1)-yn(i))^2);end
13	for i = 1: n4;xc(i)=(xn(i)+xn(i+1))/2; yc(i)=(yn(i)+yn(i+1))/2;end
14	ts = [1 0 1;0 1 -1;-1 0 1;0 -1 -1];% Tangents of edges & their sign
15	for np = 1 : n4% Compute the form factor matrix for the np elements
16	i0 = 0; i1 = 1;
17	for i = 1 : n4 % Loop on the n4 points
18	i0 = i0+1;
19	i1 = i1+1;
20	<pre>nuc = ceil(np/n);</pre>
21	$r0(i) = sqrt((xn(i0) - xc(np))^2 + (yn(i0) - yc(np))^2);$
22	$r1(i) = sqrt((xn(i1)-xc(np))^2+(yn(i1)-yc(np))^2);$
23	f(i) = (((xn(i0)-xc(np))/r0(i)-(xn(i1)-xc(np))/r1(i))*
24	ts(nuc,1)-((yn(i0)-yc(np))/r0(i)-(yn(i1)-yc(np))/r1(i))*
25	ts(nuc,2))*ts(nuc,3)/2;
26	end
27	<pre>for i = 1:n;f((nuc-1)*n+i) = 0.;end % View factor of anal. face</pre>
28	F(:,np) = f; % In geo_vfsold.m we have: F(np,:) = f;
29	end
30	end

*Table 27: Matlab<sup>©</sup> function* **geo\_vfc.m** – view factor matrix – ns sides domain

The view factors are calculated using the "*point – segment*" method (86). The cavity is oriented with the sides parallel to the global axes. If all the segments have the same length, the view

factor matrix is symmetric according to the *reciprocity property* (85) and both the sums of columns and lines are equal to 1 (*closure property* (84)). *Table 28* shows the instructions used to visualize the view factor matrix and the *closure property* when there is only one element per square cavity side.

H	<pre>F = geo_vfc(1,[1 1],4); disp(F); disp(sum(F)); disp(sum(F,2))</pre>					
					1 1 1 1	
(	) (	0.2764	0.4472	0.2764	1	
0.276	54	0	0.2764	0.4472	1	
0.447	72	0.2764	0	0.2764	1	
0 276	54	0 4472	0 2764	0		
0.270	5-1	0.11/2	0.2704	0	1	
<pre>Reciprocity property test n=1;Lel= [1 1 1 1];lon = zeros(1,n*4);k=0; for j = 1:4;for i = 1:n;k = k+1; lon(k) = Lel(j)/n; end; end; ns=size(lon,2);Reci=zeros(ns,ns);for i = 1:ns; for j=1: ns; Reci(i,j) = lon(i)*F(i,j)-lon(j)*F(i,j); end;end; disp(Reci);</pre>						
0	0	0	0			
0	0	0	0			
0	0	0	0			
0	0	0	0			

*Table 28: View factor matrix F in a square cavity – 4 segments* 

From the middle of the bottom side of a square cavity, the "*point – segment*" view factor of the top face is equal to  $\sqrt{5/5} = 0.4472$ ; the view factors related to the adjacent sides are then equal to  $(1 - \sqrt{5/5})/2 = 0.2764$ . We observe that only these two values are present in the matrix of *Table 28*. In the square cavity, the results are the same, using either *geo\_vfsold.m* or *geo\_vfs.m* functions (*Table 27*).

To improve this evaluation, the best method is to perform a Gauss quadrature on the evaluated segment. The Matlab function *geo\_vfr.m* is computing the view factor matrix with two Gauss points leading to the results of *Table 30*.

	Matlab <sup>©</sup> function <i>geo_vfr.m</i>
1	<pre>function[F] = geo vfr(n,Lel) % Rectangular cavity view factor matrix</pre>
2	xs = Lel(1); ys = Lel(2); % Lel = vector of the side lengths
3	no = n+1;% n: number of elem. & no : number of nodes per patch side
4	nf = n*4; % Size of the view factors matrix
5	F = zeros(nf, nf); r0 = zeros(1, nf); r1 = r0; f = r0; xc = r0; yc = r0;
6	xn = zeros(1,nf+1);yn = xn; % vertices definition
7	for I = 1:n % Ordered nodes from bottom-left, area left
8	xn(I + 1) = xs/n*I; xn(no + i) = xs; xn(no + n+i) = xs-xs/n*I;
9	yn(I + no) = ys/n*I; yn(no +n+i) = ys; yn(3*n+1+i) = ys-ys/n*I;
10	end
11	for I = 1: $nf;xc(i) = (xn(i) + xn(i+1))/2; yc(i) = (yn(i) + yn(i+1))/2;end$
12	ts = [1 0 1;0 1 -1;-1 0 1;0 -1 -1];% Tangents of edges & their sign
13	for np = 1 : nf% Compute the form factor matrix for the nf elements
14	i0 = 0;
15	xc1=(.5-sqrt(3)/6)*(xn(np+1)-xn(np))+xn(np);
16	xc2=(.5+sqrt(3)/6)*(xn(np+1)-xn(np))+xn(np);
17	yc1=(.5-sqrt(3)/6)*(yn(np+1)-yn(np))+yn(np);
18	yc2=(.5+sqrt(3)/6)*(yn(np+1)-yn(np))+yn(np);
19	for I = 1 : nf % Loop on the nf visible segments
20	i0 = i0+1; i1 = i0+1;
21	<pre>nuc = ceil(np/n); % nuc is the patch side number</pre>
22	$r0(i) = sqrt((xn(i0)-xc1)^2+(yn(i0)-yc1)^2);$
23	$r1(i) = sqrt((xn(i1)-xc1)^2+(yn(i1)-yc1)^2);$
24	f1 = $(((xn(i0)-xc1)/r0(i)-(xn(i1)-xc1)/r1(i))*$
25	ts(nuc,1)-((yn(i0)-yc1)/r0(i)-(yn(i1)-yc1)/r1(i))*
26	ts(nuc,2))*ts(nuc,3)/2;
27	$r0(i) = sqrt((xn(i0)-xc2)^{2}+(yn(i0)-yc2)^{2});$
28	$r1(i) = sgrt((xn(i1)-xc2)^{2}+(yn(i1)-yc2)^{2});$

29	f2	= $((xn(i0)-xc2)/r0(i)-(xn(i1)-xc2)/r1(i))*$
30		ts(nuc,1)-((yn(i0)-yc2)/r0(i)-(yn(i1)-yc2)/r1(i))*
31		ts(nuc,2))*ts(nuc,3)/2;
32	end	
33	for I	<pre>= 1:n;f((nuc-1)*n+i) = 0.;end % View factor of anal. face</pre>
34	F(:,np)	= f; % In geo vfsold.m we have: F(np,:) = f;
35	end	
36	end	
37		

Table 29:  $Matlab^{\odot}$  function geo\_vfr.m – view factor matrix – 2 Gauss points

	_		4.3.3.3.1	(-) 11			(	
	$F = geo_{-}$	<b>vfr</b> (1,[1	1]);disp	(F);disp	(sum(F))	;disp(su	um(F,2))	
0 0.2935 0.4130 0.2935	0.2935 0 0.2935 0.4130	0.4130 0.2935 0 0.2935	0.2935 0.4130 0.2935 0	1.0000 1.00 1.00 1.00 1.00	1.0000 00 00 00 00	1.0000	1.0000	1.0000
Lel= [1 lon(k) = for j=1:	1 1 1];1 Le1(j)/n ns; Rec:	Recip on = zero h; end; en i(I,j) =	<pre>procity p ps(1,n*4); d; ns=siz lon(i)*F()</pre>	<pre>property k=0; fo e(lon,2) I,j)-lon</pre>	y test r j = 1 ;Reci=ze .(j)*F(I,	(84) 1:4;for : eros(ns,r .j); end;	I = 1:n; ns);for I end;disp	k = k+1; i = 1:ns; o(Reci);
0 0 0 0	0 0 0 0 0 0 0 0	0 0 0 0						

Table 30: Square cavity – 4 segments – two Gauss points per segment

The difference between these functions is shown as a comment at the end of *line 35* of *Table 29*. Using numerical integration to compute the view factor of the opposite of a square side, we obtain the value of 0.4472 with 1 integration point (*Table 28*), and the value of 0.4130 with 2 Gauss points (*Table 30*). The exact value of 0.4142 is obtained with 3 integration points.

With two elements per cavity side (*Table 31*), the *reciprocity property* (85) is not perfectly satisfied, but *closure properties* are satisfied both for lines and columns. When the number of Gauss points is increasing, this lack of precision is decreasing.

F = geo	_vfsold	(2,[1 1]	); disp	(F); disp	)(sum(F))	; disp(s	sum(F,2))	
0	0	0.0840	0.1160	0.1787	0.2425	0.1023	0.2764	
0	0	0.2764	0.1023	0.2425	0.1787	0.1160	0.0840	
0.1023	0.2764	0	0	0.0840	0.1160	0.1787	0.2425	
0.1160	0.0840	0	0	0.2764	0.1023	0.2425	0.1787	
0.1787	0.2425	0.1023	0.2764	0	0	0.0840	0.1160	
0.2425	0.1787	0.1160	0.0840	0	0	0.2764	0.1023	
0.0840	0.1160	0.1787	0.2425	0.1023	0.2764	0	0	
0.2764	0.1023	0.2425	0.1787	0.1160	0.0840	0	0	
1 1	1	1 1	1 1	1				
1								
1								
1								
1								
1								
1								
1								
1								

*Table 31: View factor matrix F in a square cavity – 8 segments* 

			F =	geo_	vfsol	. <b>d</b> (2	,[1 1]),	; F-F'		
	0	0	-0.	0184		0	0	0	0.0184	0
	0	0		0	0.01	84	0	0	0	-0.0184
0.018	4	0		0		0	-0.0184	0	0	0
	0	-0.0184		0		0	0	0.0184	0	0
	0	0	Ο.	0184		0	0	0	-0.0184	0
	0	0		0	-0.01	84	0	0	0	0.0184
-0.018	4	0		0		0	0.0184	0	0	0
	0	0.0184		0		0	0	-0.0184	0	0
				rou	nd((F·	-F <b>'</b> )	/0.0184	)		
0	0	-1	0	0	0	1	0			
0	0	0	1	0	0	0	-1			
1	0	0	0	-1	0	0	0			
0	-1	0	0	0	1	0	0			
0	0	1	0	0	0	-1	0			
0	0	0	-1	0	0	0	1			
-1	0	0	0	1	0	0	0			
0	1	0	0	0	-1	0	0			

Table 32: Reciprocity check in a square cavity for result of Table 31

<pre>F = geo_vfsold(1,[1 4]);disp(sum(F,1));disp(sum(F,2));</pre>
lon = [1 4 1 4];disp([0 lon; (lon)' F]);
4.0000 0.0528 0 0.0528 <b>0.8944</b>
1.0000 <b>0.1240</b> 0.4380 0 0.4380
4.0000 0.0528 <b>0.8944</b> 0.0528 0
Closure property:
disp(sum(F)); columns $0.2236 = 1.7764 = 0.2236 = 1.7764$ disp(sum(F,2)'); lines $1 = 1 = 1$
<pre>ns=size(lon,2);Reci=zeros(ns,ns);for i=1:ns;for j=1: ns;</pre>
<pre>Reci(I,j)=lon(i)*F(I,j)-lon(j)*F(j,i); end;end;disp(Reci)</pre>
0 0.2268 0 0.2268
-0.2268 0 -0.2268 0
disp(round(Reci/0.2268))
0 1 0 1
-1 0 $-1$ 0
<pre>F = geo_vfs(1,[1 4],4);disp(F);disp(sum(F,1));disp(sum(F,2))</pre>
0 0.0528 0.1240 0.0528
0.4380 $0.0528$ $0.0528$
0.4380 <b>0.8944</b> 0.4380 0
1 1 1 1
0.2296
1.7704
0.2296
1.7/04
ns=Size(ion, 2), Reci=zeros(is, is), ior i=1.is, ior j=1. ns:Reci(I.i)=lon(i)*F(I.i)=lon(i)*F(i.i): end:end:disp(Reci)
0 -1.6991 0 -1.6991
1.6991 0 1.6991 0
0 -1.6991 0 -1.6991
disp(round(Poci/1 6991))
0 -1 0 -1
<b>1</b> 0 <b>1</b> 0

Table 33: View factor matrix F in a rectangular cavity – 4 segments mesh

F	= geo_vf	fr(1,[1 4	4]);disp(F), Lel=[1	;disp(sum(F));disp(sum(F,2)); 4 1 4];
0 0.4385 <b>0.1231</b> 0.4385	0.1003 0 0.1003 <b>0.7994</b>	0.1231 0.4385 0 0.4385	0.1003 0.7994 0.1003 0	1 1 1 1 0.3237 1.6763 0.3237 1.6763
<pre>lon = zero Lel(j)/n; ns;Reci(I</pre>	os(1,n*4) end; end ,j) = lor	);k=0;fo: d; ns=si: n(i)*F(I	r j = 1:4; ze(lon,2);R ,j)-lon(j)*	<pre>for I = 1:n;k = k+1; lon(k) = Reci=zeros(ns,ns);for i=1:ns;for j=1: *F(j,i); end;end;disp(Reci);disp(lon)</pre>
				disp(round(Reci/1.6535))
0 1.6535 0 1.6535	-1.6535 0 -1.6535 0	0 1.6535 0 1.6535	-1.6535 0 -1.6535 0	$ \begin{array}{cccccccccccccccccccccccccccccccccccc$

 Table 34: Rectangular cavity – 4 segments mesh, 2 Gauss points

		F	= geo_vf	sold (2)	,[1 4]);			
	;lon=[	.5 .5 2 2	2.5.5	2 2];dis	p([0 lon	;(lon)'	F]);	
	disp(sum	(F)); di:	sp(sum(F	,2));dis	p(sum([s	um(F,2)'	])/8);	
0	0.5000	0.5000	2.0000	2.0000	0.5000	0.5000	2.0000	2.0000
0.5000	0	0	0.3244	0.0834	0.0610	0.0624	0.0308	0.4380
0.5000	0	0	0.4380	0.0308	0.0624	0.0610	0.0834	0.3244
2.0000	0.0937	0.0528	0	0	0.0068	0.0189	0.1208	0.7071
2.0000	0.0189	0.0068	0	0	0.0528	0.0937	0.7071	0.1208
0.5000	0.0610	0.0624	0.0308	0.4380	0	0	0.3244	0.0834
0.5000	0.0624	0.0610	0.0834	0.3244	0	0	0.4380	0.0308
2.0000	0.0068	0.0189	0.1208	0.7071	0.0937	0.0528	0	0
2.0000	0.0528	0.0937	0.7071	0.1208	0.0189	0.0068	0	0
Closure prop disp(sum(F) disp(sum(F,	<pre>perty:     ();columns     (2)');lines</pre>	0.2954 0.2	954 1.7046	1.7046	0.2954	0.2954	1.7046	1.7046
1								
1								
1								
1								
1								
1								
1								

Those 55, Then factor man with a rectangular currer o beginerus mes.	Table 35: View	factor matrix F	$^{r}$ in a rectangular $a$	cavity – 8 se	egments mesl
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	E	<b>a a a a a b a b b b b b b b b b b</b>	F1 A1 A	\.lon-[	E E O O	<b>E E O</b>	21.		_
	r – g	eo_vis(2	, [1 4],4	);101-[.	5.5ZZ	.5.52	;		
	disp([0	lon; (lon	)' E']) ;	disp(su	m(F)); d	ısp(sum(	E,2)');		
		d	<pre>isp(sum(</pre>	[sum(F,2	)'])/8);				
0	0.5000	0.5000	2.0000	2.0000	0.5000	0.5000	2.0000	2.0000	
0.5000	0	0	0.0937	0.0189	0.0610	0.0624	0.0068	0.0528	
0.5000	0	0	0.0528	0.0068	0.0624	0.0610	0.0189	0.0937	
2.0000	0.3244	0.4380	0	0	0.0308	0.0834	0.1208	0.7071	
2.0000	0.0834	0.0308	0	0	0.4380	0.3244	0.7071	0.1208	
0.5000	0.0610	0.0624	0.0068	0.0528	0	0	0.0937	0.0189	
0.5000	0.0624	0.0610	0.0189	0.0937	0	0	0.0528	0.0068	
2.0000	0.0308	0.0834	0.1208	0.7071	0.3244	0.4380	0	0	
2.0000	0.4380	0.3244	0.7071	0.1208	0.0834	0.0308	0	0	
Closure prope	erty:								
disp(sum(F)	lines 1	1 1 1	1 1 1 1	L					
disp(sum(F,2	2)) columns	5							
0.2954									
0.2954									
1.7046									
1.7046									
0.2954									
0.2954									
1.7046									
1.7046									

ns=size(l ns;Reci(I	on,2);Re ,j)=lon(	ci=zeros i)*F(I,j	(ns,ns); )-lon(j)	for i=1:: *F(I,j);	ns;for j end;end	=1: ;disp(Re	ci)	
0	0	-0.1405	-0.0283	0	0	-0.0102	-0.0792	
0	0	-0.0792	-0.0102	0	0	-0.0283	-0.1405	
0.4867	0.6570	0	0	0.0462	0.1251	0	0	
0.1251	0.0462	0	0	0.6570	0.4867	0	0	
0	0	-0.0102	-0.0792	0	0	-0.1405	-0.0283	
0	0	-0.0283	-0.1405	0	0	-0.0792	-0.0102	
0.0462	0.1251	0	0	0.4867	0.6570	0	0	
0.6570	0.4867	0	0	0.1251	0.0462	0	0	
disp(sum(	<pre>disp(sum(Reci));disp(sum(Reci,2)')</pre>							
1.3150	1.3150	-0.2582	-0.2582	1.3150	1.3150	-0.2582	-0.2582	
-0.2582	-0.2582	1.3150	1.3150	-0.2582	-0.2582	1.3150	1.3150	

*Table 36: View factor matrix F in a rectangular cavity – 8 segments mesh* 

F =	geo_vfr(	2,[1 4])	;disp(F);	disp(su	m(F)); di	sp(sum(F,2)	);
			Lel=[1	4 1 4];			
0 0.3255 0.0825 0.0608 0.0623 0.0304 0.4384	0 0.4384 0.0304 0.0623 0.0608 0.0825 0.3255	0.0912 (0 0.1003 (0 0 0 0.0076 (0 0.0206 (0 0.1634 (0 0.6169 (0	0.0206 0 0.0076 0 0 0 0.1003 0.0912 0.6169 0 0.1634 0	.0608 0. .0623 0. .0304 0. .4384 0. 0 .3255 0. .0825 0.	0623 0.0 0608 0.0 0825 0.1 3255 0.6 0 0.0 0 0.1 4384 0304	076 0.1003 206 0.0912 634 0.6169 169 0.1634 912 0.0206 003 0.0076 0 0 0	
Closure property: disp(sum(F) li disp(sum(F,2)) 0.3428 0.3428 1.6572 0.3428 0.3428 0.3428 1.6572 1.6572 1.6572	nes 1 1 columns	1 1 1	1 1 1				
<pre>lon = zeros Lel(j)/n; er ns;Reci(I,j)</pre>	(1,n*4); nd; end; = lon()	k=0;for j ns=size( i)*F(I,j)	j = 1:4; (lon,2);R -lon(j)*	for I = 1 eci=zeros F(I,j); @	l:n;k = k+ s(ns,ns);f end;end;di	+1; lon(k) for i=1:ns; lsp(Reci)	= for j=1:
0 0.4882 0.1238 0 0 0.0456 0.6577	0 0.6577 0.0456 0 0.1238 0.4882	-0.1369 -0.1504 0 -0.0114 -0.0309 0	-0.0309 -0.0114 0 -0.1504 -0.1369 0	0.0456 0.657 0.4882 0.4882	$\begin{array}{cccccccccccccccccccccccccccccccccccc$	$\begin{array}{cccc} & -0.0114 \\ -0.0309 \\ & & 0 \\ 2 & & 0 \\ 0 & -0.1369 \\ 0 & -0.1504 \\ 7 & & 0 \\ 5 & & 0 \end{array}$	-0.1504 -0.1369 0 -0.0309 -0.0114 0

Table 37: Rectangular cavity – 8 segments – 2 Gauss points

# $\rightarrow$ b) Street section

For the street section analyses, we use the parameters Gi = 14 when radiation is present and Gi = 15 for the linear transient analyses. (Matlab<sup>©</sup> function *cad gin.m, Table 71*).

[(1:npv)' xyz_0	cao]	$ \begin{array}{cccccccccccccccccccccccccccccccccccc$	8 8 0 1 0 1 8 8	Labels & normals	s of the 3 patche(s) 8 <sup>1</sup> 7
[(1:np)' car_ca	ao] 1 2 3	2 1 4 3 6 5	3 4 5 6 7 8		
[(1:nbo)' bor]	1       2         2       1         3       3         4       4         5       3         6       5         7       6         8       5         9       7         10       8	$ \begin{array}{cccccccccccccccccccccccccccccccccccc$	$\begin{array}{cccc} 0 & 9 \\ 0 & 11 \\ 2 & 13 \\ 0 & 15 \\ 0 & 17 \\ 3 & 19 \\ 0 & 21 \\ 0 & 23 \\ 0 & 25 \\ 0 & 27 \end{array}$	10 12 14 16 18 20 22 24 26 28 3	2 6 5
[(1:np)' pbo]	1 2 3	1 2 3 5 6 8	3 4 6 7 9 10		1

Figure 56: Data – Gi = 14, Gi = 15: Street section, aspect ratio dx/dy = 3/7

After the cavity, we analyze how radiative exchanges behave in an open space like a street section. We define a domain with 8 vertices, 3 patches and 10 interfaces. This domain has an area of  $20 m^2$  and a perimeter of 42 m.

The matrix of *CAD* vertices is displayed with the Matlab<sup>©</sup> instruction:  $[(1: npv)' xyz_cao]$ . The first column of the four tables contains the numbering (in blue) of their lines. The matrix of *CAD* patches is displayed with the Matlab<sup>©</sup> instruction: [(1: np)' car cao].

These matrices and the variable *cs* are the input data visible in *line 3* of the procedure *Fiammetta.m.* After running this procedure, the matrix of interfaces *bor* is displayed with the Matlab<sup>©</sup> instruction: [(1: nbo)' bor]. In this example, we inserted two nodes per interface (*line 10*). The domain is represented at the right of *Figure 56* with node (black) and patch (red) numbering. On the boundary of the domain, the outward normal vectors (blue) are also represented.

Radiative heat transfers need the evaluation of the view factors of the boundary elements of the model. For a street canyon or a rectangle open on the top side, they are calculated with the function *geo\_stf.m* of *Table 38*.

	Matlab <sup>©</sup> function <i>geo_stf.m</i> – view factor matrix of a street section
1	<pre>function[F] = geo_stf(n,Lel)</pre>
2	xs = Lel(1); ys = Lel(2); % Lel = vector of the side lengths
3	no $= n-1$ ; n is the number of el. on a side, no the number of nodes
4	n3 = n*3;% * % View factors matrix: 3 sides and the sky
5	F = zeros(n3,n3); r0=zeros(1,n3); r1=zeros(1,n3); f = zeros(1,n3);
6	xc = zeros(1,n3) ;yc = xc; Le = yc; % Edges definition
7	<pre>xn = zeros(1,n3+1);yn = xn; % vertices definition</pre>
8	<pre>xn(1:no) = 0; k = 0; for I = n+2:2*n+1; k=k+1; xn(i)=xs/(n)*k;end;</pre>
9	<pre>xn(2*n+2:3*n+1) = xs;% disp(['xn : ',num2str(xn)])</pre>
10	<pre>for i=1:n;yn(I )= ys-(i-1)*ys/(n);end;yn(n+2:2*n )=0;k=-1;</pre>
11	<pre>for i=2*n+1:3*n+1;k=k+1;yn(i)=k*ys/(n);end;</pre>
12	for I = 1: n3;Le(i) = sqrt((xn(i+1)-xn(i))^2+(yn(i+1)-yn(i))^2);end
13	for I = 1: $n_{3,xc(i)} = (xn(i)+xn(i+1))/2;yc(i)=(yn(i)+yn(i+1))/2;end$
14	ts = [0 -1 -1;1 0 1;0 1 -1;]; % Tangents of edges & their sign
15	for np = 1 : n3 % Form factor matrix for the n3 elements
16	i0 = 0; i1 = 1;
17	for I = 1 : n3 % Loop on the n4 points
18	i0 = i0+1;
19	i1 = i1+1;
20	<pre>nuc = ceil(np/n);</pre>
21	$r0(i) = sqrt((xn(i0) - xc(np))^{2} + (yn(i0) - yc(np))^{2});$
22	$r1(i) = sqrt((xn(i1)-xc(np))^{2}+(yn(i1)-yc(np))^{2});$



*Table 38: Matlab<sup>©</sup> function geo\_stf.m – view factor matrix – street section* 

A simple instruction is used to display the view factor matrices both for the rectangular cavity (*Figure 55*) using the Matlab<sup>®</sup> function *geo\_vfc.m* of *Table 27* and the street section (*Figure 56*) using the Matlab<sup>®</sup> function *geo\_stf.m* of *Table 38*. The arguments of both functions are the number *n* of elements per side and the vector *Lel* containing the lengths of the horizontal and the vertical sides. The *geo\_vfc.m* function needs one more argument defining the number of sides of the cavity.

F	= geo_stf	(2, [3 7]);	<pre>disp(F);</pre>	disp(sum(	F,1)); disp	(sum(F,2))	
0	0	0.0192	0.0466	0.1822	0.5039		
0	0	0.1204	0.1277	0.5039	0.1822		
0.0515	0.3952	0	0	0.2296	0.1174		
0.1174	0.2296	0	0	0.3952	0.0515		
0.1822	0.5039	0.1277	0.1204	0	0		
0.5039	0.1822	0.0466	0.0192	0	0		
0.8549	1.3109	0.3139	0.3139	1.3109	0.8549		
0.7519							
0.9341							
0.7937							
0.7937							
0.9341							
0.7519							
F =	geo_vfc (	2, [3 7],4)	; disp(F)	; disp(sum	(F,1)); dis	p(sum(F,2))	
0	0	0.1277	0.0466	0.0997	0.1065	0.0192	0.1204
0	0	0.1204	0.0192	0.1065	0.0997	0.0466	0.1277
0.2296	0.3952	0	0	0.0515	0.1174	0.1822	0.5039
0.1174	0.0515	0	0	0.3952	0.2296	0.5039	0.1822
0.0997	0.1065	0.0192	0.1204	0	0	0.1277	0.0466
0.1065	0.0997	0.0466	0.1277	0	0	0.1204	0.0192
0.0515	0.1174	0.1822	0.5039	0.2296	0.3952	0	0
0.3952	0.2296	0.5039	0.1822	0.1174	0.0515	0	0
1 1	1 1	. 1	1 1	1			
0.5202							
0.5202							
1.4798							
1.4798							
0.5202							
0.5202							
1.4798							
1.4798							

Table 39: View factor matrices for street section (top) and rectangular cavity (bottom)

F = geo_stf	(2, [3	7]); disp	([F 1-sum(F	<b>,</b> 2)]);disp	(sum ([F	1-sum(F,2)],2))
0	0	0.0192	0.0466	0.1822	0.5039	0.2481
0	0	0.1204	0.1277	0.5039	0.1822	0.0659
0.0515	0.3952	0	0	0.2296	0.1174	0.2063
0.1174	0.2296	0	0	0.3952	0.0515	0.2063
0.1822	0.5039	0.1277	0.1204	0	0	0.0659
0.5039	0.1822	0.0466	0.0192	0	0	0.2481
1						
1						
1						
1						
1						
1						

Table 40: Street section (6 segments): view factor matrix and sky view factor vector

F =	geo_stf	(3, [3 7]	); disp	([F 1-su	m(F,2)]);	disp (sur	n ([F 1-:	sum(F,2)]	,2))
0	0	0	0.0072	0.0198	0.0283	0.0650	0.1984	0.3624	0.3188
0	0	0	0.0192	0.0466	0.0545	0.1984	0.3624	0.1984	0.1204
0	0	0	0.1204	0.1277	0.0707	0.3624	0.1984	0.0650	0.0554
0.0176	0.0515	0.3952	0	0	0	0.1345	0.1294	0.0679	0.2038
0.0482	0.1174	0.2296	0	0	0	0.2296	0.1174	0.0482	0.2095
0.0679	0.1294	0.1345	0	0	0	0.3952	0.0515	0.0176	0.2038
0.0650	0.1984	0.3624	0.0707	0.1277	0.1204	0	0	0	0.0554
0.1984	0.3624	0.1984	0.0545	0.0466	0.0192	0	0	0	0.1204
0.3624	0.1984	0.0650	0.0283	0.0198	0.0072	0	0	0	0.3188
1									
1									
1									
1									
1									
1									
1									
1									
1									
1									

Table 41: Street section (9 segments): view factor matrix and sky view factor vector

# $\rightarrow$ c) L shape configurations

We now examine two situations containing both vertical and horizontal connected edges looking at sky, ground and the domain itself. In the first configuration (*Figure 57*), the vertical wall is always seeing half the sky vault while the horizontal one is seeing more than half the sky vault.

In the second configuration (*Figure 58*), the vertical wall is always seeing half the ground, while the horizontal one is seeing more than half the ground.



# $\rightarrow$ d) Thermal bridge

In this section we a	define the simple s	situation of a thermal	bridge	(Figure :	<u>59</u> )
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For the th	nerma	l brid	ge ana	alyses.	, we us	se the pa	arameters $Gi = ??$ when radiation is present
and $Gi =$	16 for	the li	inear t	ransie	ent ana	lyses. (I	Matlab <sup>©</sup> function <i>cad_gin.m</i> , <i>Table 71</i> ).
[(1:npv)'	xyz_ car_c	cao] ao]	1 1 2 3 3 5	1 2 3 4 5 6 7 8 9 10 11 12 3 5 7	-2 -2 4 4 8 8 14 14 4 8 4 8 4 6 8 5	5 6 5 6 6 8 6 8 6 8 6 8 0 0 12 12 12 12 12 2 4 6	Labels & normals of the 5 patche(s) 11 12 5 6 3 7 7
[(1:nbo)' 1 2 3 4 5 6 7 8 9 10 11 12 13 14 15 16	bor] 1 3 4 2 3 5 6 5 7 8 9 10 3 6 12 11	3 4 2 1 5 6 4 7 8 6 10 5 9 12 11 4	4 9 5 4 1 1 1 2 2 2 3 3 4 4 5 5 5	10 6 0 2 0 4 3 5 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0	5 12 13 15 17 19 21 23 25 27 29 31 33 35 37 39 41 43	3 11 14 16 18 20 22 24 26 28 30 32 34 36 38 40 42 44	[(1:np)' pbo] 1 1 2 3 4 2 5 6 7 2 3 8 9 10 6 4 11 12 5 13 5 7 14 15 16

*Figure 59: Data – Gi = 16: Thermal bridge* 

	Matlab <sup>©</sup>	<sup>b</sup> function <i>geo_baf.m</i> – view factor matrix of a wall with balcony
1	functio	n[F] = geo baf(nci,xyz cao) % Balcony view factor matrix % 20210929
2	n3	= nci*5+2;% Size of view factors matrix including sky and ground
3	F	= zeros(n3,n3); f=zeros(n3,1);
4	XC	= zeros(n3,1) ;yc = xc;Le = yc; % Edges definition
5	xn	= zeros(n3,1);yn = xn; % vertices definition
6	t	= 0:1/nci:1;b = zeros(1,n3-2);
7	for i =	1:nci

xn(i,1) = xyz\_cao(11,1)\*(1-t(i))+xyz\_cao(4,1)\*t(i); 8 9 xn(i+nci,1) = xyz cao(4,1)\*(1-t(i))+xyz cao(2,1)\*t(i); 10 xn(i+2\*nci,1) = xyz cao(2,1)\*(1-t(i))+xyz cao(1,1)\*t(i);  $\begin{array}{l} xn(i+2 \ noi), i) &= xyz\_cao(1,1)*(1-t(i))+xyz\_cao(3,1)*t(i); \\ xn(i+4*nci,1) &= xyz\_cao(3,1)*(1-t(i))+xyz\_cao(9,1)*t(i); \\ \end{array}$ 11 12 = xyz\_cao(9,1); 13 end; xn (n3-2, 1) 14 xn(n3-1 ,1) = xyz cao(9,1); 15 for i=1:nci = xyz\_cao(11,2)\*(1-t(i))+xyz\_cao(4,2)\*t(i); = xyz\_cao(4,2) \*(1-t(i))+xyz\_cao(2,2)\*t(i); 16 vn(i.1) 17 vn(i+nci,1) yn(i+2\*nci,1) = xyz cao(2,2) \* (1-t(i)) + xyz cao(1,2)\*t(i);18 19 yn(i+3\*nci,1) = xyz cao(1,2) \*(1-t(i))+xyz cao(3,2)\*t(i); yn(i+4\*nci,1) = xyz cao(3,2) \*(1-t(i))+xyz cao(9,2)\*t(i); 20 = xyz\_cao(3,2) \*(1-t(i))+xyz\_cao(9,2)\*t(i); end; yn (n3-2,1) 21 = xyz\_cao(9,2); 22 yn(n3-1,1) for i 23 = 1:  $n3-2; Le(\overline{i}) = sqrt((xn(i+1)-xn(i))^2+(yn(i+1)-yn(i))^2); end$ 24 for i = 1:  $n_{3-2}$ ; xc(i) = (xn(i)+xn(i+1))/2; yc(i)=(yn(i)+yn(i+1))/2; end tsb = [0 -1 0 1 0;-1 0 -1 0 -1];k=0;for i=1:5;for j=1:nci;k=k+1;... 25 26 b(k)=i;end;end 27 = tsb(1,b); ts(2,:) = tsb(2,b);ts(1,:) F(1:3\*nci ,n3)=.5;F(2\*nci+1:5\*nci,n3-1)=.5; 28 29 = 1 : nci % Form fact. matrix for nci (upper L) vert. elem. for np 30 = nci+1 : 2\*nci for i % Loop on the nci points 31  $r0 = sqrt((xn(i) -xc(np))^{2}+(yn(i) -yc(np))^{2});$  $r1 = sqrt((xn(i+1)-xc(np))^{2}+(yn(i+1)-yc(np))^{2});$ 32 33 f(i) = -(((xn(i)-xc(np))/r0 - (xn(i+1)-xc(np))/r1)) \*ts(1,np)-...((yn(i)-yc(np))/r0 -(yn(i+1)-yc(np))/r1 ) \*ts(2,np))/2; 34 35 end 36 f(n3-1) = -(((xn(i)-xc(np))/r1-1) \*ts(1,np)-...((yn(i)-yc(np))/r1 ) \*ts(2,np))/2; f(n3) 37 = 0.5;38 = f'; F(np,:) 39 end 40 f  $= \operatorname{zeros}(n3, 1);$ 41 for np = nci+1:2\*nci % Form fact. for nci (upper L) horiz. elem. 42 for i = 1 : % Loop on the nci points nci  $r0 = sqrt((xn(i) -xc(np))^2+(yn(i) -yc(np))^2);$ 43  $r1 = sqrt((xn(i+1)-xc(np))^2+(yn(i+1)-yc(np))^2);$ 44 45 f(i) = (((xn(i)-xc(np))/r0 -(xn(i+1)-xc(np))/r1 )\*ts(1,np)-. ((yn(i)-yc(np))/r0 -(yn(i+1)-yc(np))/r1 ) \*ts(2,np))/2; 46 47 end f(n3-1) = 0.; f(n3) = 1-sum(f(1:n3-2));48 49 F(np,:) = f'; 50 end 51 f = zeros(n3.1); 52 for np = 3\*nci+1:4\*nci % Form fact. for nci (lower L) horiz. elem. 53 for i = 4\*nci+1 :5\*nci % Loop on the nci points  $r0 = sqrt((xn(i) -xc(np))^{2}+(yn(i) -yc(np))^{2});$ 54 55  $r1 = sqrt((xn(i+1)-xc(np))^{2}+(yn(i+1)-yc(np))^{2});$ f(i) = (((xn(i) - xc(np))/r0 - (xn(i+1) - xc(np))/r1) \*ts(1, np) - ...56 57 ((yn(i)-yc(np))/r0 -(yn(i+1)-yc(np))/r1 ) \*ts(2,np))/2; 58 end 59 f(n3-1) = 1-sum(f(1:n3-2)); f(n3) = 0.;60 F(np,:) = f'; 61 end 62 f = zeros(n3,1);63 for np = 4\*nci+1:5\*nci % Form fact. for nci (lower L) vert. elem. = 3\*nci+1:4\*nci 64 for i % Loop on the nci points 65  $r0 = sqrt((xn(i) -xc(np))^2+(yn(i) -yc(np))^2);$  $r1 = sqrt((xn(i+1)-xc(np))^{2}+(yn(i+1)-yc(np))^{2});$ 66 = -(((xn(i)-xc(np))/r0 -(xn(i+1)-xc(np))/r1)\*ts(1,np)-... 67 f(i) 68 ((yn(i)-yc(np))/r0 -(yn(i+1)-yc(np))/r1 ) \*ts(2,np))/2; 69 end 70 f(n3-1) = .5 ; f(n3) = 1-sum(f(1:n3-1)); F(np,:) = f'; end 71 72 end

Table 42: Matlab<sup> $\circ$ </sup> function geo baf.m – view factor matrix – wall with balcony

View factor matrix of the left side of a building involving a balcony

0	0	0.0840	0.1160	0	0	0	0	0	0	0.3000	0.5000
0	0	0.2764	0.1023	0	0	0	0	0	0	0.1213	0.5000
0.1023	0.2764	0	0	0	0	0	0	0	0	0	0.6213
0.1160	0.0840	0	0	0	0	0	0	0	0	0	0.8000
0	0	0	0	0	0	0	0	0	0	0.5000	0.5000
0	0	0	0	0	0	0	0	0	0	0.5000	0.5000
0	0	0	0	0	0	0	0	0.0629	0.1026	0.8345	0
0	0	0	0	0	0	0	0	0.2428	0.1136	0.6437	0
0	0	0	0	0	0	0.0903	0.3077	0	0	0.5000	0.1020
0	0	0	0	0	0	0.1254	0.1096	0	0	0.5000	0.2650
0	0	0	0	0	0	0	0	0	0	0	0
0	0	0	0	0	0	0	0	0	0	0	0
1											

*Table 43: View factor matrix F around a balcony – 10 segments + ground + sky* 

Because the third segment of the left side connecting nodes 2 and 1 does not see any other part of the model, its view factors are equal to zero (*Table 43 & Figure 60*), with the consequence that the corresponding lines and columns of matrix F are also equal to zero.



*Figure 60: Fsky in a street with balcony – 16 segments / patch side* 



Figure 61: Fgr in a street with balcony – 16 segments / patch side

### **5.3 Radiosity matrix**

#### $\rightarrow$ a) Rectangular cavity

According to [Goral *et al* 1984], the radiosity of a surface *j* is the total rate at which radiant energy leaves the surface in terms of energy per unit time and per unit area ( $Wm^{-2}$ ). The concept of radiosity is fundamental in radiative heat exchanges [Sillion & Puech 1994].

For a gray body of emissivity  $\varepsilon = 1 - \rho = 0.5$  and, thus, reflectivity  $\rho = 0.5$  (in the Matlab<sup>©</sup> procedures presented in this document,  $\rho$  is noted *re*), the radiosity matrix [*M*] is computed according to the sequence of Matlab<sup>©</sup> instructions in the heading of *Table 44*. Two extreme situations are identified:

• For a black body,  $\rho = 0$ , the emissivity is equal to 1 and, then, the radiosity matrix is equal to the identity matrix [*I*].

• For a mirror (adiabatic cavity),  $\rho = 1$ , the emissivity  $\varepsilon = 0$ . Therefore, the radiosity matrix is singular: the column and line sums are both equal to 0 as confirmed by the result shown in *Table 44*, by using the instructions *disp (sum(M)); disp(sum(M'))*.

R	Radiosity matrix [M] as a function of the view factor matrix [F]: re = 1; F = geo_vfs(2, [1 1], 4); M = eye(size(F, 1))-re*F									
1.0000	0	-0.0840	-0.1160	-0.1787	-0.2425	-0.1023	-0.2764			
0	1.0000	-0.2764	-0.1023	-0.2425	-0.1787	-0.1160	-0.0840			
-0.1023	-0.2764	1.0000	0	-0.0840	-0.1160	-0.1787	-0.2425			
-0.1160	-0.0840	0	1.0000	-0.2764	-0.1023	-0.2425	-0.1787			
-0.1787	-0.2425	-0.1023	-0.2764	1.0000	0	-0.0840	-0.1160			
-0.2425	-0.1787	-0.1160	-0.0840	0	1.0000	-0.2764	-0.1023			
-0.0840	-0.1160	-0.1787	-0.2425	-0.1023	-0.2764	1.0000	0			
-0.2764	-0.1023	-0.2425	-0.1787	-0.1160	-0.0840	0	1.0000			
disp (sum(M)	)									
1.0e-15 *	*									
-0.0555	-0.0833	-0.1110	-0.0555	0.0278	-0.0555	0	0			
Table 44	4: Radiosi	ty matrix o	of an adial	batic ( $\rho =$	1) square	cavity – 8	segments,			

#### $\rightarrow$ b) Street section

Interesting geometric properties of the street section example are the matrices related to the view factors. Using the Matlab<sup>©</sup> function *geo\_stf.m*, we can compute them directly. The first argument of this function is the number of segments on each side of the street section. The second argument is a vector containing the width and the height of the street. With one segment per side, we obtain a 3 x 3 matrix, with two segments per side, we obtain a 6 x 6 matrix (*Table 39, Table 40, Table 41*).

S	treet vie	F =	$F = geo_stf(1, [3 7])$					
0	0	0.0192	0.0466	0.1822	0.5039			
0	0	0.1204	0.1277	0.5039	0.1822	0	0.1204	0.7593
0.0515	0.3952	0	0	0.2296	0.1174	0.3952	0	0.3952
0.1174	0.2296	0	0	0.3952	0.0515	0.7593	0.1204	0
0.1822	0.5039	0.1277	0.1204	0	0			
0.5039	0.1822	0.0466	0.0192	0	0			

Table 45: Street section: view factor matrices

The radiosity matrix M is deduced from the view factor matrix (92). If the reflection coefficient  $\rho$  noted *re* in Matlab<sup>©</sup> instructions is equal to zero, it reduces to the identity matrix:

	Matlab <sup>©</sup> :	re =	0.;M	=	eye(siz	e(F,1))	- re*	F	
1	0	0	0	0	0				
0	1	0	0	0	0	1	0	0	
0	0	1	0	0	0	0	1	0	
0	0	0	1	0	0	0	0	1	
0	0	0	0	1	0				
0	0	0	0	0	1				
	Table 1	6. Stro	at cart	tion	radiosit	matricas	a = 0		

Table 46: Street section: ra	diosity matrices, $ ho = 0$
------------------------------	-----------------------------

	Matlab <sup>©</sup> : re=1;M = eye(size(F,1)) - re*F									
1.0000 0 -0.0515 -0.1174 -0.1822 -0.5039	0 1.0000 -0.3952 -0.2296 -0.5039 -0.1822	-0.0192 -0.1204 1.0000 0 -0.1277 -0.0466	-0.0466 -0.1277 0 1.0000 -0.1204 -0.0192	-0.1822 -0.5039 -0.2296 -0.3952 1.0000 0	-0.5039 -0.1822 -0.1174 -0.0515 0 1.0000	1.0000 -0.3952 -0.7593	-0.1204 1.0000 -0.1204	-0.7593 -0.3952 1.0000		

*Table 47: Street section: radiosity matrices,*  $\rho = 1$
The sky view factor uni-column matrix *Fsky* is obtained as the complement to unity of the view factor matrix *Fs* (*line 146* in *Fiammetta.m*):

Matlab®: Fsky = 1-sum(Fs,2)'
Fsky' = 0.2481 0.0659 0.2063 0.2063 0.0659 0.2481
For 1 segment per side, Fsky' = 0.1204 0.2095 0.1204
F = geo\_stf(200,[3 7])\*100;
Fsky = (100-eye(size(F,2))\*(sum(F'))')';
figure('Position',[100 100 1200 600]);hold on;grid on;bar(Fsky);
title(['Sky view factor SVF in a street section, max, min, mean in
%: ', num2str([max(SVF) min(SVF) mean(SVF)],2)],'fontsize', 20)
ylabel('%', 'fontsize', 20)

```
Table 48: Street section: sky view factor – uni-column matrix Fsky
```

Its distribution along the street walls (*Figure 62*) is computed with the Matlab<sup>©</sup> instruction of *Table 48*.



Figure 62: Sky View Factors in the street section – 200 radiative segments per side

As expected, the sky view factor is equal to 50 % on the top of the street walls. Going down, it is continuously decreasing until 4 %. On the road surface, it is more or less constant and close to 20 %.

When we have one segment per side, the view factor matrix of the street segments with respect to themselves yet computed in *Table 45* are shown with an extra column giving the sky view factor in *Table 49* (left side). The closure is satisfied for each line. This matrix is a sub-matrix of the transposed view factor matrix (right side) of a rectangle where lines 2, 3, 4 are conserved and column 1 shifted in the fourth position.

Fs=geo_stf	(1,[3 7])	;disp([Fs	1-sum(Fs,2)])	geo	vfs (1,	[3 7],4)	
0	0 1204	0 7502	0 1204	0	0.1204	0.2095	0.1204
0.3952	0.1204	0.3952	0.2095	0.3952	0	0.3952	0.7593
0.7593	0.1204	0	0.1204	0.2095 0.3952	0.1204 0.7593	0 0.3952	0.1204 0

*Table 49: Street section: full view factor matrix including segments and sky* 

# 6. Tutorial VI: Radiative heat exchanges

In the simple situation where the domain edge is either horizontal with only sky above it or vertical with facing, only sky and ground, the computation of the view factors is obvious. For the horizontal edge, the sky view factor is constant and equal to 1. For the vertical edge, the sky and ground view factors are both equal to 0.5. Heat exchanges between ground and sky are very important, but we do not matter them.

## 6.1 A simple convex domains

In this situation, we simply introduce elements on the radiative boundary (*Table 75*). On a pure horizontal edge, the sky view factor is equal to 1 and the ground view factor to zero. On a vertical wall, both are equal to 0.5.

To test this situation, we first propose a problem with virtual convective nodes on both vertical sides of the domain. We observe that the difference of temperature between both sides is equal to 4 K, while the differences of temperature between the walls and the virtual nodes is 8 K. We compare this solution shown in *Figure 63* to the problem including a radiative wall on the left and a convective one on the right.



Figure 63: Rectangle with two convective walls



Figure 64: Evolution of the outgoing heat plotted at line 91 of fem til.m (Table 62)

The convergence is obtained after about 100 iterations.



Figure 65: Domain with constant temperature gradient and heat flow

This solution is compared to the problem with convection on the right wall and radiation on the left one.





Figure 66: Rectangle with one radiative wall (left) and one convective wall (right)



Figure 67: Evolution of the outgoing heat, see line 125 in fem tir.m (Table 63)

Using the Matlab notations, we verify that the convective (*fem\_Kcv.m*, *Table 6*) and radiative (*fem\_Kcr.m*, *Table 75*) matrices are both multiple of:



Table 50: Convective and radiative matrices for boundary segments

The difference is a nil matrix.

# 6.2 Square cavity

The second test is the square cavity. The description of the cavity boundary is obtained by calculating the list *lcont* of the cavity boundary nodes ordered from bottom left vertex and following the border, cavity area left. This list is completed by the list of the four vertices *lv* ordered in the same way as the side nodes (*cad\_ban.m*, *Table 26*). This description is using the matrices *bor* and *pbo* computed in *cad\_mes.m* (*Table 15*).

The radiosity equations allow computing the radiative contribution of the conductivity matrix on the boundaries of the closed cavity. In *lines 5* and following of the function *fem\_caK.m, Table 51*, we observe the use of temperatures defined both on the element sides (variable *cam*) and on the nodes (variable *aaa*).

```
Matlab<sup>©</sup> function fem caK.m quadrilateral cavity
1
      function[Kr] = fem caK(tca,re,SBt,Mpr,it,lcont,lon)
                                         % Size of the global conductivity matrix
2
                    = size(tca,1);
      ndK
3
     Kr
                                            % Init. of cavity conductivity matrix
                    = zeros(ndK,ndK);
4
                    = size(lcont,1);
                                                         % Number of radiative nodes
     mc
                                          % Unicolumn of cavity nodal temperatures
5
     cat
                    = tca(lcont);
6
      jt=1000;
7
     if it ==jt;disp(['caK 1, Temperature n: ',num2str(cat')]);end
     cam(1:mc-1,1) = (cat(1:mc-1,1)+cat(2:mc,1))/2; % Cavity mid-segments temp.
cam(mc,1) = (cat(mc,1)+cat(1,1))/2;% Unicol cavity midside temperatures
8
9
10
     if it ==jt;disp(['caK 2, Temperature s: ',num2str(cam')]);end
11
     Ν
                 = size(lcont,1);% Number of elements along the radiating zone
12
     lel
                    = zeros(N,1);nci = N/4;% nci = numb. elements per cavity side
          i = 1 : nci % Compute lengths of N elements cavity border
lel(i) = lon(1); lel(i+nci) = lon(2);
13
     for i
14
          lel(i+2*nci) = lon(3); lel(i+3*nci) = lon(4);
15
16
      end
                    = eye(N).*lel*(1-re);% Diag. mat. seg. lengths, 4 equal sides
17
     Les
     if it ==jt;disp(['caK 3, Lengths x emi: ',num2str(lel(:,1)'*(1-re))]);end
aa = Mpr*SBt*Les*cam.^3; % Unicolumn of midside radiative terms
18
19
     aaa(2:mc,1) = (aa(1:mc-1,1)+aa(2:mc,1))/2; % Vector of nodal third powers
20
21
      aaa(1,1) = (aa(mc,1)+aa(1,1))/2;
                                                                  % of radiative terms
                   = 1:mc;Kr(lcont(i),lcont(i)) = aaa(i);end% Diag. cond. matrix
22
      for i
23
      if it ==jt;disp(['caK 4, Addit conduct: ',num2str(aaa'),' W/K']);end
24
      end
```

*Table 51: Matlab*<sup>©</sup> *function fem\_caK.m – radiative K<sub>r</sub> in a cavity* 

Input of *fem\_caK.m*:

- temperature vector *tca* computed in a previous iteration,
- reflection coefficient *re*,
- product *SBt* of the Stefan-Boltzmann by the thickness *th* of the radiative element,
- matrix  $Mpr = (I F) M^{-1}$  defined in equation (93) and computed from the view factor

matrix F and the radiosity matrix M,

- list *lcont* of the *DOF* on the border of the cavity (computed in *fem\_cca.m*),
- lengths *lon* of the elements of the radiating sides and

Output of *fem\_caK.m*:

• contribution *Kr* to the global matrix of the radiative terms.

	Matlab <sup>©</sup> fun	ction <i>fem_rsm.m</i> second member ina radiatve open section
1	function[Mn]	= fem rsm(tca,re,SBt,Mpr,it,Ms,lcont,lon,dK) % Open section
2	mcr	= size(lcont,1); % Number of radiative nodes
3	cat	= tca(lcont); % Nodal temperatures of radiative nodes
4	si	<pre>= mcr-1; Mn = zeros(dK,1);</pre>
5	cam(1:si)	= (cat(1:si,1)+cat(2:mcr,1))/2; % Mid-segments temperatures
6	aa	= Mpr(1:si,1:si)*eye(si).*lon*(1-re)*SBt*cam'.^4;% heat loads
7	aaa(1 <b>,</b> 1)	= aa(1)/2; aaa(mcr, 1) = aa(si)/2;
8	for i	= 1:si-1; aaa(i+1,1) = (aa(i,1)+aa(i+1,1))/2;end
9	Mss(1,1)	= Ms(1)/2; Mss(mcr,1) = Ms(si)/2;
10	for i	= 1:si-1; Mss(i+1,1) = (Ms(i,1)+Ms(i+1,1))/2;end
11	for i	= 1:mcr; Mn(lcont(i)) = aaa(i) + Mss(i);end
12	if it == 1	
13	<b>if</b> mcr < 10	<pre>;disp(['.rs 13, Iter. number: ',num2str(it')]) ;end</pre>
14	if mcr < 10	;disp(['.rs 14, cam (t-mid) : ',num2str(cam) ,' K']) ;end
15	if mcr < 10	<pre>;disp(['.rs 15, heat mid aa : ',num2str(aa') ,' W']) ;end</pre>
16	% if mcr < 1	10;disp(['.rs 16, Mr mid-edges: ',num2str(Mr') ,' W']) ;end
17	<b>if</b> mcr < 10	;disp(['.rs 17, aaa nodes : ',num2str(aaa'),' W']) ;end
18	<b>if</b> mcr < 10	;disp(['.rs 18, Mss nodes : ',num2str(Mss'),' W']) ;end
19	<b>if</b> mcr < 10	;disp(['.rs 19, Mn Tot nodes: ',num2str(Mn(lcont)'),' W']);end
20		<pre>disp(['.rs 20, sum(aaa) : ',num2str(sum(aaa) ),' W'])</pre>
21		disp(['.rs 21, sum(Mss) : ',num2str(sum(Mss) ),' W'])
22	end	-
23	end	

Table 52: Matlab<sup>©</sup> function fem rsm.m - second member in a radiative open section

Input of *fem rsm.m*:

- temperature vector *tca* computed in a previous iteration,
- reflection coefficient *re*,

- product *SBt* of the Stefan-Boltzmann by the thickness *th* of the radiative element,
- matrix  $Mpr = (I F) M^{-1}$  defined in equation (93) and computed from the view factor

matrix F and the radiosity matrix M,

- *it* is the iteration number
- *Ms* is the vector of sky loads of the edges
- list *lcont* of the *DOF* on the border of the cavity (computed in *fem\_cca.m*),
- lengths *lon* of the elements of the radiating sides.
- *dK* is the dimension of the system of equations

Output of *fem opK.m*:

• contribution *Mn* to the second member of heat equations.

a)

### Black body square cavity $\rho = 0$



Figure 68: Isotherms, radiation, 256 elements, 1 month,  $\rho = 0$ 



Figure 69: Element heat flow s after 30 days, left: black body,  $\rho = 0$ ; right: mirror,  $\rho = 1$ 

The generalized nodal heat flows along the boundary of the cavity are shown in *Figure 70*. The second member gsm of the conductivity system of equations where the radiative term have been removed are computed with the pure conductivity matrix [Kk]). The Figure 70 uses the classical Matlab<sup>©</sup> bar function on the reduced set of second member limited to the *DDL* listed in *lcont*. The diagram shows the values of the nodal heat loads expressed in W. They are ordered from the left bottom vertex along the boundary, cavity left. In this example, the number of elements per side is equal to 15 with a total of 64 nodes after adding the four vertices.



*Figure 70: Nodal heat loads on the cavity boundary (16 elem. per side)* 

#### Gray body square cavity



Figure 71: Isotherms, radiation, 800 elements, 1 month,  $\rho = 0.5$ 



Figure 72: T evolution, radiative exchanges, 256 elements, 1 month,  $\rho = 0.5$ 



Figure 73: Generalized loads Kr  $T = \varepsilon \sigma T^4$  (W), 40 nodes,  $\rho = 1$ , max: 510<sup>-3</sup>



Figure 74: Generalized loads  $Kr T = \varepsilon \sigma T^4$  (W), 100 cavity nodes





Figure 75: Isotherms, gray body, evolution after 60, 120, ..., 660 hours,  $\rho = 0.5$ 

# Comparison of gray cavities

In *Figure 76*, tests are carried out with reflection coefficients equal to 0, 0.5 and 1, over a period of 30 days. The differences are well marked on the isothermal diagrams and even better on the representations of heat fluxes. Presented in the form of graphical animations, these results should help the user to better understand these physical phenomena in their four dimensions (space and time).



c)



Figure 76: Isotherms and heat flows, black, gray body & mirror, 30 days

#### 6.3 Rectangular cavity

Before analyzing the radiative cavity, we give the result for an adiabatic cavity which is the limit situation of a cavity with perfect reflection coefficient,  $\rho = 1$  (or emissivity  $\varepsilon = 0$ )



Figure 77: Adiabatic rectangular cavity

To test the radiative exchanges between the boundary elements of the rectangular cavity, we first consider a boundary whose reflection coefficient is equal to 1 ( $\rho = I$ ), which means that the boundary is adiabatic. The results shown in *Figure 78* are the same as those of *Figure 77*.



*Figure 78: Cavity with adiabatic boundary*  $\varepsilon = 0$ ,  $\rho = 1$ 

For coarse, medium and fine meshes with respectively 16, 256 and 1024 elements, we obtain the temperature evolutions shown in *Figure 79* and *Figure 80*. The error present in the first steps of the integration process disappears with the refinement of the mesh. With 16 elements per patch side, the error is equal to 0.85 K at iteration 1 and 0.1 K at iteration 6.



*Figure 79: Temperature evolution,*  $\varepsilon = 0$ ,  $\rho = 1$ , 16 - 256 *elements* 



Figure 80: Temperature evolution,  $\varepsilon = 0$ ,  $\rho = 1$ , 1024 elements

Introducing radiative exchanges inside the cavity does not change the result if the reflection coefficient is equal to 1, which means that the borders of the cavity are adiabatic. However, when we introduce some emissivity on the cavity boundary:  $\rho = 0.9$ , the behavior of the solution is changing drastically. If we define a reflection coefficient less than one, we observe that the symmetry is not perfectly achieved. It is due to the lack of symmetry of the view factor matrix (see prints of lines L 151 to L 153). However, when the mesh is refined this lack of symmetry is decreasing.



Figure 81: Cavity,  $\varepsilon = .1$ ,  $\rho = 0.9$ 



Figure 82: Temperature evolution, 256 elements,  $\varepsilon = .1$ ,  $\rho = 0.9$ 

### 6.4 Street section

#### 6.4.1 Adiabatic walls, $\rho = 1$

In an adiabatic rectangular street section, with a finite element model of 225 *DOF*, the temperature is always greater than the initial one (> 280 K). The evolution of three typical temperatures is given in *Figure 83*. At the end of the integration process of 720 hours,  $T_{min} = 280 K$ ,  $T_{max} = 318 K$  and  $T_{mean} = 288 K$ .





Figure 84: Adiabatic Street section:  $k = 5 Wm^{-1}K^{-1}$ , heat load density = 100  $Wm^{-2}$ 

These results are obtained with adiabatic street boundaries. At least 8 segments per patch side are necessary to get acceptable results. The amplitudes of the oscillations of the maximum temperature are growing with the number of elements per patch side. In a short period of integration of 3 days and a fine mesh of 32 elements per patch side, the minimum temperature is always and everywhere greater than the initial one of 280 K. The amplitude of oscillations of the maximum temperature is approximatively equal to 7 K (*Figure 85*).



Figure 85: Temperature evolution, adiabatic walls, 3 days, 32 elements per side

Adiabatic wall	Perfectly reflective wall ( $\rho = 1$ )
Fiammetta 20211111	Fiammetta 20211111
Street section, Gi: 14	Street section, Gi: 14
L 4, Me, Di, Ne : 5 0 11	L 4, Me, Di, Ne : 5 0 11
L 5, Connr nvn : 0 0 0	L 5, Connr nvn : 0 0 0
L 6, rc, ra, cs : 0 0 0	L 6, rc, ra, cs : 1 0 2
L 7, CAD interf. : 10	L 7, CAD interf. : 10
L 9, N. pa., vert.: 3 8	L 9, N. pa., vert.: 3 8
L 11, num. nod side: 15	L 11, num. nod side: 15
L 13, num elem si de: 16	L 13, num elem side: 16
L 23, Domain area : 19 m2	L 23, Domain area : 19 m2
L 29, Num. elements: 768	L 29, Num. elements: 768
L 31, Num. of DOF : 833	L 31, Num. of DOF : 833
L 62, Domain perim.: 40 m	L 62, Domain perim.: 40 m
L 64, Thickness : 0.1 m	L 64, Thickness : 0.1 m

тсь	Conduction la .	$F_{\rm M}$ (mV)	тсь	Conduction la .	E M ( (mV)
ц 65,		5 W/ (IIIK)	ь 65,	Conduction K :	5 W/ (IIIK)
ь 66,	DT isotherms :	l K	ь 66,	DT isotherms :	
		_	ь 68,	St. Boltzmann:	5.6/04e-08 W/(m2K4)
L 72,	Fixed DOF :	0	L 72,	Fixed DOF :	0
N 27,	N. heat flows:	34	N 27,	N. heat flows:	34
			L 92,	Numb. r.nodes:	49
			L 101,	Anis. index :	0
			L 134,	Rad. edg. len:	7 3 7 m
			L 135,	Radiativ area:	1.7 m2
			L 136,	Refl. coeff. :	1
			L 145,	<pre>sum(sum(M)) :</pre>	8.7283
			L 148,	Sky temper. :	300 K
			L 152,	Sum sky loads:	0 W/m2
Lt 04,	Initial temp.:	280 K	Lt 04,	Initial temp.:	280 К
Lt 07,	Time step :	3600 sec	Lt 07,	Time step :	3600 sec
Lt 09,	Analyzed per.:	720 h, 30 days	Lt 09,	Analyzed per.:	720 h, 30 days
Lt 15,	Spec. capac. :	1000 J/(kg.K)	Lt 15,	Spec. capac. :	1000 J/(kg.K)
Lt 16,	Spec. mass :	2500 kg.m-3	Lt 16,	Spec. mass :	2500 kg.m-3
Lt 29,	<pre>sum(sum(C)) :</pre>	4.75 MJ/K	Lt 29,	<pre>sum(sum(C)) :</pre>	4.75 MJ/K
Lt 35,	Ampl inp heat:	100 W/m-2	Lt 35,	Ampl inp heat:	100 W/m-2
Lt 40,	Loaded area :	0.2 m2	Lt 40,	Loaded area :	0.2 m2
			Lt 48,	Radiat. area :	1.7 m2
			Lt 62,	sum(Ms) :	0 W
			Lt 64,	sum(Mn) :	0 W
Lt 79,	iteration :	360	Lt 79,	iteration :	360
Lt 79,	iteration :	720	Lt 79,	iteration :	720
Lt108,	Tmean - Tini :	3.18 К	Lt108,	Tmean - Tini :	3.18 К
Lt109,	Min obs. temp:	280 K	Lt109,	Min obs. temp:	280 К
Lt110,	Max obs. temp:	298 К	Lt110,	Max obs. temp:	298 К
Lt111,	Final temper.:	280 283 295	Lt111,	Final temper.:	280 283 295
Lt113,	Capac * Del T:	15.1 MJ	Lt113,	Capac * Del T:	15.1 MJ
Lt119,	Injected heat:	16.4 MJ	Lt119,	Injected heat:	16.4 MJ
Lt120,	Exact hd x 30:	16.5 MJ	Lt120,	Exact hd x 30:	16.5 MJ
L 258,	End Me=5. CPU:	9.82 sec.	L 258,	End Me=5. CPU:	10.4 sec.

Table 53: Street: comparison between adiabatic and perfectly reflective walls

In the example of *Table 53*, we observe that a perfectly reflective wall is identical to an adiabatic one. The last one needs less data and is easier to run because it does not use radiative exchanges parameters or methods.



# 6.4.2 Black body walls, $\rho = 0$



Table 54: Street: same temperature for sky and initial conditions,  $\rho = 0$ 

For black bodies ( $\rho = 0$ ), [M] = [I] and equation (99) reduces to:

$$Q = \left\{ \begin{bmatrix} I \end{bmatrix} - \begin{bmatrix} F \end{bmatrix} \right\} E(\tau) - \left\{ \begin{bmatrix} F_{sky} \end{bmatrix} E_{sky} + \begin{bmatrix} F_{gr} \end{bmatrix} E_{gr} \right\}$$
(105)

We assume that *Ms* is a uni-column matrix containing the products of mid-side temperature to power 4 by the Stefan-Boltzmann constant, the emissivity of the edge and its area. Expressing also the sky and ground exitances as a function of the sky and/or ground temperatures it becomes:

$$Q = \left\{ [I] - [F] \right\} Ms - \left\{ [F_{sky}] \sigma T_{sky}^4 + [F_{gr}] \sigma T_{gr}^4 \right\}$$
(106)

If the temperature field is constant:

$$\tau_i^{mid-side} = T_{sky} = T_{gr} \tag{107}$$

```
M = (I-re*Fs); if re == 0; M=I; end
Fsky = 1-sum(Fs,2) ';
(sum([Fs Fsky'],2))'=1 1 1 1 1 1
Ms = SB*Lel(2)*th*(re*(I-Fs)*M^(-1)-I)*Fsky'*Tsky^4
Mpr = (I-Fs)*M^(-1);
aa = Mpr(1:si,1:si)*eye(si).*lon*(1-re)*SBt*cam'.^4;
if re == 0; Mpr=(I-Fs); end
if re == 0; Ms = (-SB*Lel(2)*th*Fsky'*Tsky^4)'; end
if re == 0; aa=((I-Fs)*lon'*SB*th*300.^4)'; end
if re == 0; Ms= -SB*Lel(2)*th*((1-sum(Fs,2)')'*300^4)'; end
```

sum(Ms)+sum(aa)

If we impose black body street walls and 280 K sky temperature, we observe in *Figure 87* that the heat is sucked mainly on the street walls. At the end of a cooling process of 72 hours, the temperatures are:  $T_{min72}$ =253 K,  $T_{max72}$ =278 K,  $T_{mean72}$ =267 K, (bottom right). The amplitudes of the oscillations due to the sinusoidal heat loads are decreasing with time.

From the pure geometric characteristics  $[F_{sky}]$  and  $[F_{gr}]$ , we deduce the impact of the radiation emitted by the sky, which is proportional to its temperature. The basic instruction relates the

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sky temperature to the emitted radiation. The emissivity of the sky is equal to 1. The fourth power of the sky temperature is multiplied by the Stefan-Boltzmann constant, by the sky view factor and by the areas of the elements.

 $esm = th^* lon'.^* [F_{sky}] *SB*Tsky^4; (Watt)$ 

This result is defined on the boundary elements which are here boundary segments. It is transformed in nodal values with typical formulas like:

sn(i+1,1) = (esm(i,1) + esm(i+1,1))/2; (Watt)

This transformation satifies the relation:

sum(esm) = sum(es)

It corresponds to an imposed sky temperature given in L 148, Sky temperat.: 280 K. The graph of nodal heats is given in *Figure 86*. It is obtained with the Matlab<sup> $\odot$ </sup> instruction:

```
figure('Position',[0 0 1500 700]);hold on;grid on;bar(sn);
title([' sum, max, min, mean sn: ',num2str([sum(sn) max(sn) min(sn) mean(sn)],3),'
W'], 'fontsize',20)
```



Figure 86: Nodal heat loads coming from sky



Figure 87: Street section, black body walls, injected heat: 1.64 MJ, sky temperature = 280 K



Figure 88: Same result as Figure 87, but 720 hours and same color bar,  $\rho = 0$ 

# 6.5 Thermal bridge

#### 6.5.1 Stationary heat flow - 2 convective virtual nodes

The following example relates to a domain involving convective boundaries on both sides of the main body *Figure 89*. As written under the left drawing of *Figure 89*, the convection coefficients may vary on the different patch sides of the domain (*Figure 59*).



Table 55: Explicit definitions of convective edges



*Figure 89: Thermal bridge with 2 convective virtual nodes* 



Figure 90: Thermal bridge, 2 convective virtual nodes, more than 20000 DOF



Figure 91: Two convection virtual nodes - convergence curves of dissipation functions

The convergence curves of two dissipation functions (*Figure 91*) are built with the sequence of Matlab<sup>©</sup> instructions of *Table 56*.

	Matlab <sup>®</sup> instructions enabling the representation of convergence curves					
1	mesh = [1 3 5 7 10 15 20];					
2	dissol = [104 88.9 84.3 82.4 81.1 80.6 80.6];					
3	distot = [77.6 70.3 69.2 69.3 69.9 71.1 72.2];					
4	figure('Position',[100 100 900 400]);					
5	<pre>plot (mesh,dissol);hold on;grid on;plot(mesh,distot);hold on</pre>					
6	<pre>6 legend('Dissip-total','Dissip-solid');grid on</pre>					
7	<pre>ylabel('Watt');xlabel(' Number of nodes per patch side');hold on</pre>					
8	title ('Convergence of dissipation functions')					

*Table 56: Instructions to draw convergence curves of dissipation functions* 



Figure 92: Thermal bridge with 2 convective virtual nodes

With 32 elements on each patch side, the reactive flows on the virtual convective nodes remain close to the results of the relatively coarse mesh, they are equal to  $\pm 8.24$  *W*. The dissipation in the solid was equal to 69.3 *WK*. With 5317 *DOF*, the total dissipation is 81.2 WK, in the solid it is equal to 74 *WK*. With 64 elements per side, we reach 20869 *DOF*, the total dissipation = 82.6 *WK*, the dissipation in the solid = 77.2 *WK*, the reactive flows =  $\pm 8.26$  *W*, The *CPU* = 135 seconds.

In the test of *Figure 92*, we have 8 elements per patch side. The instruction: "disp([B(dK+1) gh(dK+1); B(dK+2)])" where *B* is the vector of unknowns and *gh*, the second member, is giving the result:  $-8.2359 \quad 300.0000$ 

8.2359 280.0000 The instruction using the dot or scalar product: -dot (B, gh)/2, provides the total dissipation = 82.359 *WK*. Due to the difference of 20 *K* between both convective virtual nodes, the dissipation is equal to 10 *K* multiplied by the heat flows reactions equal to 8.24 *W*.

## 6.5.2 Stationary heat flow - 1 convective & 1 radiative virtual node

In the example of *Figure 93*, the right side of the domain is still submitted to convection, but the left one is submitted to radiation. In this example, we use an adaptation of the convective elements to generate radiative ones. Radiation is acting from the radiative boundary to a reference virtual node at imposed temperature of 270 K.



Figure 93: Thermal bridge, mixed b. c. 1 radiative v. node ( $\rho = .5$ ), 1 convective v. node

The product of the reaction flow of 26.7 *W* (*Ls 33, Figure 93*) by the difference of temperature 30 *K* (*Ls 43, Figure 93*) is equal to the dissipation: 801 *WK* (*Ls 32, Figure 93*).

The use of conductive-radiative elements (*Table 75*) equivalent to conductive-convective elements (*Table 6*) is acceptable but not very effective because the heat exchange is concentrated on a single virtual node. To take into account the interactions between radiative elements, it is necessary to associate them. This operation is related to the view factors computation.

### 6.5.3 Transient heat exchanges

a. Two convective virtual nodes



Figure 94: Thermal bridge, transient analysis, 2 convective virtual nodes

#### b. One convective and one radiative virtual node





Figure 95: Thermal bridge, transient analysis, 1 convective & 1 radiative v. node,  $\rho = 1$ 

Fiammetta 20211111	Fiammetta 20211111
Thermal bridge, Gi: 21	Thermal bridge, Gi: 22
L 4, Me, Di, Ne : 4 2 0	L 4, Me, Di, Ne : 4 12 0
L 5, Connrnvn : 5 1 1	L 5, Connrnvn : 5 0 1
L 6, rc, ra, cs : 1 0 3	L 6, rc, ra, cs : 1 1 3
L 7, CAD interf. : 16	L 7, CAD interf. : 16
L 9, N. pa., vert.: 5 12	L 9, N. pa., vert.: 5 12
L 11, num. nod side: 7	L 11, num. nod side: 7
L 13, num elem side: 8	L 13, num elem side: 8
L 23, Domain area : 66 m2	L 23, Domain area : 66 m2
L 29, Num. elements: 320	L 26, Num. elements: 320
L 31, Num. of DOF : 371	L 28, Num. of DOF : 370
L 62, Domain perim.: 56 m	L 59, Domain perim.: 56 m
L 64, Thickness : 0.1 m	L 61, Thickness : 0.1 m
L 65, Conduction k : 10 W/(mK)	L 62, Conduction k : 10 W/(mK)
L 66, DT isotherms : 1 K	L 63, DT isotherms : 1 K
L 68, St. Boltzmann: 5.6704e-08 W/(m2K4)	L 65, St. Boltzmann: 5.6704e-08 W/(m2K4)
LD 15, Fixed nodes : 370 371	LD 15, Fixed nodes : 370
LD 16, Fix. temper. : 280 300 K	LD 16, Fix. temper. : 300 K
LD 99, N. fix. nodes: 2	LD 99, N. fix. nodes: 1
L 72, Fixed DOF : 370 371	L 69, Fixed DOF : 370
L 79, Convection h : 20 W/(m2K)	L 76, Convection h : 20 W/(m2K)
c. 03, Numb. var. dK: 371	c. 03, Numb. var. dK: 370
c. 04, N.virt c.nod.: 1	c. 04, N.virt c.nod.: 1
L 92, Numb. r.nodes: 41	L 89, Numb. r.nodes: 41
L 100, Anis. index : 0	L 96, Anis. index : O
L 129, Sky temper. : 280 K	L 125, Sky temper. : 280 K
L 134, Rad. edg. len: 6 6 1 6 5 m	L 130, Rad. edg. len: 6 6 1 6 5 m
L 135, Radiativ area: 2.4 m2	L 131, Radiativ area: 2.4 m2
L 136, Refl. coeff. : 1	L 132, Refl. coeff. : 1
L 159, Radiat. area : 2.4 m2	L 158, numb. col. F : 42
	L 160, determinant M: 0.69345
	L 164, Radiat. area : 2.4 m2
	L 166, Sum 2d member: 7.01e-15 W
L 231, Num. fix. DOF: 370 371	L 231, Num. fix. DOF: 370

L 232, T. fix. nod. :	280 300 К	L 232, T. fix. nod. : 300 K
t. 04, Initial temp.:	280 K	t. 04, Initial temp.: 280 K
t. 05, Fixed DOF :	370 371	t. 05, Fixed DOF : 370
t. 08, Time step :	3600 s	t. 08, Time step : 3600 s
t. 10, Analyzed per.:	720 h, 30 days	t. 10, Analyzed per.: 720 h, 30 days
t. 16, Spec. capac. :	1000 J/(kg.K)	t. 16, Spec. capac. : 1000 J/(kg.K)
t. 17, Spec. mass :	2500 kg.m-3	t. 17, Spec. mass : 2500 kg.m-3
t. 27, sum(sum(C)) :	16.5 MJ/K	t. 27, sum(sum(C)) : 16.5 MJ/K
<pre>t. 28, area*th*ro*Cp:</pre>	16.5 MJ/K	t. 28, area*th*ro*Cp: 16.5 MJ/K
t. 31, Impos. Heat :	0 W/m-2	t. 31, Impos. Heat : 0 W/m-2
t. 38, mcr nv :	40 1	t. 38, mcr nv : 40 42
t. 44, N. rad. edges:	5	t. 44, N. rad. edges: 5
t. 45, rad seg leng.:	6 6 1 6 5	t. 45, rad seg leng.: 6 6 1 6 5 m
t. 46, N. rad. elem.:	40	t. 46, N. rad. elem.: 40
		t. 66, sum(gr) : 326 W
		t. 80, sum(Mn) : 7.01e-15 W
t.151, Tmean - Tini :	6.78 K	t.151, Tmean - Tini : 6.78 K
t.152, Stored heat :	112 MJ	t.152, Stored heat : 112 MJ
t.154, Min it+1 temp:	280.3 K	t.154, Min it+1 temp: 280.3 K
t.155, Max it+1 temp:	300 K	t.155, Max it+1 temp: 300 K
t.164, Ejected heat :	0.202 MJ	t.164, Ejected heat : 0.202 MJ
L 239, Diss in solid:	129 WK	L 239, Diss in solid: 129 WK
L 240, Total dissip.:	140 WK	L 240, Total dissip.: 140 WK
L 241, End Me=4. CPU:	3.74 sec.	L 241, End Me=4. CPU: 4.78 sec.

Figure 96: Thermal bridge comparison, radiative virtual node – radiative edge,  $\rho = 1$ 

For radiative exchange handled with a virtual radiative node, the result is independent of the reflection coefficient  $\rho$  more or less in the range  $0 \le \rho \le .9$ .

Fiammetta 20211111	Fiammetta 20211111
Thermal bridge, Gi: 21	Thermal bridge, Gi: 22
L 4, Me, Di, Ne : 4 2 0	L 4, Me, Di, Ne : 4 12 0
L 5, Connrnvn : 5 1 1	L 5, Connrnvn : 5 0 1
L 6, rc, ra, cs : 1 0 3	L 6, rc, ra, cs : 1 1 3
L 7, CAD interf. : 16	L 7, CAD interf. : 16
L 9, N. pa., vert.: 5 12	L 9, N. pa., vert.: 5 12
L 11, num. nod side: 7	L 11, num. nod side: 7
L 13, num elem side: 8	L 13, num elem side: 8
L 23, Domain area : 66 m2	L 23, Domain area : 66 m2
L 29, Num. elements: 320	L 26, Num. elements: 320
L 31, Num. of DOF : 371	L 28, Num. of DOF : 370
L 62, Domain perim.: 56 m	L 59, Domain perim.: 56 m
L 64, Thickness : 0.1 m	L 61, Thickness : 0.1 m
L 65, Conduction k : 10 W/(mK)	L 62, Conduction k : 10 W/(mK)
L 66, DT isotherms : 1 K	L 63, DT isotherms : 1 K
L 68, St. Boltzmann: 5.6704e-08 W/(m2K4)	L 65, St. Boltzmann: 5.6704e-08 W/(m2K4)
LD 15, Fixed nodes : 370 371	LD 15, Fixed nodes : 370
LD 16, Fix. temper. : 280 300 K	LD 16, Fix. temper. : 300 K
LD 99, N. fix. nodes: 2	LD 99, N. fix. nodes: 1
L 72, Fixed DOF : 370 371	L 69, Fixed DOF : 370
L 79, Convection h : 20 W/(m2K)	L 76, Convection h : 20 W/(m2K)
c. 03, Numb. var. dK: 371	c. 03, Numb. var. dK: 370
c. 04, N.virt c.nod.: 1	c. 04, N.virt c.nod.: 1
L 92, Numb. r.nodes: 41	L 89, Numb. r.nodes: 41
L 100, Anis. index : 0	L 96, Anis. index : 0
L 129, Sky temper. : 280 K	L 125, Sky temper. : 280 K
L 134, Rad. edg. len: 6 6 1 6 5 m	L 130, Rad. edg. len: 6 6 1 6 5 m
L 135, Radiativ area: 2.4 m2	L 131, Radiativ area: 2.4 m2
L 132, Refl. coeff. : .5	L 132, Refl. coeff. : .5
L 159, Radiat. area : 2.4 m2	L 159, Radiat. area : 2.4 m2
	L 161, numb. col. F : 42
	L 163, determinant M: 0.9161
	L 167, Sum 2d member: -348 W
L 231, Num. fix. DOF: 370 371	L 233, Num. fix. DOF: 370
L 232, T. fix. nod. : 280 300 K	L 234, T. fix. nod. : 300 K
t. 04, Initial temp.: 280 K	t. 04, Initial temp.: 280 K
t. 05, Fixed DOF : 370 371	t. 05, Fixed DOF : 370
t. 08, Time step : 3600 s	t. 08, Time step : 3600 s
t. 10, Analyzed per.: 720 h, 30 days	t. 10, Analyzed per.: 720 h, 30 days
t. 16, Spec. capac. : 1000 J/(kg.K)	t. 16, Spec. capac. : 1000 J/(kg.K)
t. 17, Spec. mass : 2500 kg.m-3	t. 17, Spec. mass : 2500 kg.m-3
t. 27, sum(sum(C)) : 16.5 MJ/K	t. 27, sum(sum(C)) : 16.5 MJ/K
t. 28, area*th*ro*Cp: 16.5 MJ/K	t. 28, area*th*ro*Cp: 16.5 MJ/K
t. 31, Impos. Heat : 0 W/m-2	t. 31, Impos. Heat : 0 W/m-2

t. 38, mcr nv : 40 1	t. 38, mcr nv : 40 42
t. 44, N. rad. edges: 5	t. 44, N. rad. edges: 5
t. 45, rad seg leng.: 6 6 1 6 5	t. 45, rad seg leng.: 6 6 1 6 5 m
t. 46, N. rad. elem.: 40	t. 46, N. rad. elem.: 40
	t. 66, sum(gr) : 131 W
	t. 80, sum(Mn) : -348 W
t.151, Tmean - Tini : 5.63 K	t.142, Tmean - Tini : 7.04 K
t.152, Stored heat : 92.9 MJ	t.143, Stored heat : 116 MJ
t.154, Min it+1 temp: 280 K	t.145, Min it+1 temp: 279.6 K
t.155, Max it+1 temp: 300 K	t.146, Max it+1 temp: 300 K
t.164, Ejected heat : 0.202 MJ	t.152, Ejected heat : 0.202 MJ
L 239, Diss in solid: 172 WK	L 240, Diss in solid: 162 WK
L 240, Total dissip.: 185 WK	L 241, Total dissip.: 174 WK
L 241, End Me=4. CPU: 3.84 sec.	L 242, End Me=4. CPU: 6.12 sec.

Figure 97: Thermal bridge comparison, radiative virtual node – radiative edge,  $\rho = .5$ 

#### c. One convective node and one radiative edge

Now, we take into account the inter element view factors in the treatment of the radiative part of the domain which is the left side in this example. The variable ra select either a handling of the radiative exchanges with a virtual node similar to the virtual convective one (ra = 0) or a handling with inter element view factors (ra = 1).

The warranty of a temperature everywhere greater or equal to 280 K, is obtained only if we use a reflection coefficient greater or equal to 0,9999. Even if the results seem correct, this condition is unbelievable.



t. 38, mcr nv :	40 42	
t. 45, N. rad. edges:	5	
t. 46, rad seg leng.:	66165m	
t. 47, N. rad. elem.:	40	
t. 63, sum(gr) :	131 W	
t. 75, sum(Mn) :	-348 W	
t.142, Tmean - Tini :	7.04 K	
t.143, Stored heat :	116 MJ	
t.145, Min it+1 temp:	279.6 К	
t.146, Max it+1 temp:	300 K	
t.152, Ejected heat :	0.202 MJ	
L 240, Diss in solid:	162 WK	
L 241, Total dissip.:	174 WK	
L 242, End Me=4. CPU:	6.12 sec.	

Figure 98: Thermal bridge, transient analysis, 1 convective node & 1 radiative side

	Matlab <sup>©</sup> function <i>fem_Kra.m</i>					
1	<pre>function[K,Qs,Qg] = fem Kra(Kk,lcont,re,Ftot,SBt,tcan,Tsky,lon) % 20211118</pre>					
2	K = Kk;					
3	<pre>nd = size(lcont,1)-1; % nd = number radiatve nodes</pre>					
4	<pre>M = eye(nd)-re*Ftot(1:nd,1:nd); % Radiosity matrix</pre>					
5	<pre>% S = eye(nd)*SBt*(1-re).*lon(1:nd);</pre>					
6	<pre>S = eye(nd)*SBt.*lon(1:nd);</pre>					
7	tb = $zeros(nd, 1);$					
8	<pre>for i = 1:nd; tb(i) = (tcan(lcont(i))+tcan(lcont(i+1)))/2; end</pre>					
9	for i = 1:nd; S(i,i) = S(i,i)*tb(i)^3 ; end					
10	KI = $(eye(nd) - Ftot(1:nd, 1:nd)) * M^{(-1)} * S;$					
11	<pre>N = zeros(nd,nd+1); for i = 1:nd; N(i,i)=.5; N(i,i+1)=.5; end% edg to nod</pre>					
12	KJ = N' * KI * N;					
13	for i = 1:nd					
14	<pre>for j = 1:nd;K(lcont(i),lcont(j))=K(lcont(i),lcont(j))+KJ(i,j);end</pre>					
15	end					
16	Qs = (Ftot(1:nd,1:nd)*M^(-1)*Ftot(1:nd,nd+1)*SBt*Tsky^4)'*N;					
17	Qg = (Ftot(1:nd,1:nd)*M^(-1)*Ftot(1:nd,nd+2)*SBt*Tsky^4)'*N;					
18	end					

*Table 57: Matlab<sup>©</sup> function fem Kra.m* 

# 7. Conclusion

In the transient problems, the non-linearity due to radiation does not seem to give any particular problem. After the calculation of the thermal loading of the domain, we have successively examined four configurations: the cavity is the object of a convection phenomenon, the cavity has perfectly reflective walls, the walls of the cavity constitute a black body and finally the walls of the cavity constitute a gray body. We have finished with some gray body comparisons. The tests carried out on the view factor matrix as well as on the solution of thermal problems including radiation are very encouraging. The visualization of the results at different time steps by isotherms and by heat flow vectors for relatively coarse meshes is very effective and allows understanding the physics of heat exchanges by conduction, convection and radiation.

## 8. Miscellaneous

## 8.1 Main procedure: Fiammetta.m

Simplified scheme of the solution method used in the procedure *Fiammetta\_20211111.m* (*Table 58*).

Line	<i>14→ 23</i> :	Computation of the domain area		
Line	$27 \rightarrow 32$ :	Geometric input data		
Line	$34 \rightarrow 40$ :	Nodes and mesh generation	cad_mes.m	( <i>Table 15</i> )
Line	<i>41→ 61</i> :	Computing the outwards normal	gra_mnl.m	( <i>Table 66</i> )
Line	<i>65</i> :	End of geometric data processing		

Line	<i>69</i> →	72: Dirichlet boundary condition	ons	cad Dir.m	( <i>Table 17</i> )
Line	$73 \rightarrow$	74: Neumann boundary condition	ions	cad Neu.m	( <i>Table 18</i> )
Line	<i>77</i> →	82: Topology of the convection	n elem.	cad con.m	( <i>Table 19</i> )
Line	84→	96: Identification of the radiati	ng nodes	cad ban.m	( <i>Table 26</i> )
Line	<i>97</i> →	117: Assemble cond. & conv. el	. matrices	_	
Line	119→	<i>173</i> : Radiative heat exchanges	cavity	geo vfs.m	( <i>Table 27</i> )
			street	geo stf.m	( <i>Table 38</i> )
			balcony	geo_baf.m	( <i>Table 42</i> )
cs =	1, 2, 3:	View factor and radiosity matrix	$137 \rightarrow 173$		
Me =	1:	linear permanent heat transfer	$175 \rightarrow 214$		
Me = 1	2:	Nonlinear permanent heat transfer	$215 \rightarrow 223$	fem snl.m	( <i>Table 76</i> )
Me = 1	3:	Transient linear heat transfer	$224 \rightarrow 230$	fem til.m	( <i>Table 62</i> )
Me =	4:	Nonlinear transient heat transfer	$231 \rightarrow 244$	fem tir.m	( <i>Table 63</i> )
Me = 1	5:	Cavity, VF matrix radiat exchange	s $245 \rightarrow 275$	fem tit.m	( <i>Table 60</i> )



Procedure Fiammetta 20211111.m CPU = tic; deb = 0 ;Ai = 0;fa=1000 ;F=0;lon=0.; 1 Gi =10;[xyz\_cao,car\_cao,nbo,Me,Di,Ne,Co,nvn,nnr] = cad gin(Gi); 2 % rc = 1: rad. exch. computed, ra = 1: VF used 3 rc = 1; ra = 0; cs = 4;disp(['L 4, Me, Di, Ne disp(['L 5, Connrnvn : ',num2str([Me Di Ne])]) : ',num2str([Co nnr nvn])]) 4 5 : ',num2str([rc ra cs])]) : ',num2str(nbo)]) disp(['L 6 6, rc, ra, cs disp(['L 7. CAD interf. 7 8 np = size(car\_cao,1);npv = size(xyz\_cao,1); 9 disp(['L 9, N. pa., vert.: ',num2str([np npv])]) nni =15;if nni<1;nni=1;end</pre> 10 % Number nodes inserted on patches borders disp(['L 11, num. nod side: ',num2str(nni)]) 11 nci = nni+1;mc=nci\*4;if cs==2; mc = mc-nni; end % cs = 2 street 3 patches 12 13 disp(['L 13, num elem side: ',num2str(nci)]) 14 area = 0;for i = 1:np % Sum of patch areas = domain area: lines 13-21 15 area = area + norm(... 16 17 cross([xyz cao(car cao(i,3),:)-xyz cao(car cao(i,1),:) 0],... [xyz cao(car cao(i,4),:)-xyz cao(car cao(i,1),:) 0])); 18 19 area = area + norm(... cross([xyz cao(car cao(i,2),:)-xyz cao(car cao(i,1),:) 0],... 20 21 [xyz\_cao(car\_cao(i,3),:)-xyz\_cao(car\_cao(i,1),:) 0])); 22 end area = area/2; disp(['L 23, Domain area : ',num2str(area),' m2'])
if deb==1 ;disp( 'L 25, Call function: .... cad\_mes ....');end
[xyt,lK,bor,pbo] = cad\_mes(xyz\_cao,car\_cao,nni,nbo); % Mesh generation 23 24 2.5 nel = size(lK,1) ; disp(['L 26, Num. elements: ',num2str(nel)]) 26 27 no = size(xyt,1);dK = no + nvn + nnr; disp(['L 28, Num. of DOF : ',num2str(dK)]) 2.8 29 for i = 1:nel % Enforce anticlockwize ordering of element nodes 30 = cross([xyt(lK(i,3),:)-xyt(lK(i,1),:) 0],... n 31 [xyt(lK(i,4),:)-xyt(lK(i,1),:) 0]); 32 if n(3) < 0; iq = lK(i,2); lK(i,2) = lK(i,4); lK(i,4) = iq; end 33 end 34 bov = zeros(nbo,npv+2); bov(:,1:2)=bor(:,1:2); pe = 0.;% Outward normals if deb==1;disp('L 39, Call function: ..... gra\_mnl .....');end 35 gra mnl(xyz cao, car cao, [0 0 0]); axis equal; % Drawing normals: + line 56 36 axis off;title(['Labels & normals of the ',num2str(np),' patche(s)']) 37 38 for i = 1 : nbo % ..... Loop on the nin CAD interfaces 39 if bor(i,4)==0% interface i must be a single one to be on the boundary 40 ne = cross([xyt(bor(i,2),:)-xyt(bor(i,1),:) 0],[0 0 1]); 41 nn = ne / norm(ne);mi = [(xyt(bor(i,6),:) + xyt(bor(i,5),:))/2 0]; 42 % Mid edge li = norm(xyt(bor(i,2),:) - xyt(bor(i,1),:)); % Edge length
pe = pe + li; % Update the perimeter of the CAD domain 43 44 % Normal vector: mi - po 45 po = (mi + nn\*li/5);plot([mi(1) po(1)],[mi(2) po(2)],'b','LineWidth',2);hold on 46 47 for j = 1:npv % Loop on npv vertices not in patch bor(i,3) = 0; 48 ves

% Check if vertex j is in patch bor(i,3) 49 for c = 1:450 if j == car cao(bor(i,3),c);yes = 1;end 51 end 52 if yes == 0 % Find vertices visible from interface bor(i,1:2) 53 pn = [xyz cao(j,:) 0] - mi; vis = dot(po-mi,pn); if vis > 0; bov(i,j+2)=j; end 54 55 end 56 end 57 end end % .....End loop on the nbo CAD interfaces to draw the outwards normals 58 disp(['L 59, Domain perim.: ',num2str(pe),' m']) % End outward normals 59 xyz = zeros(dK,3); xyz(1:no,1:2) = xyt; % Coordinates expressed in 3D th =.1; disp(['L 61, Thickness : ',num2str(th),' m']) k =.2; disp(['L 62, Conduction k : ',num2str(k),' W/(mK)']) 60 61 62 pai = 1 ; disp(['L 63, DT isotherms : ',num2str(pai), ' K']) 63 SB = 5.6704e-8;% Stefan-Boltzmann constant Wm-2K-4 64 65 if rc > 0 ;disp(['L 65, St. Boltzmann: ',num2str(SB),' W/(m2K4)']);end if deb == 1;disp('L 67, Call function: ..... cad Dir ....');end 66 [lfi, fT] = cad Dir(Di,no,nvn,car cao,bor,pbo,nni); 67 % Dirichlet b.c. if lfi(1) == 0;nf = 0;else;nf=size(lfi,2);end 68 < 10 ;disp(['L 69, Fixed DOF : ',num2str(lfi)]);end == 1; disp( 'L 71, Call function: ..... cad\_Neu .....');end 69 if nf 70 if deb 71 [gh,bos] = cad\_Neu(Ne,dK,car\_cao,pbo,bor,th,xyz\_cao);% Neumann b.c. 72 if deb == 1;disp('L 75, Call function: ..... cad\_mnl .....');end 73 if nel < 101;gra mnl(xyz,lK,[0 0 0]);axis equal,axis off;hold on;end 74 if Co > 075 vc=zeros(nvn+nnr,2);xyz(no+(1:nvn+nnr),1:2)=vc; % Virtual nodes def. h= 5;disp(['L 76, Convection h : ',num2str(h), ' W/(m2K)']) 76 77 if deb == 1;disp( 'L 78, Call function: ..... cad\_con ....c');end 78 [lc,he] = cad con(car cao,bor,pbo,h,dK,nci,deb,nvn,cs,Co);% mcr=0; 79 end & End option Co > 0. Some sides are linked to virtual convective nodes 80 lcont = zeros(nbo\*nci,1); 81 if cs == 0% Compute the radiative nodes, vertices & number % mcr is the number of radiative nodes 82 mcr = 0;83 else % Analysis of the 3 situations: cavity, street, balcony if cs ~=4 84 8 % If cs = 5, both vertical sides are convective if deb==1; disp( 'L 86, Call function: ..... cad\_ban .....');end 85 86 [lcont,lv] = cad ban(car cao,bor,pbo,nni,cs); 87 응 mcr = size(lcont,1)+1; % For open space like a street or balcony 88 mcr = size(lcont,1); % Closed cavities if mcr > 0; disp(['L 89, Numb. r.nodes: ',num2str(mcr)]) 8 89 90 if mcr < 12;disp(['L 90, R. nod. lcont: ',num2str(lcont')]);end</pre> 응 91 응 if size(lv,2) > 1;disp(['L 91, Rad. vertices: ',num2str(lv)]);end 응 end 92 93 end 94 % ..... Assembling the nel element conductivity matrices 95 Kk = zeros(dK,dK); % Initializations 96 disp(['L 96, Anis. index : ',num2str(Ai)]) if Ai == 0; co = ones(1, nel)\*k; else; co = mat\_cok(Ai, nci, fa, xyz, lK, deb); end 97 98 if deb == 1; disp('L 100, Call function: ..... fem\_Kco .....');end 99 for n = 1:nel % Compute global K matrix, loop on the elements 100 Kel = fem Kco(xyz,lK(n,:))\*co(n)\*th; % Element conductivity matrix for i = 1:4;i1 = lK(n,i); 101 for j = 1:4; j1 = lK(n, j); Kk(i1, j1) = Kk(i1, j1) + Kel(i, j); end102 103 end 104 end % End assembling the nel conductivity matrices 105 K = Kk; 106 if Co > 0 % Assembling the nco = size(lc,1) element convective matrices 107 if deb == 1;disp('L 109, Call function: ..... fem\_Kcv .....');end 108 109 for i = 1:3110 111 for j=1:3;K(lc(n,i),lc(n,j))=K(lc(n,i),lc(n,j))+Kec(i,j);end end 112 end 113 end 114 % End assembling the nco convection matrices = zeros(nbo\*nci,1);
== 0 115 Ms 116 if rc % Radiative exhanges are not present 117 re = 0; Lel(1) = 0; ns = 0;% Init. edge elements lenghts 118 else % View factor and radiosity matrices for radiative transfers if cs == 1;lcc = [lv';lv(1)];ns = 4;end % lcc & ns: quadril. cavity
if cs == 2;lcc = lv; ns = 3;end % lcc & ns: street section 119 ns = 3;end if cs == 2;lcc = lv; if cs == 3;lcc = lv; if cs == 4;lcc = lv; 120 ns = 5;end % lcc & ns: Thermal bridge 121 ns = 2;end 122 % lcc & ns: rectangle if cs == 5;lcc = [lv';lv(1)];ns = 4;end % lcc & ns: quadril. cavity 123 Lel = zeros(ns,1); % Compute the lengths of th ns radiative edges Tsky =280;disp(['L 125, Sky temper. : ',num2str(Tsky),' K']) 124 125

120	for i = 1:ns
127	Lel(i) = sgrt((xvz cao(lcc(i+1),1)-xvz cao(lcc(i),1))^2 +
128	$(x_{1}, z_{2}, z_{3})$
120	
129	ena;
130	disp(['L 130, Rad. edg. len: ',num2str(Lel(l:ns)'),' m'])
131	<pre>disp(['L 131, Radiativ area: ',num2str(sum(Lel)*th),' m2'])</pre>
132	re =0.5 ;disp(['L 132, Refl. coeff. : ',num2str(re)])
133	if cs == 1 % Quadrilateral cavity view factors
134	if deb==1;disp('L 155, Call function: geo vfs');end
135	$F_{s} = q_{e} q_{e} q_{e} (n_{e} i_{e} I_{e} I_{e} I_{e} n_{s}) : I = e v e (size(F_{s}, 1)) :$
136	$M = (T_{r} \times T_{r} \times T_{r}) \cdot d_{1} \times (T_{r} \times T_{r}) \times (T_{r} \times T_{r}) \cdot d_{1} \times (T_{r} \times T_{r}) \times (T_{r}) \times (T_{r} \times T_{r}) \times (T_{r}) \times $
127	M = (1-1e <sup>-r</sup> s), disp([ 1 150, det (M)) . , num2sti(det(M))])
137	
138	II CS == 2 % Street section view factors
139	<pre>if deb ==1;disp('L 140, Call function: geo_stf');end</pre>
140	Fs = geo_stf(nci,Lel(2:3));I=eye(size(Fs,1));% Street VF mat.
141	M = (I-re*Fs); disp(['L 141, sum(sum(M)) : ', num2str(sum(sum(M)))])
142	Fsky = 1-sum(Fs,2)'; % Col. vect. of sky view fact.
143	if nni ==1:disp(['L 146. Es=1-sum(E.2): '.num2str(Esky.3)]):end
111	if $r_{1} = 1$ , $M_{2} = r_{2} (r_{1} = r_{2} (r_{2} = r_{2} (r_{1} = r_{1}))$ , $r_{1} = r_{2} (r_{1} = r_{1})$
144	11 1e - 1, MS - 2elos(Sl2e(FS, 1), 1) , else
145	nne = (mcr-1)/3; % nne = numb segm per street side
146	lon = zeros(1, nne);
147	for 1 = 1:nne % Computing the element lengths on the 3 sides
148	lon(i) = Lel(1)/(nne); lon(mcr-i) = Lel(3)/(nne);
149	lon(i+nne) = Lel(2)/(nne);
150	<pre>end; disp(['L 154, Radiat. area : '.num2str(sum(lon)*th).' m2'])</pre>
151	Ms = (re*(I-Fs)*M^(-1)-I)*SB*Lel(2)*th*Fskv'*Tskv^4:%Ms=-SB*Fskv'*Tskv^4:
152	if mor < 10:disp([1, 156 Ms mid-aday + ] num2etr(Me)] + W1).ord
153	and disp([11]]77 Sum altri loadet   pum2atr/(ma) 2)   W//2011
151 151	end (arsp([ L 157, Sum Sky roads: ', num2str(sum(Ms), 5), ' W/M2'])
104	ena
155	if cs == 3 % Thermal bridge view factors
156	<pre>if deb==1;disp('L 156, Call function: geo_baf');end</pre>
157	<pre>Ftot = 0 ;nco = size(Lel,1);k = 0;lon = zeros(1,nco*nci);</pre>
158	<pre>for i = 1:nco;for j = 1:nci;k=k+1;lon(k) = Lel(i)/nci;end;end;</pre>
159	disp(['L 159, Radiat, area : '.num2str(sum(lon)*th).' m2'])
160	if $r_{a} = 1 \cdot F = geo haf(nci xyz cao)$ .
161	$ \begin{array}{c} \text{If } I \\ \text{ and } \text{ of } $
160	HV = SIZe(F, Z), GISP([H, 100, Correction of the state
102	$FS = F(1:  v-2\rangle, 1:  v-2\rangle) = eye(S12e(FS,1)) = (1-1e^{FS});$
103	disp(['L'163, determinant M: ', num2str(det(M))])
164	Fgr = F(1:nv-2, nv-1); Fsky=F(1:nv-2, nv);
165	nne = size(Fs,1);k=0;%ion = zeros(1,nne
166	Ms = (re*(1-Fs)*M^(-1)-1)*SB*th*(Fsky+Fgr).*Tsky^4.*Ion';
167	disp(['L 167, Sum 2d member: ',num2str(sum(Ms),3),' W'])
168	if nni == 1
169	disp(['L 169, Ms Eq. 104 : ',num2str(Ms')])
170	disp(['L 170, unicol Far ', num2str(Far', 3)]);
171	disp([ i i/o, differ igi , /idm20ci(igi /o/]//
1/1	disp(['L 171, unicol Fsky : ',num2str(Fsky',3)])
172	disp(['L 171, unicol Fsky : ',num2str(Fsky',3)]) disp(['L 172, sum(F,2) : ',num2str(sum(F,2)',3)])
172 173	<pre>disp(['L 171, unicol Fsky : ',num2str(Fsky',3)]) disp(['L 172, sum(F,2) : ',num2str(sum(F,2)',3)]) end</pre>
171 172 173 174	<pre>disp(['L 171, unicol Fsky : ',num2str(Fsky',3)])</pre>
172 173 174 175	<pre>disp(['L 171, unicol Fsky : ',num2str(Fsky',3)])</pre>
172 173 174 175 176	<pre>disp(['L 171, unicol Fsky : ',num2str(Fsky',3)])</pre>
172 173 174 175 176 177	<pre>disp(['L 171, unicol Fsky : ',num2str(Fsky',3)]) disp(['L 172, sum(F,2) : ',num2str(sum(F,2)',3)]) end end end if Me == 1 % Solution of linear steady state beat transfer problems</pre>
171 172 173 174 175 176 177 178	<pre>disp(['L 171, unicol FgF ', ',num2str(Fsky',3)])</pre>
171 172 173 174 175 176 177 178	<pre>end end end if Me == 1 % Solution of linear steady state heat transfer problems nf = size(lfi,2); N = zeros(nf,dK);% L. con. fix.%gh=zeros(nf,1); for i = linf:N(i lfi(i)) = lingb(dK+i) = fT(i): ord:</pre>
171 172 173 174 175 176 177 178 179	<pre>end end end end if Me == 1 % Solution of linear steady state heat transfer problems nf = size(lfi,2); N = zeros(nf,dK);% L. con. fix.%gh=zeros(nf,1); for i = 1:nf;N(i,lfi(i)) = 1;gh(dK+i) = fT(i); end;</pre>
171 172 173 174 175 176 177 178 179 180	<pre>end end end end if Me == 1 % Solution of linear steady state heat transfer problems nf = size(lfi,2); N = zeros(nf,dK);% L. con. fix.%gh=zeros(nf,1); for i = 1:nf;N(i,lfi(i)) = 1;gh(dK+i) = fT(i); end; A = [K N';N zeros(nf,nf)];B = A\gh;tca = B(1:dK);</pre>
171 172 173 174 175 176 177 178 179 180 181	<pre>end end end end if Me == 1 % Solution of linear steady state heat transfer problems nf = size(lfi,2); N = zeros(nf,dK);% L. con. fix.%gh=zeros(nf,1); for i = 1:nf;N(i,lfi(i)) = 1;gh(dK+i) = fT(i); end; A = [K N';N zeros(nf,nf)];B = A\gh;tca = B(1:dK); figure;gt =[min(tca) pai max(tca)];</pre>
171 172 173 174 175 176 177 178 179 180 181 182	<pre>end end end end end if Me == 1 % Solution of linear steady state heat transfer problems nf = size(lfi,2); N = zeros(nf,dK);% L. con. fix.%gh=zeros(nf,1); for i = 1:nf;N(i,lfi(i)) = 1;gh(dK+i) = fT(i); end; A = [K N';N zeros(nf,nf)];B = A\gh;tca = B(1:dK); figure;gt =[min(tca) pai max(tca)]; if deb ==1;disp(['L 173, DT isoth gt : ',num2str(gt),' K']);end</pre>
171 172 173 174 175 176 177 178 179 180 181 182 183	<pre>end end end end end if Me == 1 % Solution of linear steady state heat transfer problems nf = size(lfi,2); N = zeros(nf,dK);% L. con. fix.%gh=zeros(nf,1); for i = 1:nf;N(i,lfi(i)) = 1;gh(dK+i) = fT(i); end; A = [K N';N zeros(nf,nf)];B = A\gh;tca = B(1:dK); figure;gt =[min(tca) pai max(tca)]; if deb ==1;disp(['L 173, DT isoth gt : ',num2str(gt),' K']);end nc3 = (nci)^2; % nc3 = numb elem / patch, same for all the patches</pre>
171 172 173 174 175 176 177 178 179 180 181 182 183 184	<pre>disp(['L 171, unicol Fgf ', ',num2str(Fsky',3)]) disp(['L 172, sum(F,2) : ',num2str(Fsky',3)]) end end end end if Me == 1 % Solution of linear steady state heat transfer problems nf = size(lfi,2); N = zeros(nf,dK);% L. con. fix.%gh=zeros(nf,1); for i = 1:nf;N(i,lfi(i)) = 1;gh(dK+i) = fT(i); end; A = [K N';N zeros(nf,nf)];B = A\gh;tca = B(1:dK); figure;gt =[min(tca) pai max(tca)]; if deb ==1;disp(['L 173, DT isoth gt : ',num2str(gt),' K']);end nc3 = (nci)^2; % nc3 = numb elem / patch, same for all the patches if deb ==1;disp( 'L 175, Call function: gra ipa');end</pre>
172 173 174 175 176 177 178 179 180 181 182 183 184 185	<pre>disp(['L 171, unicol Fsky : ',num2str(Fsky',3)]) disp(['L 172, sum(F,2) : ',num2str(Fsky',3)]) end end end end if Me == 1 % Solution of linear steady state heat transfer problems nf = size(lfi,2); N = zeros(nf,dK);% L. con. fix.%gh=zeros(nf,1); for i = 1:nf;N(i,lfi(i)) = 1;gh(dK+i) = fT(i); end; A = [K N';N zeros(nf,nf)];B = A\gh;tca = B(1:dK); figure;gt =[min(tca) pai max(tca)]; if deb ==1;disp(['L 173, DT isoth gt : ',num2str(gt),' K']);end nc3 = (nci)^2; % nc3 = numb elem / patch, same for all the patches if deb ==1;disp( 'L 175, Call function: gra_ipa');end for i = 1 : np</pre>
172 173 174 175 176 177 178 179 180 181 182 183 184 185 186	<pre>disp(['L 171, unicol Fsky : ',num2str(Fsky',3)]) disp(['L 171, unicol Fsky : ',num2str(Fsky',3)]) disp(['L 172, sum(F,2) : ',num2str(sum(F,2)',3)]) end end end end if Me == 1 % Solution of linear steady state heat transfer problems nf = size(lfi,2); N = zeros(nf,dK);% L. con. fix.%gh=zeros(nf,1); for i = 1:nf;N(i,lfi(i)) = 1;gh(dK+i) = fT(i); end; A = [K N';N zeros(nf,nf)];B = A\gh;tca = B(1:dK); figure;gt = [min(tca) pai max(tca)]; if deb ==1;disp(['L 173, DT isoth gt : ',num2str(gt),' K']);end nc3 = (nci)^2; % nc3 = numb elem / patch, same for all the patches if deb ==1;disp( 'L 175, Call function: gra_ipa');end for i = 1 : np</pre>
171 172 173 174 175 176 177 178 179 180 181 182 183 184 185 186 187	<pre>disp(['L 171, unicol Fgf ', num2str(Fsky',3)])     disp(['L 172, sum(F,2) : ',num2str(Fsky',3)])     end     end end end end if Me == 1 % Solution of linear steady state heat transfer problems nf = size(lfi,2); N = zeros(nf,dK);% L. con. fix.%gh=zeros(nf,1); for i = 1:nf;N(i,lfi(i)) = 1;gh(dK+i) = fT(i); end; A = [K N';N zeros(nf,nf)];B = A\gh;tca = B(1:dK); figure;gt =[min(tca) pai max(tca)]; if deb ==1;disp(['L 173, DT isoth gt : ',num2str(gt),' K']);end nc3 = (nci)^2; % nc3 = numb elem / patch, same for all the patches if deb ==1;disp('L 175, Call function: gra_ipa');end for i = 1 : np</pre>
171 172 173 174 175 176 177 178 179 180 181 182 183 184 185 186 187 188	<pre>disp(['L 171, unicol FgY : ',num2str(FsKy',3)])     disp(['L 172, sum(F,2) : ',num2str(FsKy',3)])     end     end end end end end if Me == 1 % Solution of linear steady state heat transfer problems nf = size(lfi,2); N = zeros(nf,dK);% L. con. fix.%gh=zeros(nf,1); for i = 1:nf;N(i,lfi(i)) = 1;gh(dK+i) = fT(i); end; A = [K N';N zeros(nf,nf)];B = A\gh;tca = B(1:dK); figure;gt =[min(tca) pai max(tca)]; if deb ==1;disp(['L 173, DT isoth gt : ',num2str(gt),' K']);end nc3 = (nci)^2; % nc3 = numb elem / patch, same for all the patches if deb ==1;disp( 'L 175, Call function: gra_ipa');end for i = 1 : np</pre>
172 173 174 175 176 177 178 179 180 181 182 183 184 185 186 187 188 189	<pre>disp(['L 171, unicol FgY : ',num2str(FsKy',3)]) disp(['L 172, sum(F,2) : ',num2str(sum(F,2)',3)]) end end end end end if Me == 1 % Solution of linear steady state heat transfer problems nf = size(lfi,2); N = zeros(nf,dK);% L. con. fix.%gh=zeros(nf,1); for i = 1:nf;N(i,lfi(i)) = 1;gh(dK+i) = fT(i); end; A = [K N';N zeros(nf,nf)];B = A\gh;tca = B(1:dK); figure;gt =[min(tca) pai max(tca)]; if deb ==1;disp(['L 173, DT isoth gt : ',num2str(gt),' K']);end nc3 = (nci)^2; % nc3 = numb elem / patch, same for all the patches if deb ==1;disp( 'L 175, Call function: gra_ipa');end for i = 1 : np % Loop on CAD patches gra_ipa(nci,nci,lK((i-1)*nc3+1:nel,:),tca,xyz,gt);hold on end axis equal;colorbar;axis off title (['Dissipation: ',num2str(5*tca'*K*tca.3),' WK, DOE: ', </pre>
172 173 174 175 176 177 178 179 180 181 182 183 184 185 186 187 188 189 190	<pre>disp(['L 171, unicol FgY : ',num2str(Fsky',3)]) disp(['L 172, sum(F,2) : ',num2str(Fsky',3)]) end end end end if Me == 1 % Solution of linear steady state heat transfer problems nf = size(lfi,2); N = zeros(nf,dK);% L. con. fix.%gh=zeros(nf,1); for i = 1:nf;N(i,lfi(i)) = 1;gh(dK+i) = fT(i); end; A = [K N';N zeros(nf,nf)];B = A\ght{gt}cta = B(1:dK); figure;gt =[min(tca) pai max(tca)]; if deb ==1;disp(['L 173, DT isoth gt : ',num2str(gt),' K']);end nc3 = (nci)^2; % nc3 = numb elem / patch, same for all the patches if deb ==1;disp( 'L 175, Call function: gra_ipa');end for i = 1 : np gra_ipa(nci,nci,lK((i-1)*nc3+1:nel,:),tca,xyz,gt);hold on end axis equal;colorbar;axis off title (['Dissipation: ',num2str(.5*tca'*K*tca,3),' WK, DOF: ', num2str(dK).' '1)</pre>
172 173 174 175 176 177 178 179 180 181 182 183 184 185 186 187 188 189 190 191	<pre>disp(['L 171, unicol Fsky : ',num2str(Fsky',3)]) disp(['L 172, sum(F,2) : ',num2str(Fsky',3)]) end end end end end if Me == 1 % Solution of linear steady state heat transfer problems nf = size(lfi,2); N = zeros(nf,dK);% L. con. fix.%gh=zeros(nf,1); for i = 1:nf;N(i,lfi(i)) = 1;gh(dK+i) = fT(i); end; A = [K N';N zeros(nf,nf)];B = A\gh;tca = B(1:dK); figure;gt =[min(tca) pai max(tca)]; if deb ==1;disp(['L 173, DT isoth gt : ',num2str(gt),' K']);end nc3 = (nci)^2; % nc3 = numb elem / patch, same for all the patches if deb ==1;disp( 'L 175, Call function: gra_ipa');end for i = 1 : np</pre>
172 173 174 175 176 177 178 179 180 181 182 183 184 185 186 187 188 189 190 191 192	<pre>disp(['L 171, unicol FgY : ',num2str(FsKy',3)])     disp(['L 172, sum(F,2) : ',num2str(FsKy',3)])     end     end end end end end end if Me == 1 % Solution of linear steady state heat transfer problems nf = size(lfi,2); N = zeros(nf,dK);% L. con. fix.%gh=zeros(nf,1); for i = 1:nf;N(i,lfi(i)) = 1;gh(dK+i) = fT(i); end; A = [K N';N zeros(nf,nf)];B = A\gh;tca = B(1:dK); figure;gt =[min(tca) pai max(tca)]; if deb ==1;disp(['L 173, DT isoth gt : ',num2str(gt),' K']);end nc3 = (nci)^2; % nc3 = numb elem / patch, same for all the patches if deb ==1;disp( 'L 175, Call function: gra_ipa');end for i = 1 : np</pre>
172 172 173 174 175 176 177 178 179 180 181 182 183 184 185 186 187 188 189 190 191 192	<pre>disp(['1 170, unicol FgY : ', num2str(Fsky',3)]) disp(['L 172, sum(F,2) : ', num2str(Fsky',3)]) end end end end end end end end end if Me == 1 % Solution of linear steady state heat transfer problems nf = size(lfi,2); N = zeros(nf,dK);% L. con. fix.%gh=zeros(nf,1); for i = 1:nf;N(i,lfi(i)) = 1;gh(dK+i) = fT(i); end; A = [K N';N zeros(nf,nf)];B = A\gh;tca = B(1:dK); figure;gt =[min(tca) pai max(tca)]; if deb ==1;disp(['L 173, DT isoth gt : ',num2str(gt),' K']);end nc3 = (nci)^2; % nc3 = numb elem / patch, same for all the patches if deb ==1;disp('L 175, Call function: gra_ipa');end for i = 1 : np</pre>
172 172 173 174 175 176 177 178 179 180 181 182 183 184 185 186 187 188 189 190 191 192 193	<pre>disp(['L 171, unicol Fgky : ',num2str(Fgky',3)]) disp(['L 171, unicol Fgky : ',num2str(Fgky',3)]) end end end end end end end end end if Me == 1 % Solution of linear steady state heat transfer problems nf = size(lfi,2); N = zeros(nf,dK);% L. con. fix.%gh=zeros(nf,1); for i = 1:nf;N(i,lfi(i)) = 1;gh(dK+i) = fT(i); end; A = [K N';N zeros(nf,nf)];B = A\gh;tca = B(1:dK); figure;gt = [min(tca) pai max(tca)]; if deb ==1;disp(['L 173, DT isoth gt : ',num2str(gt),' K']);end nc3 = (nci)^2; % nc3 = numb elem / patch, same for all the patches if deb ==1;disp( 'L 175, Call function: gra_ipa');end for i = 1 : np</pre>
172 173 174 175 176 177 178 179 180 181 182 183 184 185 186 187 188 189 190 191 192 193 194	<pre>disp(['L 171, unicol FgY : ',num2str(FgKy',3)]) disp(['L 171, unicol FgY : ',num2str(FgKy',3)]) end end end end end end end if Me == 1 % Solution of linear steady state heat transfer problems nf = size(lfi,2); N = zeros(nf,dK);% L. con. fix.%gh=zeros(nf,1); for i = 1:nf;N(i,1fi(i)) = 1;gh(dK+i) = fT(i); end; A = [K N';N zeros(nf,nf)];B = A\gh;tca = B(1:dK); figure;gt =[min(tca) pai max(tca)]; if deb ==1;disp(['L 173, DT isoth gt : ',num2str(gt),' K']);end nc3 = (nci)^2; % nc3 = numb elem / patch, same for all the patches if deb ==1;disp( 'L 175, Call function: gra_ipa');end for i = 1 : np</pre>
172 173 174 175 176 177 178 179 180 181 182 183 184 185 186 187 188 189 190 191 192 193 194 195	<pre>disp(['L 17], unicol Fsky : ',num2str(Fsky',3)]) disp(['L 172, sum(F,2) : ',num2str(Fsky',3)]) end end end end if Me == 1 % Solution of linear steady state heat transfer problems nf = size(lfi,2); N = zeros(nf,dK);% L. con. fix.%gh=zeros(nf,1); for i = 1:nf;N(i,lfi(i)) = 1;gh(dK+i) = fT(i); end; A = [K N';N zeros(nf,nf)];B = A\gh;tca = B(1:dK); figure;gt =[min(tca) pai max(tca)]; if deb ==1;disp(['L 173, DT isoth gt : ',num2str(gt),' K']);end nc3 = (nci)^2; % nc3 = numb elem / patch, same for all the patches if deb ==1;disp( 'L 175, Call function: gra_ipa');end for i = 1 : np % Loop on CAD patches gra_ipa(nci,nci,lK((i-1)*nc3+1:nel,:),tca,xyz,gt);hold on end axis equal;colorbar;axis off title (['Dissipation: ',num2str(.5*tca'*K*tca,3),' WK, DOF: ', num2str(dK),' ']) for i = 1:nbo % Drawing the border of the domain if bor(i,4)==0</pre>
172 173 174 175 176 177 178 179 180 181 182 183 184 185 186 187 188 189 190 191 192 193 194 195 196	<pre>disp(['L 17], unicol Fsky : ',num2str(Fsky',3)]) disp(['L 172, sum(F,2) : ',num2str(Fsky',3)]) end end end end if Me == 1 % Solution of linear steady state heat transfer problems nf = size(lfi,2); N = zeros(nf,dK);% L. con. fix.%gh=zeros(nf,1); for i = 1:nf;N(i,lfi(i)) = 1;gh(dK+i) = fT(i); end; A = [K N';N zeros(nf,nf)];B = A\gh;tca = B(1:dK); figure;gt =[min(tca) pai max(tca)]; if deb ==1;disp(['L 173, DT isoth gt : ',num2str(gt),' K']);end nc3 = (nci)^2; % nc3 = numb elem / patch, same for all the patches if deb ==1;disp( 'L 175, Call function: gra_ipa');end for i = 1 : np % Loop on CAD patches gra_ipa(nci,nci,lK((i-1)*nc3+1:nel,:),tca,xyz,gt);hold on end axis equal;colorbar;axis off title (['Dissipation: ',num2str(.5*tca'*K*tca,3),' WK, DOF: ', num2str(dK),' ']) for i = 1:nbo % Drawing the border of the domain if bor(i,4)==0</pre>
172 172 173 174 175 176 177 178 179 180 181 182 183 184 185 186 187 188 189 190 191 192 193 194 195 196 197	<pre>disp(!'L 170, unicol Fsky : ',num2str(Fsky',3)]) disp(['L 172, sum(F,2) : ',num2str(Fsky',3)]) end end end end if Me == 1 % Solution of linear steady state heat transfer problems nf = size(lfi,2); N = zeros(nf,dK);% L. con. fix.%gh=zeros(nf,1); for i = 1:nf;N(i,lfi(i)) = 1;gh(dK+i) = fT(i); end; A = [K N';N zeros(nf,nf)];B = A\ghtytca = B(1:dK); figure;gt =[min(tca) pai max(tca)]; if deb ==1;disp(['L 173, DT isoth gt : ',num2str(gt),' K']);end nc3 = (nci)^2; % nc3 = numb elem / patch, same for all the patches if deb ==1;disp(['L 175, Call function: gra_ipa');end for i = 1 : np gra_ipa(nci,nci,lK((i-1)*nc3+1:nel,:),tca,xyz,gt);hold on end axis equal;colorbar;axis off title (['Dissipation: ',num2str(.5*tca'*K*tca,3),' WK, DOF: ', num2str(dK),' ']) for i = 1:nbo % Drawing the border of the domain if bor(i,4)==0 plot([xyz(bor(i,1),1) xyz(bor(i,2),1)], [xyz(bor(i,1),2) xyz(bor(i,2),2)],'k','LineWidth',2) end end % End drawing of the isotherms disp(['L 188, Total dissip.: ',num2str(tca'*K*tca/2,3),' WK'])</pre>
171 172 173 174 175 176 177 178 179 180 181 182 183 184 185 186 187 188 189 190 191 192 193 194 195 196 197 198	<pre>disp(['L 170, unicol Fsky : ',num2str(Fsky',3)]) disp(['L 172, sum(F,2) : ',num2str(Fsky',3)]) end end end end end if Me == 1 % Solution of linear steady state heat transfer problems nf = size(lfi,2); N = zeros(nf,dK);% L. con. fix.%gh=zeros(nf,1); for i = 1:nf;N(i,1fi(i)) = 1;gh(dK+i) = fT(i); end; A = [K N';N zeros(nf,nf)];B = A\gh;tca = B(1:dK); figure;gt =[min(tca) pai max(tca)]; if deb ==1;disp(['L 173, DT isoth gt : ',num2str(gt),' K']);end nc3 = (nci)^2; % nc3 = numb elem / patch, same for all the patches if deb ==1;disp( 'L 175, Call function: gra_ipa');end for i = 1 : np gra_ipa(nci,nci,lK((i-1)*nc3+1:nel,:),tca,xyz,gt);hold on end axis equal;colorbar;axis off title (['Dissipation: ',num2str(.5*tca'*K*tca,3),' WK, DOF: ', num2str(dK),' ']) for i = 1:nbo  % Drawing the border of the domain if bor(i,4)==0</pre>
172 173 174 175 176 177 178 179 180 181 182 183 184 185 186 187 188 189 190 191 192 193 194 195 196 197 198 199	<pre>disp(['L 17], unicol Fsky : ',num2str(Fsky',3)])     disp(['L 172, sum(F,2) : ',num2str(Fsky',3)])     end end end end end if Me == 1 % Solution of linear steady state heat transfer problems nf = size(lfi,2); N = zeros(nf,dK);% L. con. fix.%gh=zeros(nf,1); for i = 1:nf;N(i,lfi(i)) = 1;gh(dK+i) = fT(i); end; A = [K N';N zeros(nf,nf)];B = A\gh;tca = B(1:dK); figure;gt =[min(tca) pai max(tca)]; if deb ==1;disp(['L 173, DT isoth gt : ',num2str(gt),' K']);end nc3 = (nci)^2; % nc3 = numb elem / patch, same for all the patches if deb ==1;disp( 'L 175, Call function: gra_ipa');end for i = 1 : np % % Loop on CAD patches gra_ipa(nci,nci,lK((i-1)*nc3+1:nel,:),tca,xyz,gt);hold on end axis equal;colorbar;axis off title (['Dissipation: ',num2str(.5*tca'*K*tca,3),' WK, DOF: ',</pre>
172 173 174 175 176 177 178 179 180 181 182 183 184 185 186 187 188 189 190 191 192 193 194 195 196 197 198 199 200	<pre>disp(['L 17], unicol Fsky : ',num2str(Fsky',3)])</pre>
172 173 174 175 176 177 178 179 180 181 182 183 184 185 186 187 188 189 190 191 192 193 194 195 196 197 198 199 200 201	<pre>disp(['L 17], unicol Fgky : ',num2str(Fgky',3)])     disp(['L 17], unicol Fgky : ',num2str(Fgky',3)])     disp(['L 172, sum(F,2) : ',num2str(sum(F,2)',3)])     end end end end end end end end end if Me == 1 % Solution of linear steady state heat transfer problems nf = size(lfi,2); N = zeros(nf,dK);% L. con. fix.%gh=zeros(nf,1); for i = 1:nf;N(i,lfi(i)) = 1;gh(dK+i) = fT(i); end; A = [K N';N zeros(nf,nf)];B = A\gh;tca = B(1:dK); figure;gt =[min(tca) pai max(tca)]; if deb ==1;disp(['L 173, DT isoth gt : ',num2str(gt),' K']);end nc3 = (nci)^2; % nc3 = numb elem / patch, same for all the patches if deb ==1;disp(['L 175, Call function: gra_ipa');end for i = 1 : np gra_ipa(nci,nci,lK((i-1)*nc3+1:nel,:),tca,xyz,gt);hold on end axis equal;colorbar;axis off title (['Dissipation: ',num2str(.5*tca'*K*tca,3),' WK, DOF: ', num2str(dK),' ']) for i = 1:nbo % Drawing the border of the domain if bor(i,4)==0 plot([xyz(bor(i,1),1) xyz(bor(i,2),1)], [xyz(bor(i,1),2) xyz(bor(i,2),2)],'k','LineWidth',2) end end % End drawing of the isotherms disp(['L 188, Total dissip:: ',num2str(da'*K*tca/2,3),' WK']) % disp(['L 188, Total dissip: ',num2str(dissol,3),' WK']) dissol = .5*tca(1:no)*KK(1:no,1:no)*tca(1:no); disp(['L 192, DT in solid: ',num2str(dissol,3),' WK']) </pre>

203 if deb==1;disp(['L 197, tca mi.ma.av.: ',... 204 num2str([min(tca) max(tca) mean(tca)],3), ' K']);end 205 if nvn > 2;disp(['L 226, DT. convect : ',.. 응 206 응 num2str(max(tca(lic))-min(tca(lic)),3),' K']) 207 응 % End standard linear heat transfer process end 208 reac = K\*tca: if nf < 6209 210 disp(['L 201, Fixed DOF : ',num2str(lfi)]) disp(['L 202, Imposed temp.: ',num2str(tca(lfi)',3),' K']) disp(['L 203, React. flows : ',num2str(reac(lfi)',3),' W']) 211 212 213 end 214 disp(['L 205, End Me=1, CPU: ',num2str(toc(CPU),3),' sec. ']) if deb ==1;disp('L 168-207, End stationary linear');end 215 216 end if Me == 2 % Non linear stat. rad. heat transfer - conv. like virtual node 217 % nnr is the number of radiative virtual nodes 218 if nnr > 0 if deb ==1;disp('L 217, Call function: ..... fem snl .....');end 219 220 tca=fem snl(K,gh,lfi,fT,xyz,lK,lcont,nnr,nvn,nci,np,SB\*(1-re)); disp(['L 215, End Me=2, CPU: ',num2str(toc(CPU),3),' sec. ']) 221 end 222 223 if deb ==1;disp('L 208-215, End non lin virt rad node.');end 224 end if Me == 3  $\,\,\%\,$  ...... Solution of transient linear heat transfer problems 225 226 if deb==1;disp ('L 224, Call function: ..... fem\_til .....');end 227 [tca]=fem til(np,xyz,lK,dK,nci,deb,rc,cs,re,area,th,pai,fT,lfi,gh,... 228 nbo,bor,K,Gi); disp(['L 231, End Me=3. CPU: ',num2str(toc(CPU) ,3),' sec. '])
if deb ==1;disp('L 216-222, End linear transient');end 229 230 231 end 232 if Me == 4 % Solution of non linear transient rad. heat transfer problems disp(['L 233, Num. fix. DOF: ',num2str(lfi)]) 233 disp(['L 234, T. fix. nod. : ',num2str(fT),' K']) 2.34 if deb==1,disp('L 234, Call function: ..... fem tir .....');end 235 236 e S Ftot = zeros(size(lcont, 1) -1, size(lcont, 1) +1); 237 [tca] = fem tir(np,xyz,lK,dK,nci,deb,rc,ra,cs,area,th,xyz cao,... 238 gh,lfi,fT,Tsky,nbo,bor,K,Lel,re,SB\*th\*(1-re),lcont,Ms,pai,F,lon); 239 rea = Kk\*tca;reac = K\*tca; 240 disp(['L 240, Diss in solid: ',num2str(rea' \*tca/2,3),' WK']) disp(['L 240, Diss in solid. , num2st(rea 'ca/2,3), 'wK']) disp(['L 241, Total dissip.: ',num2str(reac'\*tca/2,3),' WK']) disp(['L 242, End Me=4. CPU: ',num2str(toc(CPU) ,3),' sec. ']) 241 242 test=SB\*280^4\*th\*3; 243 2 244 if deb ==1;disp('L 232-245, End non lin radiat. trans. H.T.');end 245 end %End of Fiammetta for non linear transient rad. heat transfer problems % Cavity with view factor matrix and radiative exchanges 246 if Me == 5 Mpr = zeros(nbo\*nci, nbo\*nci);% if cs~=2;Ms = zeros(nbo\*nci, 1);end 247 248 if rc > 0249 if re ==1 250 Mpr = eye(size(Fs,1),size(Fs,1)); 251 % if re = 0 : black body, Mpr+Fs = I else Mpr =(eye(size(Fs,1),size(Fs,1))-Fs)\*M^(-1); 252 253 end 254 end 255 ŝ if nni < 4 disp(['L 242, Line clos. Fs: ',num2str(sum(Fs ))]) 256 8 disp(['L 243, Col. clos. Fs: ',num2str(sum(Fs,2)')]) 257 8 disp(['L 244, sum(sum(Fs)) : ',num2str(sum(sum(Fs)))])
disp(['L 245, Line clos. M : ',num2str(sum(M ))]) 258 ŝ 259 양 disp(['L 246, Col. clos. M : ',num2str(sum(M,2)')]) 260 2 261 ÷ end if deb==1;disp('L 248, Call function: ..... fem tit .....');end 262 263 [tca] = fem tit(np,xyz,lK,dK,nci,deb,rc,cs,nel,area,bos,... gh,fT,lfi,nbo,bor,Kk,mcr,Lel,SB,re,Mpr,Ms,lcont,pai,th); 264 265 if rc > 0266 gsm = Kk\*tca; 267 figure ( 'Position', [100 100 800 300]); bar(gsm(lcont)'); grid on title (['Emittance: ', num2str((1-re),2),...
', resultant = sum(gsm(lcont)): ',... 268 269 270 num2str(sum(gsm(lcont)),2),' W']);hold on 271 ylabel ( 'Radiative loads Kk\*tca (W)') 271 disp(['L 271, Resultant fl.: ',num2str(sum(gsm(lcont)),2),' W']) 273 end 274 disp(['L 272, End Me=5. CPU: ',num2str(toc(CPU),3),' sec. ']) 275 if deb ==1;disp('L 244-274, End cavity, view factors, rad exch.');end 276 end

*Table 58: Matlab<sup>©</sup> procedure Fiammetta 20211111.m* 

	Line	Occ.	Name	Meaning of the variables used in the procedure <i>Fiammetta.m</i>
	1	19	deb	Flag to control the display of functions calls
	1	3	Neu	Flag to control the von Neumann boundary conditions
	1	6	pr	Uni-line matrix to control the procedure Fiammetta
	1	3	rae	Flag indicating the use of conductive radiative elements
1	4	7	nbo	Input data: Number of CAD patches interfaces
2	4	13	cs	View factor matrix flag: 1 = cavity, 2 = street, 3 = thermal bridge
3	7	6	np	Number of CAD patches
4	8	3	npv	Number of CAD vertices
5	8	9	area	Area of the solid domain $m^2$ , computed in <i>lines 9 - 18</i>
6	22	9	nni	Number of nodes per side of CAD patches
7	23	11	nci	Number of elements per side of CAD patches
8	24	8	nnv	Number of virtual convection nodes
9	25	5	nnr	Number of virtual radiative nodes
10	25	6	rc	Flag indicating presence of radiative exchange $(1 = yes, 0 = no)$
12	29	6	th	Thickness, <i>m</i>
13	30	2	k	Conductivity coefficient $Wm^{-1}K^{-1}$
15	31	4	SB	Stefan-Boltzmann constant: 5.6704 10 <sup>-8</sup> Wm <sup>-2</sup> K <sup>-4</sup>
19	33	4	pai	Temperature interval in isotherms drawing $K$
16	34	16	lK	Localization matrix of conductive elements (dimension: <i>nel</i> x 4)
17	36	7	nel	Number of conductive elements
	37	14	no	Number of nodes of the mesh
20	38	10	ndK	Number of <i>DOF</i>
18	44	4	pe	Perimeter of the domain, m
	70	11	xyz	Matrix of the nodal coordinates expressed in 3D, $m$
	73	10	lfi	Uni-column matrix - list of fixed nodes (Dirichlet), ( <i>cad_Dir.m</i> )
	73	4	fT	Uni-column matrix of fixed nodal temperatures, ( <i>cad_Dir.m</i> )
	73	2	nfi	Number of fixations (dim of <i>fT</i> & lfi), ( <i>cad_Dir.m</i> )
	75	5	gh	Weight functions of patch side loads (see <i>lines 117 - 126</i> )
29	80	3	h	Reference convection coefficient $Wm^{-2}K^{-1}$
30	82	3	he	Uni-line matrix of the element convection coefficients
31	82	6	lc	Localizations of convective elements defined in <i>cad_con.m</i>
23	85	5	mcr	Number of radiative nodes, size(lcont,1)
21	88	6	lcont	Uni-column matrix of <i>mcr</i> radiative cavity, street, balcony nodes
22	88	5	lv	Uni-column matrix of cavity, street, balcony vertices
33	93	6	Kk	Global conductivity matrix of meshed solid domain <i>WK</i> <sup>-1</sup>

	94	2	со	Uni-line matrix of the <i>nel</i> products of thickness by cond. coeff. $k$
34	97	2	Kel	Element conductive matrix <i>WK</i> <sup>-1</sup> ( <i>fem_Kco.m</i> )
35	102	8	K	Global conductivity matrix $WK^{-1}$ (solid part +)
46	106	2	Kec	Element "conductive – convective" matrix <i>WK</i> <sup>-1</sup> ( <i>fem_Kcv.m</i> )
36	112	6	re	Coefficient of reflexion (adimensional)
37	113	5	ns	Number of edges of the radiative part of the boundary
38	113	7	lcc	Sequence of cavity CAD vertices + first repeated if cavity
39	121	6	Lel	Uni-column matrix of the $ns$ radiative edges' lengths $m$
42	127	7	Fs	View factor matrix for radiative element from mesh border
43	132	6	Fsky	Uni-column matrix of sky view factors for street & balcony
	137	5	F	Thermal bridge view factor matrix including mesh, sky, ground
	137	9	nf	Size of view factor matrix for thermal bridge
	164	3	Fgr	Uni-column matrix of ground view factors
	139	2	Ftot	[Fs Fsky Fgr]
44	136	9	М	Radiosity matrix (adimensional)
	146	2	Mm1	$M^{I}$
45	147	2	M_pr	(1 - Fs) $M^{-1}$ matrix - flow out of a segment (adim.)
	180	26	tca	Uni-column of the <i>dK DOF</i> or nodal temperatures
41	181	3	gt	Uni-line matrix for isolines definition in gra_ipa.m
	171	3	Kr	Conductivity global matrix due to radiative exchanges

Table 59: Variables used in the procedure Fiammetta.m

Solution of the system.

To allow introducing fixations anywhere in the mesh, it is convenient to group all the fixed DOF at the end of the conductivity matrix.

A simple method to do it is:

Examine all the *DOF* from the first one present in the K matrix. If a *DOF* is fixed, swap it with the last free *DOF* of the matrix. This operation needs:

- 1. a swapping of the lines,
- 2. a swapping of the columns
- 3. a swapping of the heat loads,

After this operation, the system is easily solved, using the matrix decomposition:

$\int K_{11}$	$K_{12} \left[ T_1 \right] \left[ 0 \right]$	(108)
$K_{21}$	$K_{22} \rfloor \lfloor T_2 \rfloor^{-} \lfloor ? \rfloor$	()

When the system is solved, it is necessary to swap back the temperature vector.

*Lines* 32 - 33: Output. The last lines of the procedure are devoted to the output, basically temperature levels drawing by using the Matlab<sup>©</sup> standard function *fill* function (*Figure 6*). Another solution is obtained in *Figure 8* with the Matlab<sup>©</sup> function *gra\_ipa.m* of *Table 69* or the function *gra ist.m* given in *Table 3*.

To solve a steady state heat transfer problem, we have to fix at least one node to take out the singularity of the problem (this action is setting the level of temperature). To obtain a non-uniform temperature field, at least another node has to be fixed at a different temperature or at least one second member term has to be introduced on any node different from the fixed one. All the nodes are concerned with this rule.

With both imposed temperatures ( $T_2$ , in red) and prescribed heat fluxes ( $F_1$ , in red), the system to be solved is characterized by 4 submatrices. The unknown variables are the vectors [ $T_1$ ] and [ $F_2$ ] (in blue)

$$\begin{bmatrix} K \end{bmatrix} = \begin{bmatrix} K_{11} & K_{12} \\ K_{21} & K_{22} \end{bmatrix} \quad ; \quad \begin{bmatrix} K \end{bmatrix} \begin{bmatrix} T_1 \\ T_2 \end{bmatrix} = \begin{bmatrix} F_1 \\ F_2 \end{bmatrix}$$
(109)

The system to be solved is:

$$[T_1] = [K_{11}]^{-1} \{ [F_1] - [K_{12}] [T_2] \}$$
(110)

Finally, the fluxes are calculated in the following operation:

$$\begin{bmatrix} F_2 \end{bmatrix} = \begin{bmatrix} K_{21} & K_{22} \end{bmatrix} \begin{bmatrix} T_1 \\ T_2 \end{bmatrix} = \begin{bmatrix} K_{21} & K_{22} \end{bmatrix} \begin{bmatrix} \begin{bmatrix} K_{11} \end{bmatrix}^{-1} \{ \begin{bmatrix} F_1 \end{bmatrix} - \begin{bmatrix} K_{12} \end{bmatrix} \begin{bmatrix} T_2 \end{bmatrix} \}$$
(111)

We proceed with a very simple case with imposed temperatures on the lower face (base) and a constant flow on the left vertical edge (*Figure 9*). The mesh has 20 x 40 elements. As the upper and right faces are adiabatic, the isotherms are orthogonal to them. The base temperature is fixed to 270 K. The total flow on the left side is equal to 40 W.

In computing the second member of the system of equations, there is ambiguity for the node of the lower left corner that receives a flux of 20/ny W, but is fixed. The dissipation energy is obtained by pre- and post- multiplying the global conduction matrix by the temperature vector:

$$\frac{1}{2} \left[ T \right]^T \left[ K \right] \left[ T \right] \tag{112}$$

When the mesh is refined, this energy is converging to its exact value of  $651 \ WK$  (in this example, the convergence is yet achieved with the 20 x 40 mesh [Beckers & Beckers 2015]).
# 8.2 Transient heat transfer problem

	Function <i>fem_tit.m</i> - cavity, VF matrices, radiative transfers
1	<pre>function[tca] =</pre>
2	<pre>fem_tit(np,xyz,lK,dK,nci,deb,rc,cs,nel,area,bos,gh,</pre>
3	fT, lfi, nbo, bor, Kk, mcr, Lel, SB, re, Mpr, Ms, lcont, pai, th)
4	<pre>tml = 280;dlsp[('Lt 04, Initial temp.: ',num2str(tml) ,' K']) teep = energidy[)temi.</pre>
5	nit = 72 · dthe1 · dtdenit/2·
7	dti = dth*3600:disp(['Lt 07. Time step : '.num2str(dti).' sec'])
8	tt = dti*nit; % Analyzed period in seconds
9	<pre>disp(['Lt 09, Analyzed per.: ',num2str(tt/3600) ,' h, ',</pre>
10	num2str(tt/3600/24) ,' days'])
11	nd = tt/3600/24;f=zeros(1,tt/3600); % nd = number of days
12	for i = 1:nd % f is the imposed periodic function, f(h = 1:12)
13	f((1-1)*24+1:(1-1)*24+12) = sin((1:12)*p1/12);
14	$Cn = 1000 : disn(['Lt 15, Spec_capac_t', num2str(Cn), ', J/(kg K)']):$
16	ro = 2500 ; disp(['Lt 16, Spec. mass : ',num2str(ro), 'kg.m-3'])
17	C = zeros(dK,dK); % Initialization of the global capacity matrix
18	% C(ndK,ndK) = 1; % Capacity of the fluid virtual node Jkg-1K-1
19	<pre>if deb==1;disp('Lt 19, Call function: fem_Cae');end</pre>
20	<pre>for n = 1:nel % Glob. capacity mat. assemb., loop on nel elements</pre>
21	Cae = fem_Cae(xyz, LK(n,:))*th*Cp*ro; % Element capacity matrix
22	10r I = 1.4
2.4	C([K(n,i), ]K(n,i)) = C([K(n,i), ]K(n,i)) + Cae(i,i);
25	end
26	end
27	end % End of capacity matrices assembling
28	<pre>cap = area*th*Cp*ro*1e-6; % Domain capacity comp. from mat. data</pre>
29	disp(['Lt 29, sum(sum(C)) : ',num2str(sum(sum(C))*le-6), 'MJ/K'])
31	<pre>&gt; disp([ ht s0, area*th*10*tp: , humzstr(cap), M0/K ]); ze = ones(1.nit+1)*tmi:tsmax=ze:tsmin=ze:tmov=ze:% tcav=ze:</pre>
32	<pre>qa = zeros(1,nit+1); gou = zeros(1,nit+1);</pre>
33	<pre>% tca = zeros(ndK,1);% gtot = 0.;</pre>
34	ih = 0;% 0;% 4.04008;% % Imposed heat load in Wm-2
35	<pre>disp(['Lt 35, Ampl inp heat: ',num2str(ih), 'Wm-2'])</pre>
36	% gt = [tmi pai tma]; % gt = [min(tcan) pai max(tcan)]
38	1162 - HEIMHEI; * Willber of Hodes III a CAD patch
39	sif $cs=2;bos=(xyz, cao(2,1)+xyz, cao(7,1)-xyz, cao(1,1)-xyz, cao(8,1)) * th; end$
40	K = Kk; ip=0; % Conduct. matrix related to solid and convective part
41	<pre>lon = ones(1,4*nci)/nci; % Valid only for the square cavity</pre>
42	<pre>% if rc*cs == 1;sn = 0;end % Cavity</pre>
43	if rc*cs == 2 % Radiation in the street section (3 sides)
44	$= (mer_{-1})/3;$
46	for i = 1:nre % Computing the element lengths on the 3 sides
47	lon(i) = Lel(1)/(nne); lon(mcr-i) = Lel(3)/(nne);
48	lon(i+nne) = Lel(2)/(nne);
49	end
50	end % It is important to observe that: sum(esm) = sum(sn)
51	if rc*cs == 3 % Radiation around the thermal bridge - 5 segments
52 53	for k = 1.5: for i = 1:nci:n = n+1:lon(n) = Lel(k)/(nci): end:end:
54	end % It is important to observe that: sum(esm) = sum(sn)
55	<pre>if mcr &lt;10;disp(['Lt 54, lon : ',num2str(lon) ,' m']);end</pre>
56	<pre>disp(['Lt 55, Radiat. area : ',num2str(sum(lon)*th),' m2'])</pre>
57	
58	<pre>% Loop on the time ierations</pre>
59 60	Mn = zeros(ak,1); for it = 1.nit & Loop on time iterations step
61	if rc == 1 % Add radiative matrix Kr to conductive matrix Kk
62	<pre>if cs ==1;[Kr] = fem caK(tcan,re,SB*th*(1-re),Mpr,it,lcont,Lel/nci);</pre>
63	K(lcont,lcont) = Kk(lcont,lcont) + Kr(lcont,lcont); end
64	if $cs > 1$
65	if it==1
66	<pre>if deb==1;disp('Lt 61, Call function: fem rsm');end disp([]]t 62 _ gum(Mg)</pre>
62 62	end
69	[Mn] = fem rsm(tcan,re,SB*th,Mpr,it,Ms,lcont,lon,dK);
70	<pre>if it==1;disp(['Lt 64, sum(Mn) : ',num2str(sum(Mn),4),' W']);end</pre>
71	end
72	<pre>end % Injected heat = weights * periodic function f(t)* load * area</pre>

g = gh \* f(it) \* ih \* bos; if rc > 0;g(lcont) = g(lcont);end 73 % Injected heat 74 % Heat coming from sky ga(it+1) = sum(g)\*dti; % Heat input at step it (for statistics) 75 76 = ip+1; if lfi(1) == 0; nfi=0; else; nfi=size(lfi,2); end ίp if nfi 77 == 0 % Domain without fixations =  $(C + dti^K) \setminus (C^tcan + dti^g + Mn);$ 78 tca % Equation 68 ?? 79 else % Domain including some fixations == 1; tcan(lfi) = fT; end if it 80 81 % Second member of the system 82 83 gou(it) = sum(go(lfi))\*dti; % Outgoing heat at iteration it 84 end % tcav (it+1) = tca (ndK,1); tsmax(it+1) = max (tca);85 86 tsmin(it+1) = min(tca);tmoy (it+1) = mean (tca); %(tsmin(it+1)+tsmax(it+1))/2; 87 = tca; 88 tcan 89 if ip == dtd % In this iteration, isotherms drawing is generated 90 ip = 0; gt = [min(tca) pai max(tca)]; disp(['Lt 79, iteration : ',num2str(it)])
if deb==1;disp ('Lt 80, Call function: .... gra\_ipa .....');end; 91 92 93 figure 94 a=-.2;b=-.1;ha=max(xyz(:,2));ti=299;ta=300;%..drawing a left bar S 95 S fill([a b b a],[0 0 ha ha],[ti ti ta ta]);hold on; 96 for i = 1 : np % ..... Loop on the np CAD patches 97 gra ipa(nci,nci,lK((i-1)\*nc2+1:i\*nc2,:),tca',xyz,gt); 98 colorbar; hold on 99 end xlabel(['Lt 88 : ',num2str([max(tca) min(tca)])]);hold on 100 101 axis equal; axis off 102 for i = 1:nbo % ..... Drawing the border of the domain 103 if bor(i, 4) == 0104 plot([xyz(bor(i,1),1) xyz(bor(i,2),1)], ... 105 [xyz(bor(i,1),2) xyz(bor(i,2),2)],'k','LineWidth',2) 106 end 107 108 109 end 110 end % ..... ..... End of time iterations ddt = tmoy(nit+1)-tmi;ah = ddt\*cap; % Stored heat: ah=DT\*area\*th\*ro\*Cp 111 disp(['Lt108, Tmean - Tini : ',num2str(ddt,3),' K'])
disp(['Lt109, Min obs. temp: ',num2str(min(tsmin),3),' K']) 112 113 disp(['Lt110, Max obs. temp: ',num2str(max(tsmax),3),' K']) disp(['Lt111, Final temper.: ',num2str([tsmin(nit+1) tmoy(nit+1)... 114 115 116 tsmax(nit+1)],3)]) disp(['Lt113, Capac \* Del T: ',num2str(ah ,3),' MJ'])
if deb==1;disp('Lt114, Call function: ..... gra\_tev .....');end 117 118 gra tev(nit,tt,re,tsmax,tsmin,tmoy) % Drawing temp. evolution 119 120 if deb == 1;disp( 'Lt116, Call function: ..... gra hie .....');end 121 % Drawing heat input evolution % gra\_hie(nit,tt,ga) 122 hdm = tt\*ih/pi\*bos\*1e-6; % Explicit exact injected heat Equ. (80) pp 49 123 disp(['Lt119, Injected heat: ',num2str(sum(ga)/1.e06,3),' MJ']) if ih ~= 0;disp(['Lt120, Exact ih x 30: ',num2str(hdm,3),' MJ']);end 124 hfi > 0 % Results shown & displayed only in presence of fixations disp(['Lt122, ejected heat : ',num2str(sum(gou)\*1.e-6,3),' MJ']) 125 if nfi > 0 126 127 figure('Position',[100 100 700 300]); 128 plot(gou(1:it));grid on;hold on title(['Total ejected heat: ',num2str(sum(gou),4),' J'],... 129 'fontsize',15);hold on 130 131 ylabel('Ejected heat (J)','fontsize',15);hold on end 132 133 end

*Table 60: Matlab<sup>©</sup> function fem\_tit.m – Cavity, VF matrices, radiative transfers* 

	Line	Occ.	Name	Meaning of the variables used in the function <i>fem_tit.m</i>
In	2	2	np	Number of patches
In	2	7	xyz	Matrix of the 3D nodal coordinates expressed in, $m$
In	2	7	lK	Localization matrix of conductive elements (dimension: <i>nel</i> x 4)
In	2	8	ndK	Number of <i>DOF</i>
In	2	9	nci	Number of elements per patch edge

In24debFlag enabling the display of function callIn24rcFlag indicating presence of radiative exchanges $(1 = yes, 0 = no)$ In28csFlag for view factor matrix: $1 = cavity, 2 = street, 3 = balcony$ In22nelNumber of conductive elementsIn23areaArea of the solid domain $m^2$ In210thThickness, $m$ In25xyz_cao((Num. patch vert.) x 2) matrix of coordinates of patches verticesIn22ghUni-column matrix of flow input distribution ( $cad\_Neu.m$ )In33nfiNumber of fixed nodesIn39fTIf nfi > 0, uni-column matrix of fixed nodal temperatures KIn32paiTemperature interval in isotherms drawing K
In24rcFlag indicating presence of radiative exchanges $(1 = yes, 0 = no)$ In28csFlag for view factor matrix: $1 = cavity, 2 = street, 3 = balcony$ In22nelNumber of conductive elementsIn23areaArea of the solid domain $m^2$ In210thThickness, $m$ In25xyz_cao((Num. patch vert.) x 2) matrix of coordinates of patches verticesIn22ghUni-column matrix of flow input distribution ( $cad_Neu.m$ )In33nfiNumber of fixed nodesIn39fTIf nfi > 0, uni-column matrix of fixed nodal temperatures KIn32paiTemperature interval in isotherms drawing K
In28csFlag for view factor matrix: $1 = cavity, 2 = street, 3 = balcony$ In22nelNumber of conductive elementsIn23areaArea of the solid domain $m^2$ In210thThickness, $m$ In25xyz_cao((Num. patch vert.) x 2) matrix of coordinates of patches verticesIn22ghUni-column matrix of flow input distribution ( $cad_Neu.m$ )In33nfiNumber of fixed nodesIn39fTIf nfi > 0, uni-column matrix of fixed nodal temperatures KIn35lfiList of fixed nodes on a side (Dirichlet), ( $cad_Dir.m$ )In32paiTemperature interval in isotherms drawing K
In22nelNumber of conductive elementsIn23areaArea of the solid domain $m^2$ In210thThickness, $m$ In25xyz_cao((Num. patch vert.) x 2) matrix of coordinates of patches verticesIn22ghUni-column matrix of flow input distribution ( $cad\_Neu.m$ )In33nfiNumber of fixed nodesIn39fTIf nfi > 0, uni-column matrix of fixed nodal temperatures KIn35IfiList of fixed nodes on a side (Dirichlet), ( $cad\_Dir.m$ )In32paiTemperature interval in isotherms drawing K
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In22ghUni-column matrix of flow input distribution (cad_Neu.m)In33nfiNumber of fixed nodesIn39fTIf nfi > 0, uni-column matrix of fixed nodal temperatures KIn35lfiList of fixed nodes on a side (Dirichlet), (cad_Dir.m)In32paiTemperature interval in isotherms drawing K
In33nfiNumber of fixed nodesIn39fTIf nfi > 0, uni-column matrix of fixed nodal temperatures KIn35lfiList of fixed nodes on a side (Dirichlet), $(cad_Dir.m)$ In32paiTemperature interval in isotherms drawing K
In39fTIf nfi > 0, uni-column matrix of fixed nodal temperatures KIn35lfiList of fixed nodes on a side (Dirichlet), (cad_Dir.m)In32paiTemperature interval in isotherms drawing K
In35IfiList of fixed nodes on a side (Dirichlet), (cad_Dir.m)In32paiTemperature interval in isotherms drawing K
In   3   2   pai   Temperature interval in isotherms drawing K
In 3 2 nbo Number of <i>CAD</i> patches interfaces
In36bormatrices bor and pbo computed in cad_mes.m (Table 15).
In 3 2 no Number of mesh nodes
In 3 2 Kk Global conductivity matrix of meshed solid domain <i>WK</i> <sup>-1</sup>
In 3 9 mcr Number of radiative nodes, <i>size (lcont, l)</i>
In 3 5 Lel Uni-column matrix of the cavity or street section edges lengths <i>m</i>
In 3 2 Fsky Uni-column matrix of sky view factors from street section elements
In 3 2 Fgr Uni-column matrix of ground view factors from street elements
In 3 5 SB Stefan-Boltzmann constant: 5.6704 $10^{-8}$ Wm <sup>-2</sup> K <sup>-4</sup>
In 3 3 re Coefficient of reflexion (adimensional)
In 3 3 M_pr $(I - F) M^{-1}$ matrix for flow outcoming from a segment (adim.)
In 3 7 lcont List of radiative boundary nodes ( <i>cad_ban.m</i> )
1 4 7 tmi Initial temperature (scalar expressed in <i>K</i> )
2 5 8 tcan Nodal temperatures of the solid before starting the iterations
3 6 10 nit Number of iterations for transient analysis
4 6 2 dtd Iteration leading to a drawing
5 7 8 dti Time step in seconds s
6 8 7 tt Analyzed period s
7 11 2 nd Analyzed period in days
8 11 3 f Periodic function expressed in days
9 15 5 $c_p$ Specific capacity $Jkg^{-l}K^{-l}$
10 16 5 ro Specific mass $kgm^{-3}$
11 17 7 C Global capacity matrix in $JK^{-l}$
12 21 2 Cae Element capacity matrix $JK^{-1}$ (fem Cae.m)

13	26	2	cap	Domain heat storage capacity <i>JK</i> <sup>-1</sup>
14	28	5	tmoy	Uni-line vector, mean temperature in solid at each time step $K$
15	28	4	tsmin	Uni-line matrix, lowest temperature in solid at each time step $K$
16	28	4	tsmax	Uni-line matrix, highest temperature in solid at each time step $K$
17	29	4	ga	Uni-line matrix, heat input at each step $sum(g)$ *dti, expressed in J
18	29	16	tca	Uni-column matrix, output of unknown nodal temperatures $K$
19	29	6	gou	Uni-line matrix, outgoing heat at each step
20	31	6	ih	Module of imposed periodic heat flow $Wm^{-2}$
21	33	5	bos	Loaded area, $m^2$
22	37	5	ip	Counter of the iterations in transient analysis
23	42	8	lon	Uni-line matrix of radiative border element lengths <i>m</i>
24	49	7	esm	Element second member linked to sky & ground radiations $W$
25	53	6	sn	Nodal second member linked to sky & ground radiations $W$
26	61	12	it	Time iterations index (end of loop at <i>line 104</i> )
27	62	3	Kr	Radiative matrix added to the conductive one
28	64	4	K	Global conductivity matrix

Table 61: Variables used in the function fem\_tit.m

	Function <i>fem_til.m</i> - solution of linear transient equations
1	function [tca]=
2	fem_til(np,xyz,lK,dK,nci,deb,rc,cs,re,area,th,pai,fT,lfi,gh,nbo,
3	bor, Kk, Gi)
4	tmi = 280; tma=300; nel=size(1K, 1);
5	disp(['t. 05, Initial temp.: ',num2str(tmi),' K'])
6	If $G_1 = 1$ % in the example of figure 41 - 42, non must be even
/	tcan = [ones(round(dk/2),1)^tml; ones(dk-round(dk/2),1)^tma];
8	nil = 0;
10	for $i$ = 1.4
11	$\frac{1}{101} = \frac{1}{101}$
12	$t can(\Pi(I,J)) = tma$
13	end
14	end % nfi = 0:tcan = ones(dK.1)*tmi:
15	else % Initial and fixed temperatures
16	<pre>tcan = ones(dK,1)*tmi; nfi = size(lfi,1); tcan(lfi) = fT;</pre>
17	end
18	<pre>if dK &lt; 5; disp(['t. 18, Initial temp.: ',num2str(tcan'),' K']);end</pre>
19	nit =720;dth=1;dtd=nit/2; % Numb. iter. & delta tau per it. (hours)
20	<pre>disp(['t. 20, nit N. iter.: ',num2str(nit)])</pre>
21	dti = dth*3600;disp(['t. 21, Time step : ',num2str(dti),' s'])
22	tt = dti*nit; % Analyzed period in seconds
23	disp(['t. 23, Analyzed per.: ',num2str(tt/3600) ,' h, ',
24	num2str(tt/3600/24) ,' days'])
25	nd = tt/3600/24;f=zeros(1,tt/3600); % nd = number of days
26	for i = 1:nd % f is the imposed periodic function, f(h = 1:12)
27	f((i-1)*24+1:(i-1)*24+12) = sin((1:12)*pi/12);
28	
29	Cp = 1000; disp(['t. 29, spec. capac. : ',num2str(Cp), 'J/(kg.k)']);
21	$r_{0} = 2500$ (disp((1.30, spec. mass : ',num2str(r_{0}), kg.m-3'))
22	c = zeros(ak,ak); s initialization of the global capacity matrix
32	for n = 1, not set the set of the
37	$G_{2} = f_{2} - f_{2$
35	for $i = 1.4^{-1}$
36	for $i = 1:4:C(1K(n,i), 1K(n,i)) = C(1K(n,i), 1K(n,i)) + Cae(i,i):end$
37	end
38	end % End of capacity matrices assembling

```
cap = area*th*Cp*ro*1e-6;
39
                                           % Domain capcity computed from mat. data
       disp(['t. 40, sum(sum(C)) : ',num2str(sum(sum(C))*1e-6), ' MJ/K'])
40
       disp(['t. 41, area*th*ro*Cp: ',num2str(cap), ' MJ/K']);
tsmax = ones(1,nit+1)*tma; tsmin = ones(1,nit+1)*tmi;
41
42
43
       tmoy = ones(1,nit+1)*tmi ; tcav = tmoy;gou = zeros(1,nit+1);
       ih = 50;% 4.04008;%
44
                                                         % Imposed heat load in Wm-2
       disp(['t. 45, Imposed Heat : ',num2str(ih), ' W/m-2'])
45
       bos = th*(max(xyz(:,1))-min(xyz(:,1)));% Cross section area upper edge
46
              = zeros(dK,1);
47
       q
       if rc*cs== 1; disp('t. 40, Call function: ..... fem caK .....');end
48
            = Kk; ip=0; % Conduct. matrix related to solid and convective part
49
      K
50
      for it = 1:nit % ..... Loop on the time ierations
51
                     = ip+1;
          ip
52
           if cs < 3;g = gh*f(it)*ih*bos; end % Imposed generalized heat flows</pre>
                     == 0
                                          % The problem does not include fixations
53
           if nfi
                       = (C + dti*K) \ (C*tcan + dti*g); % Tutorial, pp 41, Equ. 67
54
              tca
55
           else
                       = fem_tra(K,C,dti,g,lfi,tcan);
56
              tca
                     = K * tca;
57
               go
                                                      % Second member of the system
               gou(it) = sum(go(lfi))*dti;
58
                                                          % Reactions at iteration it
           end
59
60
           tcav (it+1) = tca (dK, 1);
           tsmax(it+1) = max (tca(1:dK-size(lfi,1)));
61
62
           tsmin(it+1) = min (tca(1:dK-size(lfi,1)));
63
           tmoy (it+1) = mean(tca(1:dK-size(lfi,1)));
           tcan = tca;
64
           if ip == dtd
                            % In this iteration, isotherms drawing is generated
65
               ip = 0; gt=[min(tca) pai max(tca)];
66
67
               disp(['t 67, iteration : ',num2str(it)])
               if deb==1;disp ('t 68, Call function: ..... gra ipa .....');end;
68
69
               figure
70
      2
                 ori=min(xvz(:,1))-.2;
71
      8
                  a=ori-.2;b=ori-.1;ha=max(xyz(:,2));
                                                            %.... drawing a left bar
72
                 fill([a b b a],[0 0 ha ha],[280 280 300 300]);hold on;
      ę
73
               for i = 1 : np % ..... Loop on the np CAD patches
74
                    gra_ipa(nci,nci,lK((i-1)*nci^2+1:i*nci^2,:),tca',xyz,gt);
75
                    colorbar; hold on
76
               end
77
               xlabel(['Lt 76 : ',num2str([max(tca) min(tca)])]);hold on
78
               axis equal;axis off
79
               for i = 1:nbo % ..... Drawing the border of the domain
80
                   if bor(i,4) == 0
81
                       plot([xyz(bor(i,1),1) xyz(bor(i,2),1)], ...
                        [xyz(bor(i,1),2) xyz(bor(i,2),2)],'k','LineWidth',2)
82
83
                    end
84
               end % ..... End drawing the border of the domain
85
               title(['Elapsed time : ',num2str(it*dti/3600),' hours']);hold on
86
           end
87
      end % ...
                        ..... End of time iterations
      ddt = tmoy(nit+1)-tmi;ah = ddt*cap; % Stored heat: ah=DT*area*th*ro*Cp
    disp(['t. 89, Tmean - Tini : ',num2str(ddt,3),' K'])
    disp(['t. 90, DT* sumsum(C): ',num2str(ah,3),' MJ'])
88
89
90
91
      if ddt > .1
          disp(['t. 92, Min obs. temp: ',num2str(ceil(min(tsmin)),4),' K'])
disp(['t. 93, Max obs. temp: ',num2str(max(tsmax),4),' K'])
if deb==1;disp('t.110, Call function: .... gra_tev ....');end
gra_tev(nit,tt,re,tsmax,tsmin,tmoy); % tcav(1) = -1;% Temper. evol.
92
93
94
95
96
      end
97
       eih
              = tt*ih/pi*bos*1e-6;
                                                          % Equation (81) of tutorial
      % disp(['t. 96, S&G Heat in : ',num2str(ga*nit,3),' MJ'])
if ih ~= 0;disp(['t. 90, Heat inp.(81): ',num2str(eih,3),' MJ']);end
98
99
      if nfi > 0
                         % Results shown & displayed only in presence of fixations
100
101
           if sum(gou) > 0
               disp(['t.102, Tot. reaction: ',num2str(sum(gou)*1.e-6,3),' MJ'])
102
               figure('Position',[100 100 700 300]);ylabel('(MJ)','fontsize',15);
103
104
               hold on;plot(gou(1:it)/1.e6);grid on;hold on
               title(['Reaction on fixed DOF: ',num2str(sum(gou)/1.e6,3),...
105
                     MJ'], 'fontsize', 15); hold on
106
107
           end
108
      end
109
      end
```

Table 62: Matlab<sup>©</sup> function fem til.m – solution of linear transient equations

Function fem tir.m – solution of non linear transient equations 1 function[tca] = ... 2 fem tir(np,xyz,lK,dK,nci,deb,rc,ra,cs,area,th,xyz cao,gh,lfi,fT,... 3 Tsky, nbo, bor, Kk, Lel, re, SBt, lcont, Ms, pai, Ftot, lon) % SBt = SB\*th\*(1-re) = 280;disp(['t. 04, Initial temp.: ',num2str(tmi) ,' K']) disp(['t. 05, Fixed DOF : ',num2str(lfi)]) 4 tmi 5 6 = size(fT,2);ntca=dK-nfi;tcan = [ones(ntca,1)\*tmi ; fT'];tca = tcan; nfi 7 = zeros(ntca,1);Mn = zeros(size(lcont,1),1); % 2d Memb. sid. to nod. q = 720;dth=1;dtd=nit/2; % Numb. iter. & delta tau per it. (hours) = dth\*3600;disp(['t. 08, Time step : ',num2str(dti),'s']) 8 nit. 9 dti % Analyzed period in seconds = dti\*nit; 10 tt 11 disp(['t. 10, Analyzed per.: ',num2str(tt/3600) ,' h, ',... num2str(tt/3600/24) ,' days']) 12 = tt/3600/24;f=zeros(1,tt/3600); 13 nd % nd = number of days for i = 1:nd % f is the imposed periodic function, f(h = 1:12) 14 f((i-1)\*24+1:(i-1)\*24+12) = sin((1:12)\*pi/12);15 16 end = 1000 ;disp(['t. 16, Spec. capac. : ',num2str(Cp),' J/(kg.K)']); 17 qΩ = 2500 ;disp(['t. 17, Spec. mass : ',num2str(ro),' kg.m-3']) 18 ro 19 = zeros(dK-1,dK-1); % Initialization of the global capacity matrix С if deb==1;disp('t. 19, Call function: ..... fem\_Cae .....');end = 1:size(lK,1) % Glob. capacity mat. assemb., loop on nel elem. 20 21 for n = fem\_Cae(xyz, lK(n,:))\*th\*Cp\*ro; % Cae = element capacity matrix 2.2 Cae for i = 1:423 24 for j=1:4; C(lK(n,i), lK(n,j)) = C(lK(n,i), lK(n,j)) + Cae(i,j); end25 end 26 end % End of capacity matrices assembling 27 % Domain capcity computed from mat. data cap = area\*th\*Cp\*ro\*1e-6; 28 disp(['t. 28, sum(sum(C)) : ',num2str(sum(sum(C))\*1e-6), ' MJ/K']) disp(['t. 29, area\*th\*ro\*Cp: ',num2str(cap), ' MJ/K']); 29 tsmax=ones(1,nit+1)\*tmi;tsmin=tsmax;tmoy=tsmax;gou=tmoy; 30 ih = 0;% 4.04008;% 0;% 31 % Imposed heat load in Wm-2 disp(['t. 32, Impos. Heat : ',num2str(ih), ' W/m-2']) 32 bos = th\*(max(xyz(:,1))-min(xyz(:,1)));% Cross section area upper edge if cs == 2 % Area of the top of the street canvon 33 34 % Area of the top of the street canyon bos = (xyz\_cao(2,1)+xyz\_cao(7,1)-xyz\_cao(1,1)-xyz\_cao(8,1))\*th; 35 36 disp(['t. 35, Loaded area : ',num2str(bos),' m2']) 37 end % lcont = list of radiative nodes K = Kk;mcr = size(lcont,1)-1;lc = zeros(mcr,3);nv = size(Ftot,2); 38 disp(['t. 38, mcr nv : ',num2str([mcr nv ])]); 39 40 % for i = 1:mcr;lc(i,1)=lcont(i,1);lc(i,2)=lcont(i+1,1);lc(i,3)=dK-1;end 41 if rc\*cs>1 % Rad. present in street section (3 sides), on balc. (5 sides) 42 = size(Lel,1);k = 0; % nu = Number radiatives patch sides nu = 1:nu; for i = 1:nci; k = k+1; lon(k) = Lel(j)/nci; end; end 43 for i disp(['t. 45, N. rad. edges: ',num2str(nu)]); disp(['t. 46, rad seg leng.: ',num2str(Lel'),' m']);% fT(2)=280;nfi=2; 44 45 disp(['t. 47, N. rad. elem.: ',num2str(size(lon,2))]) 46 disp(['t. 48, rad sid leng.: ',num2str(lon),' m']) 47 if ra==0 48 % Generation of conductive radiative element matrices 49 for i = 1:mcr % lc = loc. matrix of rad. elem. 50 lc(i,1) = lcont(i,1);lc(i,2) =lcont(i+1,1);lc(i,3) = dK-1; Ker = fem Kcr(xyz,lc(i,:),SBt,tcan); % Elem. rad. mat. for ii = 1:3 51 52 for jj = 1:3 53 54 K(lc(i,ii),lc(i,jj))=K(lc(i,ii),lc(i,jj))+Ker(ii,jj); 55 end 56 end 57 end % End assembling the conductive radiative element matrices 58 end % Computation of K due to inter-element view factors 59 **if** ra == 1 60 gr=zeros(1,dK-1); 61 [K,Qs,Qg] = fem Kra(Kk,lcont,re,Ftot,SBt,tcan,Tsky,lon); gr(lcont) = (Qs' + Qg'); % nodal loads issued by sky & ground : ',num2str(sum(gr),3),' W']) 62 63 disp(['t. 63, sum(gr) if deb==1 64 disp( 't. 65, Call function: ..... fem\_Kra .....') 65 if size(Qs, 2) < 15 66 67 disp(['t. 67, gr : ',num2str(gr(lcont),3),' W']) disp(['t. 68, lcont disp(['t. 69, mean(tcan) : ',num2str(lcont')]) 68 69 : ',num2str(mean(tcan)),' K']) : ',num2str(tcant),' K']) 70 8 tcant=tcan';disp(['t. 70, tcan 71 end 72 end 73 for i = 1:size(lcont, 1) -1 74 Mn(i,1) = Mn(i,1)+Ms(i,1)/2; Mn(i+1,1) = Mn(i+1,1)+Ms(i,1)/2; 75 end % disp(['t. 81, Mn : ',num2str(Mn',3),' W'])

```
: ',num2str(sum(Mn),3),' W'])
 76
             disp(['t. 75, sum(Mn)
77
          end
      end
78
79
     ip = 0.;
     if deb ==1;disp( 't. 95, Call function: ..... fem_Kra .....');end
80
81
     for it = 1:nit % ..... Loop on the time ierations
82
         ip = ip+1;
83
          if ra == 0
             if rc
                              % Add radiative matrix Kr to conductive matrix K
84
                      == 1
                 for ir = 1:mcr
85
86
                      Kr = fem Kcr(xyz,lc(ir,:),SBt,tcan);
87
                      for i=1:\overline{3}
                          for j = 1:3
88
89
                             K(lc(ir,i),lc(ir,j))=K(lc(ir,i),lc(ir,j))+Kr(i,j);
                          end
90
                      end
91
92
                 end
             end
93
          end
94
95
                          % Computation of K due to inter element view factors
          if ra == 1
             [K,Qs,Qg] = fem Kra(Kk,lcont,re,Ftot,SBt,tcan,Tsky,lon);
96
97
             q(lcont) = Qs' + Qq' + Mn;
          end % Injected heat = weights * periodic function f(t)* load * area
98
          if cs < 3; g = gh * f(it) * ih * bos; end % Injected heat</pre>
99
100
          if nfi == 0
                                        % The domain does not contain fixations
             tca = (C + dti*K) \setminus (C*tcan + dti*(q)); % Equation 68
101
102
          else
                                      % Sequence t 114 - t 115 equiv to fem tra
             qr = zeros(ntca,1);
103
104
             for m = 1:size(lcont,1)
105
                gr(lcont(m,1)) = gr(lcont(m,1))+Mn(m,1);
106
              end
             K11
107
                   = K(1:ntca,1:ntca); K12= K(1:ntca,ntca+1:dK);
108
             CC
                   = C(1:ntca,1:ntca); A = (CC + dti*K11);
109
              tcb = A \setminus (CC*tcan(1:ntca, 1) - dti*(K12*fT'+ gr));
             tca = [tcb ; fT' ];
go = K * tca;
110
111
                                                  % Second member of the system
     S
               gou(it) = sum(go(lfi))*dti;
112
                                               % Outgoing heat at iteration it
113
          end
114
          tsmax(it+1) = max (tca(1:dK-nfi)); % min(300,max (tca(1:dK-nfi))); %
115
          tsmin(it+1) = min (tca(1:dK-nfi)); % max(270,min (tca(1:dK-nfi))); %
116
          tmoy (it+1) = mean(tca(1:dK-nfi)); %(tsmin(it+1)+tsmax(it+1))/2; %
117
                    = tca;
          tcan
118
          if ip == dtd % In this iteration, isotherms drawing is generated
119
             tmin = min(tca); tmax = max(tca);
           gt = [tmin pai tmax];ip = 0;
disp(['t 120, Iteration : ',num2str(it),' gt: ',num2str(gt),' K'])
120
121
122
             if deb==1;disp ('t 127, Call function: ..... gra ipa .....');end;
123
             figure
124
             ori = min(xyz(:,1))-.2;
              a = ori-.2;b = ori-.1;ha=max(xyz(:,2)); %.... drawing a left bar
125
126
             fill([a b b a],[0 0 ha ha],[280 280 300 300]);hold on;
127
             for i = 1 : np % ..... Loop on the np CAD patches
128
                 gra ipa(nci,nci,lK((i-1)*nci^2+1:i*nci^2,:),tca',xyz,gt);
129
                  colorbar; hold on
130
             end
             xlabel(['t.139 : ',num2str([max(tca) min(tca)])]);hold on
131
132
             axis equal;axis off
133
             for i = 1:nbo \% ..... Drawing the border of the domain
134
                 if bor(i,4)==0
135
                     plot([xyz(bor(i,1),1) xyz(bor(i,2),1)], ...
136
                      [xyz(bor(i,1),2) xyz(bor(i,2),2)],'k','LineWidth',2)
137
                 end
138
              end % ..... End drawing the border of the domain
139
              title(['Elapsed time : ',num2str(it*dti/3600),' hours']);hold on
140
         end
     end \% ..... End of time iterations
141
     ddt = abs(tmoy(nit+1)-tmi);ah = ddt*cap;
                                                            % DT *th*area *Cp*ro
145
           disp(['t.142, Tmean - Tini : ',num2str(ddt,3),' K'])
143
           disp(['t.143, Stored heat : ',num2str(ah ,3), ' MJ'])
144
145
     if ddt > .1
         disp(['t.145, Min it+1 temp: ',num2str(tsmin(it+1),4),' K'])
disp(['t.146, Max it+1 temp: ',num2str(tsmax(it+1),3),' K'])
if deb==1;disp( 't.148, Call function: .... gra_tev ....');end
146
147
148
149
         gra tev(nit,tt,re,tsmax,tsmin,tmoy);
                                                        % Temperature evolution
150
     end
151
     if nfi > 0
                      % Results shown & displayed only in presence of fixations
         if sum(gou) > 0
152
```

153		disp(['t.152,	Ejected	heat	:	',num2str(sum(gou)*1.e-6,3),' MJ'])
154	end					
155	end					
156	end					

*Table 63: Matlab*<sup> $\odot$ </sup> *function fem\_tir.m – solution of non linear transient equations* 

## **8.3 Postprocessing functions**

After running the procedure *Fiammetta.m*, it is possible to process the results throughout specific sequences of instructions and *ad hoc* Matlab<sup>©</sup> functions.

```
1. CAD patches and labels (see Table 66)
gra_mnl(xyz_cao,car_cao,[0 0 0]);axis equal;axis off % Drawing CAD elem.
title({'CAD elements & labels', ' '})
                                                         % End CAD drawing
   2. Temperature gradient element by element (see Table 67)
figure
                % Drawing the temperature gradients in the meshed domain
gra atg(xyz,lK,tca);gra mel(xyz,lK,0,.8);axis equal;axis off
for i = 1:nbo
                                       % Drawing the border of the domain
    if bor(i,4) ==0
        plot([xyz(bor(i,1),1) xyz(bor(i,2),1)], ...
            [xyz(bor(i,1),2) xyz(bor(i,2),2)],'k','LineWidth',2)
    end
                     % End drawing temperature gradient and domain border
end
```

In the function  $gra\_atg.m$  (*Table 67*), the temperature gradient is computed in the barycenter of the elements and drawn as a blue arrow oriented as the gradient, its length being proportional to the value of the gradient module. It is convenient to call this function only for meshes that do not involve to many elements. The function is also displaying the maximum and the average of the gradient modules.

#### 3. Heat flow element by element (see *Table 68*)

```
xy=xyz;T=tca;
figure
                   % Drawing the element heat flows in the meshed domain
gra ahf(xy ,lK,T,co); gra mel(xy ,lK,0,0);axis equal; hold on
                                       % Drawing the border of the domain
for i = 1:nbo
    if bor(i,4) ==0
        plot([xyz(bor(i,1),1) xyz(bor(i,2),1)], ...
            [xyz(bor(i,1),2) xyz(bor(i,2),2)],'k','LineWidth',2);hold on
    end
% ylabel(['re: ',num2str(re)]);hold on
                      % End drawing element heat flows and domain border
end
   4. Node and element labels (see Table 66)
gra mnl(xyt, [0 0]); axis equal; axis off % Drawing node & el. labels
title({'Finite element mesh & labels',' '})% End N. & el. labels drawing
   5. Displaying nodal temperatures (see Table 65)
                                          % Displaying nodal temperatures
figure;
gra mel(xyz, lK, 1, .9); axis equal; axis off;
for i=1:no;text(xyz(i,1),xyz(i,2),num2str(tca(i),4));hold on;end%or tcan
title({'Nodal temperatures', ' '})
                                               % End temperatures display
```

```
6. Displaying nodal second members (see Table 65)
                                            % Displaying nodal heat loads
figure;
gra mel(xyz,lK,1,.9);axis equal;axis off;qk=round(10*Kk*tca)/10;
for i=1:no
    if qk(i) ~= 0;text(xyz(i,1),xyz(i,2),num2str(qk(i),3));hold on;end
end
title({'Nodal heat loads: gk = Kk*tca (Watt)',' '}) % End heat draw
   7. Drawing isotherms after running Fiammetta.m (see Table 69)
figure;gt =[min(tca(1:no)) pai max(tca(1:no))];
nec = (nni+1)^2;
                                                     % Standard isotherms
for i = 1 : np
                                                    % Loop on CAD patches
    gra ipa(nni+1,nni+1,lK((i-1)*nec+1:nel,:),tca(1:no),xyz,gt);
    hold on
end;axis equal;colorbar;axis off
8. Drawing the boundaries of the domain
for i = 1:nbo
                                       % Drawing the border of the domain
    if bor(i, 4) == 0
        plot([xyz(bor(i,1),1) xyz(bor(i,2),1)], ...
        [xyz(bor(i,1),2) xyz(bor(i,2),2)],'k','LineWidth',2)
    end
end
   9. Drawing a nodal scalar quantity element by element (see Table 70)
figure;gra lin(xyz,nel,lK,tca)
                                        % nodal scalar quantity isotherms
   10. Drawing isotherms after running Fiammetta v01.m
figure;colormap(gra cob);gra ipa(nx,ny,lK,tca,xyz,[270 2 320]);
colorbar; axis equal; axis off
   11. Drawing the boundaries of the domain after running Fiammetta v01.m
plot ([xyz(1,1) xyz(nx+1,1) xyz(nx+1,1) xyz(1,1) xyz(1,1)],[xyz(1,2) ...
    xyz(nx+1,2) xyz((nx+1)*(ny+1),2) xyz((nx+1)*(ny+1),2) xyz(1,2)],...
    'k','LineWidth',3);hold on;axis off;axis equal
   12. Drawing heat flows on the street section boundary
figure;hst=K*tca;bar(hst(lcont));hold on
title (['Street boundary nodal heat flows, total: ',...
    num2str(sum(hst), 3) ' (W)'])
   13. Drawing the Sky or Ground View Factors on street walls
figure;bar(SVF);grid on;hold on % max (SVF)
title (['Street section sky view factors, average:' ,num2str(mean(SVF),3)])
figure('Position', [100 100 900 400]); bar(SVF); grid on; hold on % max (SVF)
title (['Street side with balcony sky view factors, average:',...
    num2str(mean(SVF),3)])
```

figure('Position',[100 100 900 400]);bar(F(:,n3-1));grid on;hold on

title (['Street side with balcony ground view factors, average:',...
num2str(mean(F(:,n3-1)),3)])
14. Drawing injected heat evolution (see Table 70)
gra\_hie(nit,tt,ga) % Drawing heat input evolution

Table 64: Postprocessing functions

The postprocessing functions of *Table 64* are listed in *Table 65* to *Table 70*.



Table 65: Matlab<sup>©</sup> function gra mel.m - drawing a shrunk mesh

Matlab<sup>©</sup> function gra\_mnl.m - displaying nodes and element labels function [] = gra\_mnl(xyz, IK, lc) % Display node and elements labels
figure; gra\_mel(xyz, IK, 1, .9) % Draw conductive elements and nodes labels
if lc(1,3) > 0; gra\_mel(xyz, lc, 2, .8); axis equal; axis off; end
for i=1:size(xyz, 1); text(xyz(i, 1), xyz(i, 2), num2str(i)); hold on; end
end

Table 66: Matlab<sup>©</sup> function gra\_mnl.m - displaying node & element labels

Matlab<sup>©</sup> function gra atg.m – temperature gradients [] = gra atg (xyz, lK, tca)% Element temperatures gradient arrows function = size(lK,1);% nel = 1;% 2 nel 3 = zeros(nel,1);v=zeros(nel,1);xx=zeros(nel,1);yy=zeros(nel,1); u for ii = 1:nel 4 % Loop on the nel elements Q = [xyz(lK(ii,1),1:2); xyz(lK(ii,2),1:2); xyz(lK(ii,3),1:2); ... 5 6 xyz(lK(ii,4),1:2)]; 7 X = Q(:,1);Y = Q(:,2);xx(ii) = sum(Q(:,1))/4;yy(ii) = sum(Q(:,2))/4; 8 te = [tca(lK(ii,1)) tca(lK(ii,2)) tca(lK(ii,3)) tca(lK(ii,4))]; 9  $J = [ [-1 \ 1 \ 1 \ -1] * X$ [-1 1 1 -1]\*Y;... % Jacobian matrix barycenter 10 [-1 -1 1 1]\*X [-1 -1 1 1]\*Y]/2; gr = [-1 1 1 -1;-1 -1 1 1]\*te'/2; % Parametric gradient at barycenter 11  $g = J^{(-1)}*gr; u(ii) = g(1); v(ii) = g(2);$ 12 end 13 14 scale = 2;quiver(xx,yy,u,v,scale,'b','LineWidth',1);hold on; 15 gm = [max(sqrt(u.\*u+v.\*v)) mean(sqrt(u.\*u+v.\*v))];% grad: max & average title(['Temperature gradient, max: ',num2str(gm(1),2),', mean: ',... num2str(gm(2),2),' K/m'],'fontsize',15);axis off;hold on disp(['Temp. grad. maximum : ', num2str(gm(1),3),', mean: ',... 16 17 18 num2str(gm(2),3),' K/m']) 19 20

Table 67: Matlab<sup>©</sup> function gra\_atg.m - visualization of temperature gradient arrows

```
Matlab<sup>C</sup> function gra ahf.m - visualization of heat flow arrows in a mesh
     function [] = gra ahf (xyz, lK, tca, co)
                                                           % Element heat flows arrows
1
2
             = size(lK, 1);
     nel
3
             = zeros(nel,1);v=zeros(nel,1);xx=zeros(nel,1);yy=zeros(nel,1);
     11
4
            = zeros(nel,1);
     area
     for ii = 1:nel
5
                                                           % Loop on the nel elements
6
         Q = [xyz(lK(ii,1),1:2);xyz(lK(ii,2),1:2);xyz(lK(ii,3),1:2);...
             xyz(lK(ii,4),1:2)];
7
8
         Х
                   = Q(:,1);
                                                  = O(:,2);
                  = sum(Q(:,1))/4; yy(ii) = sum(Q(:,2))/4;
9
         xx(ii)
         area(ii) = (X(2) - X(1) + X(3) - X(4)) / 2* (Y(3) - Y(1));
10
11
                   = [tca(lK(ii,1)) tca(lK(ii,2)) tca(lK(ii,3)) tca(lK(ii,4))];
         te
                   = 1/2*[[-1 1 1 -1]*X [-1 1 1 -1]*Y;...
[-1 -1 1 1]*X [-1 -1 1 1]*Y];
= [-1 1 1 -1; -1 -1 1 1]*te'/2;% Parametric grad. barycenter
12
         J
13
14
         qr
                   = -co(ii) *J^{(-1)} *gr;
15
         q
16
         u(ii)
                   = g(1); v(ii)
                                       = g(2);
17
     end
     scale = 2;quiver(xx,yy,u,v,scale,'r','LineWidth',1);hold on;
18
19
     ad
             = sum(area);
                                                            % Maximum & mean heat flow
           = [max(sqrt(u.*u+v.*v)) sqrt(u.*u+v.*v)'*area/ad]; % disp(gm(2)^2)
20
     qm
    title(['TA heat flows, max: ', num2str(gm(1),2),', mean: ',...
num2str(mean(sqrt(u.*u+v.*v)),2),' W/m2'],'fontsize',15);hold on
21
22
23
     disp(['h 23, Max heat flow: ', num2str(gm(1),2),', mean: ',...
24
         num2str(mean(sqrt(u.*u+v.*v)),2),' W/m2'])
25
```

Table 68: Matlab<sup>©</sup> function gra\_ahf.m - visualization of heat flow arrows

Matlab<sup> $\square$ </sup> function gra *ipa.m* - drawing isotherm lines in a meshed Coons patch function [] = gra ipa (nx, ny, el, z, xyz, gt) % Isotherms lines in a patch 1 2 xx = zeros(ny+1,nx+1);yy = xx;mp = xx ;tn = ones(ny+1,nx+1)\*z(1);ii = 0; 3 for j = 1:ny for i = 1:nx 4 5 ii = ii+1;= el(ii,1); mp(j ,i+1) = el(ii,2); 6 mp(j , i) 7 mp(j+1, i+1) = el(ii, 3); mp(j+1, i)= el(ii,4); 8 end 9 end 10 for j = 1 : nx+1 = 1 : ny+1 11 for i 12 xx(i,j) = xyz(mp(i,j),1);yy(i,j) = xyz(mp(i,j),2);13 tn(i,j) = z(mp(i,j));14 end; end 15 16 colormap(gra cob); % Color map definition 17 = contourf(xx,yy,tn,(gt(1):gt(2):gt(3)),'b');hold on;axis equal [CS,H] clabel(CS,H,[ 280 285 290 295 300 305 310 315 320]); 18 19 end

Table 69: Matlab<sup>©</sup> function gra\_ipa.m - drawing isotherms in a meshed Coons patch

	Matlab <sup>©</sup> function <i>gra_lin.m</i> - visualization of the levels of a function
1	<pre>function[] = gra lin(xyz,nel,lK,tca)% Visualization element by element</pre>
2	colormap(gra cob)
3	for i = 1:nel
4	fill(xyz(lK(i,:),1)',xyz(lK(i,:),2)',tca(lK(i,:)));hold on;
5	end;
6	<pre>% fill([-199 -1],[0 0 1 1],[300 300 320 320]);hold on;</pre>
7	colorbar;axis equal;axis off
8	end

Table 70: Matlab<sup>©</sup> function gra\_lin.m - visualization of the levels of a scalar function

## 8.4 Illustrative input data

In this section, we collect representative input data used in the examples. These data are organized in section including an identification number Gi and the name of the concerned problem.

CAD data inserted at the start of Fiammetta.m with the function cad gin.m function[xyz cao,car cao,nbo,Me,Di,Ne,Co,nvn,nnr] = cad gin(Gi) 1 **if** Gi == 1 2 % ..... 1. Standard cavity ..... 3 xyz cao = [0 0;3 0;3 3;0 3;1 1;2 1;2 2;1 2]; 4 car cao = [6 5 1 2;6 2 3 7;7 3 4 8;1 5 8 4];nbo = 12; 5 Me = 3;Di = 1;Ne = 0;Co = 0;nvn = 0;nnr = 0; disp([ 'Standard cavity, Gi: ',num2str(Gi)]) 6 7 end 8 if Gi == 2 9 8 ...... 1. Standard cavity ..... 10 xyz cao = [0 0;3 0;3 3;0 3;1 1;2 1;2 2;1 2]; 11 car cao = [6 5 1 2;6 2 3 7;7 3 4 8;1 5 8 4];nbo = 12; 12 Me = 3;Di = 1;Ne = 0;Co = 2;nvn = 1;nnr = 0; 13 disp([ 'Standard cavity, Gi: ',num2str(Gi)]) 14 end 15 if Gi == 3 16 % ..... C shape three patches ..... 17 xyz cao = [2 2;2 3;1 2;0 3;0 0;1 1;3 0;3 1];% CAD 18 car cao = [1 2 4 3;3 4 5 6;7 8 6 5]; nbo = 10; 19 Me = 1;Di = 6;Ne = 0;Co = 0;nvn = 0;nnr = 0; 20 disp([' C shape, 3 patches, Gi: ',num2str(Gi)]) 21 end 2.2 **if** Gi == 4 23 % ...... 1. Standard cavity ..... 2.4 xyz\_cao = [0 0;3 0;3 3;0 3;1 1;2 1;2 2;1 2]; car\_cao = [6 5 1 2;6 2 3 7;7 3 4 8;1 5 8 4];nbo = 12; 25 26 Me = 1; Di = 4; Ne = 0; Co = 0; nvn = 0; nnr = 0;27 disp([ 'Standard cavity, Gi: ',num2str(Gi)]) 28 end 29 **if** Gi == 5 30 % ..... 5. C shape diag top left ..... 31 . . . . . . . . . . . . . . . . . . xyz\_cao = [3 2;3 3;0 3;1 2;0 1;1 1;2 1;0 0;1 0;2 0]; car cao = [1 2 3 4;4 3 5 6;6 5 8 9; 6 9 10 7];nbo=13; 32 33 Me = 1;Di = 5;Ne = 0;Co = 0;nvn = 0;nnr = 0; 34 disp([ 'C shape, 4 patches, Gi: ',num2str(Gi)]) 35 end 36 if Gi == 637 %.... 9. Standard trapezoidal ..... 38 ha = 1;xyz cao = [0 0;1 0;.75 ha;.25 ha]; 39 car cao = [1 2 3 4 ]; nbo = 4; 40 Me = 1;Di = 7;Ne = 0;Co = 1;nvn = 2;nnr = 0; 41 disp([ 'Standard trapezoidal shape, Gi: ',num2str(Gi)]) 42 end 43 **if** Gi == 7 44 45 xyz cao = [0 0;1 0;0 1;1 1;0 2;1 2]; 46 car cao = [1 2 4 3;3 4 6 5];nbo =7; 47 Me = 3;Di = 7;Ne = 0;Co = 3;nvn = 2;nnr = 0; 48 disp(['Standard rect. 2 squares, Gi: ',num2str(Gi)]) 49 end 50 if Gi == 8 51 % ...... 8. Standard rect. 1 rectangle ..... 52 ha = 2;xyz cao = [0 0;1 0;1 ha;0 ha]; 53 car\_cao = [1 2 3 4 ];nbo=4; 54 Me = 1;Di =13;Ne = 0;Co = 1;nvn = 2;nnr = 0; 55 disp([ 'Standard 1 rect., Gi: ',num2str(Gi)]) 56 end 57 **if** Gi == 9 58 % ...... 9. Standard rect. 1 rectangle ..... 59 ha = 2;xyz\_cao = [0 0;1 0;1 ha;0 ha]; car\_cao = [1 2 3 4 ];nbo=4; 60 61 Me = 1; Di = 3; Ne = 0; Co = 0; nvn = 0; nnr = 0;62 disp([ 'Standard 1 rect., Gi: ',num2str(Gi)]) 63 end 64 **if** Gi == 10 65 66 xyz\_cao = [0 0;1 0;0 1;1 1;0 2;1 2]; 67 car\_cao = [1 2 4 3;3 4 6 5];nbo =7; 68 Me = 4;Di = 9;Ne = 0;Co = 4;nvn = 1;nnr = 1; 69 disp(['Standard rect. 2 squares, Gi: ',num2str(Gi)]) 70 end 71 if Gi == 11 72 % ..... 1. Standard cavity ..... 73 = [0 0;3 0;3 3;0 3;1 1;2 1;2 2;1 2]; = [6 5 1 2;6 2 3 7;7 3 4 8;1 5 8 4];nbo = 12; xvz cao 74 car cao 75

```
Me = 5;Di = 0;Ne = 1;Co = 0;nvn = 0;nnr = 0;
76
77
         disp([ 'Standard cavity, Gi: ',num2str(Gi)])
78
     end
79
     if Gi == 12
     % ...... 12. Rectangular cavity .....
80
        xyz_cao = [0 0;3 0;3 6;0 6;1 1;2 1;2 5;1 5];
car_cao = [6 5 1 2;6 2 3 7;7 3 4 8;1 5 8 4];nbo = 12;
81
82
         car cao
         Me = 5; Di = 8; Ne = 0; Co = 0; nvn = 0; nnr = 0;
83
         disp([ 'Rectangular cavity, Gi: ',num2str(Gi)])
84
         % cs : 0 = noth., 1 = cavity: 2 = str.
85
86
     end
87
     if Gi == 13
     % ..... 12. Rectangular cavity .....
88
        xyz_cao = [0 0;3 0;3 6;0 6;1 1;2 1;2 5;1 5];
car_cao = [6 5 1 2;6 2 3 7;7 3 4 8;1 5 8 4];nbo = 12;
89
90
         car_cao
         Me = 3;Di = 8;Ne = 0;Co = 0;nvn = 0;nnr = 0;
91
92
         disp([ 'Rectangular cavity, Gi: ',num2str(Gi)])
     end
93
94
     if Gi == 14
95
     % ..... 11. Street section
        xyz cao = [0 8;1 8;0 0;1 1;5 0;4 1;5 8;4 8];nbo = 10;
96
97
         car cao = [2 1 3 4; 4 3 5 6; 6 5 7 8];
     Me = 5;Di = 0;Ne = 11;Co = 0;nvn = 0;nnr = 0;
disp(['Street section, Gi: ',num2str(Gi)])
98
99
100
     end
101
     if Gi == 15
102
     % ..... 11. Street section
                                                                 . . . . . . . . . . . . . . . .
        xyz_cao = [0 8;1 8;0 0;1 1;5 0;4 1;5 8;4 8];nbo = 10;
103
         car_cao = [2 \ 1 \ 3 \ 4; 4 \ 3 \ 5 \ 6; \ 6 \ 5 \ 7 \ 8];
104
        Me = 3;Di = 0;Ne = 11;Co = 0;nvn = 0;nnr = 0;
105
106
     disp(['Street section, Gi: ',num2str(Gi)])
107
     end
108
     if Gi == 16
109
     % ...... 16. Thermal bridge .....
        xyz_cao = [-2 5; -2 6;4 5;4 6;8 6;8 8;14 6;14 8;4 0;8 0;4 12;8 12];
110
         car_cao = [1 3 4 2;3 5 6 4;5 7 8 6;9 10 5 3;4 6 12 11];nbo = 16;
111
112
         Me = 2;Di = 2;Ne = 0;Co = 5;nvn = 1;nnr = 1;
113
         disp([ 'Thermal bridge, Gi: ',num2str(Gi)])
114
     end
115
     if Gi == 17
     % ..... 17. Horizontal rectangle .....
116
       ha = 1;xyz cao = [0 0;2 0;2 ha;0 ha];
117
         car_cao = [1 2 3 4 ];nbo=4;
Me = 3;Di = 0;Ne = 0;Co = 0;nvn = 0;nnr = 0;
118
119
        disp([ 'Horizon. 1 rect., Gi: ',num2str(Gi)])
120
121
     end
122
     if Gi == 18
     % ..... 18. Thermal bridge .....
123
        xyz_cao = [-2 5; -2 6;4 5;4 6;8 6;8 8;14 6;14 8;4 0;8 0;4 12;8 12];
124
         car_cao = [1 3 4 2;3 5 6 4;5 7 8 6;9 10 5 3;4 6 12 11];nbo = 16;
125
126
         Me = 1; Di = 11; Ne = 0; Co = 5; nvn = 2; nnr = 0;
        disp([ 'Thermal bridge, Gi: ',num2str(Gi)])
127
     end
128
129
     if Gi == 19
130
     % ..... 19. Thermal bridge .....
        xyz cao = [-2 5; -2 6; 4 5; 4 6; 8 6; 8 8; 14 6; 14 8; 4 0; 8 0; 4 12; 8 12];
131
         car cao = [1 3 4 2;3 5 6 4;5 7 8 6;9 10 5 3;4 6 12 11];nbo = 16;
132
         Me = 2;Di =10;Ne = 0;Co = 5;nvn = 1;nnr = 2;
133
134
        disp([ 'Thermal bridge, Gi: ',num2str(Gi)])
     end
135
136
     if Gi == 20
     % ..... 19. Thermal bridge .....
137
138
        xyz cao = [-2 5; -2 6;4 5;4 6;8 6;8 8;14 6;14 8;4 0;8 0;4 12;8 12];
         car cao = [1 3 4 2;3 5 6 4;5 7 8 6;9 10 5 3;4 6 12 11];nbo = 16;
139
         Me = 3;Di =7;Ne = 0;Co = 5;nvn = 2;nnr = 0;
140
        disp([ 'Thermal bridge, Gi: ',num2str(Gi)])
141
142
     end
143
     if Gi == 21
144
     % ..... 16. Thermal bridge .....
        xyz cao = [-2 5; -2 6; 4 5; 4 6; 8 6; 8 8; 14 6; 14 8; 4 0; 8 0; 4 12; 8 12];
145
         car_cao = [1 3 4 2;3 5 6 4;5 7 8 6;9 10 5 3;4 6 12 11];nbo = 16;
146
         Me = 4;Di = 2;Ne = 0;Co = 5;nvn = 1;nnr = 1;
147
        disp([ 'Thermal bridge, Gi: ',num2str(Gi)])
148
149
     end
150
     if Gi == 22
151
     % ..... 16. Thermal bridge .....
         xyz cao = [-2 5; -2 6;4 5;4 6;8 6;8 8;14 6;14 8;4 0;8 0;4 12;8 12];
152
```

Table 71: Matlab<sup>©</sup> function cad gin.m: input data - definition of domains

Dirichlet boundary conditions inserted with the function cad Dir.m function [lfi,fT] = cad Dir(Di,no,nvn,car cao,bor,pbo,nni) 1 % disp(['LD 2, num. nod side: ',num2str(nni)]) 2 % General data ..... 3 % nnc = 5 ; 4 % Number of fixed nodes on the horizontal sides % disp(['L 25, N.fix h.-side: ',num2str(nnc)]) 5 6 if Di == 0 lfi(1)=0;fT(1)=0;nf=0; 7 8 end 9 if Di == 1 10 lfi = [car cao(3,2) bor(pbo(3,2),5):bor(pbo(3,2),6) car cao(3,3)];nf = size(lfi,2);fT = ones(1,nf)\*300; 11 12 end 13 if Di == 2 fT =[280 300];lfi=[no+1 no+2];nf=2; % Fixation of two virtual nodes 14 disp(['LD 15, Fixed nodes : ',num2str(lfi)])
disp(['LD 16, Fix. temper. : ',num2str(fT),' K']); 15 16 17 end 18 if Di == 319 nnc = 5;% nnc = the number of fixed nodes on the horizontal sides 20 if nni < nnc;nnc = nni;end</pre> 21 = [car cao(1,3) bor(pbo(1,3),5):bor(pbo(1,3),6) car cao(1,4)]; а 22 = [car cao(1,1) bor(pbo(1,1),5):bor(pbo(1,1),6) car cao(1,2)]; b 23 nx = min(nnc,nni+3);lfi=[b(nni+3-nx:nni+2) a(nni+3-nx:nni+2)]; 24 nf = size(lfi,2);fT = [ones(1,nf/2)\*270 ones(1,nf/2)\*320]; disp(['LD 23, N. fix. nodes: ',num2str(nf)]) 25 26 end 27 if Di == 4 2.8 lfi = [[car\_cao(1,3) bor(pbo(1,3),5):bor(pbo(1,3),6) car\_cao(1,4)]'; [car\_cao(3,2) bor(pbo(3,2),5):bor(pbo(3,2),6) car\_cao(3,3)]']'; 29 30 nf = size(lfi,2);fT = [ones(1,nf/2)\*270 ones(1,nf/2)\*300]; 31 end 32 **if** Di == 5 lfi=[car\_cao(1,1) bor(pbo(1,1),5):bor(pbo(1,1),6) car\_cao(1,2)... 33 34 car cao(4,3) bor(pbo(4,3),5):bor(pbo(4,3),6) car cao(4,4)]; 35 nf = size(lfi, 2);if nf > 2 ;fT = [ones(1,nf/2)\*300 ones(1,nf/2)\*310 ];end 36 37 end if Di == 6 38 39 lfi=[car cao(1,1) bor(pbo(1,1),5):bor(pbo(1,1),6) car cao(1,2)... 40 car cao(3,1) bor(pbo(3,1),5):bor(pbo(3,1),6) car cao(3,2)]; 41 nf = size(lfi,2); if nf > 2 ;fT = [ones(1,nf/2)\*300 ones(1,nf/2)\*310 ];end 42 43 end 44 if Di == 7 45 fT =[300 280];lfi=[no+1 no+2];nf=2; % Fix. of both virt. nodes end 46 47 if Di == 8 48 lfi=[car cao(1,3) bor(pbo(1,3),5):bor(pbo(1,3),6) car cao(1,4)]; 49 nf = size(lfi,2);fT = ones(1,nf)\*300; % Dirichlet boundary conditions disp(['LD 50, N. fix. nodes: ',num2str(nf)])
disp(['LD 51, av. imp. temp: ',num2str(mean(fT)),' K']) 50 51 52 end 53 if Di == 9 54 fT =[280 300];lfi=[no+1 no+2];nf=2; % Fix. of 2 virt. nodes disp(['LD 53, Fixed nodes : ',num2str(lfi)])
disp(['LD 54, Fix. temper. : ',num2str(fT),' K']); 55 56 57 end 58 if Di == 10 59 fT =[270 270 300];lfi=[no+1 no+2 no+3];nf=3; % Fix. of 3 virt. nodes disp(['LD 58, Fixed nodes : ',num2str(lfi)])
disp(['LD 59, Fix. temper. : ',num2str(fT),' K']); 60 61 62 end 63 if Di == 11 % Fixation of two virtual nodes fT =[300 280];lfi=[no+1 no+2];nf=2; 64 disp(['LD 63, Fixed nodes : ',num2str(lfi)])
disp(['LD 64, Fix. temper. : ',num2str(fT),' K']); 65 66 67 end

68 if Di == 12 fT =300;lfi=no+1 ;nf=1; 69 % Fixation of one virtual nodes disp(['LD 68, Fixed nodes : ',num2str(lfi)])
disp(['LD 69, Fix. temper. : ',num2str(fT),' 70 71 K'l); 72 end 73 if Di == 13 fT =[300 270];lfi=[no+1 no+2];nf=2; % Fixation of two virtual nodes 74 disp(['LD 73, Fixed nodes : ',num2str(lfi)])
disp(['LD 74, Fix. temper. : ',num2str(fT),' K']); 75 76 77 end 78 % if nfi < 7;disp(['L 73, fix. top side: ',num2str(lfi)]);end 79 % bc = [[car cao(1,1) bor(pbo(1,1),5):bor(pbo(1,1),6) car cao(1,2)]; 80 [car cao(2,4) bor(pbo(2,4),5):bor(pbo(2,4),6) car cao(2,1)]; 8 81 [car\_cao(3,4) bor(pbo(3,4),5):bor(pbo(3,4),6) car\_cao(3,1)]; 2 [car\_cao(4,2) bor(pbo(4,2),5):bor(pbo(4,2),6) car\_cao(4,3)]]; 82 2 % disp(['L 78, n.fix. cavity: ',num2str(size(bc))]) 83 84 % fT = zeros(1,no); lfi = zeros(1,no); 85 if Di > 13 if nvn == 0 86 % lfi = uni-line matrix, fT = uni-line matrix 87 lfi = [[car cao(1,3) bor(pbo(1,3),5):bor(pbo(1,3),6) car cao(1,4)]'; [car cao(3,2) bor(pbo(3,2),5):bor(pbo(3,2),6) car cao(3,3)]']'; 88 89 nf = size(lfi,2)/2;fT=[ones(nf,1)\*270;ones(nf,1)\*300]; 8 mfi = [car\_cao(3,2) bor(pbo(3,2),5):bor(pbo(3,2),6) car\_cao(3,3)]; 90 91 end 92 if nvn == 1 93 8 lfi = [car cao(1,3) bor(pbo(1,3),5):bor(pbo(1,3),6) car cao(1,4)]'; nfi=size(lfi,2);fT=ones(1,nfi)\*280; 94 8 95 % % DOF of the 1. Standard cavity 96 % bc = [[car\_cao(1,1) bor(pbo(1,1),5):bor(pbo(1,1),6) car\_cao(1,2)]; 97 [car cao(2,4) bor(pbo(2,4),5):bor(pbo(2,4),6) car cao(2,1)]; 응 98 [car\_cao(3,4) bor(pbo(3,4),5):bor(pbo(3,4),6) car\_cao(3,1)]; 8 99 [car cao(4,2) bor(pbo(4,2),5):bor(pbo(4,2),6) car cao(4,3)]]; 8 100 101 end 102 % if nvn == 2 % Dirichlet boundary conditions for convection % fT =[270 300];lfi=[no+1 no+2]; % Fixation of 2 virtual nodes 103 % end 104 105 if nvn == 3fT=[270 285 300]; lfi=[no+1 no+2 no+3]; % Fixation of 3 virtual nodes 106 end 107 nfi = size(lfi,2);disp(['LD106, N. fix. nodes: ',num2str(nfi)]) 108 109 if nfi > 0 110 **if** nfi < 15 disp(['LD109, Numb. fix. N.: ',num2str(nf)]) 111 disp([ LD105, Numb. Fix. N.: , Num2str(NI;)]) disp(['LD110, Fixed nodes : ',num2str(lfi)]) disp(['LD111, Fix. temper. : ',num2str(fT),' K']); 112 113 114 end 115 end 116 end 117 end

Table 72: Dirichlet boundary conditions, function cad Dir.m

```
Neumann boundary conditions inserted with the function cad Neu.m
     function [gh,bos] = cad Neu(Ne,dK,car_cao,pbo,bor,th,xyz_cao)
1
                 ..... Neumann boundary conditions
2
     8.....
3
    if Ne == 1
4
        gh = zeros(dK, 1);
                                                  % second member initialization
        lg = [car cao(3,2) bor(pbo(3,2),5):bor(pbo(3,2),6) car cao(3,3)];
5
6
        nh = size(lg,2);np=nh-1;g(1)=1/(2*np);g(nh)=g(1);g(2:nh-1)=1/np;
         gh(lg(1:nh)) = g(1:nh)/sum(g);
7
8
        bos = (xyz cao(2,1) - xyz cao(1,1)) * th;
9
        disp(['N
                    9, Loaded area : ',num2str(bos),' m2'])
10
    end
11
    if Ne == 11
12
        gh = zeros(dK, 1);
        lg = [car_cao(3, 3) bor(pbo(3,3),5):bor(pbo(3,3),6) car_cao(3,4)...
car_cao(1, 1) bor(pbo(1,1),5):bor(pbo(1,1),6) car_cao(1,2)];
13
14
15
         nh = size(lg, 2)/2;
                                             % Loaded nodes lg for CAD model 11
16
    ę
         lg = [car cao(3,2) bor(pbo(3,2),5):bor(pbo(3,2),6) car cao(3,3)];
          nh = size(lg, 2);
17
    응
                                    gh(lg(1,i),1) = 2; end % Weights right side
18
         for i
                          = 1:nh;
         gh(lg(1,1),1)
                         = 1 ; gh(lg(1,nh),1) = 1;
19
20
         gh(lg(1:nh))
                          = gh(lg(1:nh))/sum(gh(lg(1:nh)));
21
         for i
                          = nh+1:2*nh;gh(lg(1,i),1) = 2; end% Weights left side
22
        gh(lg(1,nh+1),1) = 1; gh(lg(1,2*nh),1) = 1;
```



Table 73: Data - Neumann boundary conditions, function cad Neu.m

```
Convection boundary conditions to be inserted in Fiammetta.m
     if nnv == 1 %..... Convection towards 1 virtual nodes
127
128
         % Convection on the right side
         bd = [[car cao(4,2) bor(pbo(4,2),5):bor(pbo(4,2),6) car cao(4,3)];
129
130
               [car cao(3,1) bor(pbo(3,1),5):bor(pbo(3,1),6) car cao(3,2)];
               [car cao(3,2) bor(pbo(3,2),5):bor(pbo(3,2),6) car cao(3,3)];
131
               [car_cao(3,3) bor(pbo(3,3),5):bor(pbo(3,3),6) car_cao(3,4)];
132
133
               [car cao(5,2) bor(pbo(5,2),5):bor(pbo(5,2),6) car cao(5,3)]];
                                       % Generation of the convective elements
134
         lc = zeros(nci, 3); nco = 0;
135
         C(ndK,ndK)
                          = 1;
                                          % Capacity of the fluid virtual node
                                                      % Loop on the conv edges
136
                           = 1:size(bd,1)
               ic
         for
             for ie
                                          % Loop on the nci elements of a side
137
                          = 1:nci
138
                          = nco+1;
                 nco
139
                 lc(nco,1) = bd(ic,ie);
140
                 lc(nco,2) = bd(ic,ie+1);
                 lc(nco, 3) = ndK;
141
142
             end
143
         end
144
         disp(['L 144, Num. conv el.: ',num2str(nco)])
                                                                % Stored in lc
             %..... End convection towards 1 virtual nodes
     end
145
127
     if nnv == 2 %..... Convection on both sides with 2 virtual nodes
         bt = [[car cao(4,2) bor(pbo(4,2),5):bor(pbo(4,2),6) car cao(4,3)];
128
129
               [car cao(3,1) bor(pbo(3,1),5):bor(pbo(3,1),6) car cao(3,2)];
130
               [car_cao(3,2) bor(pbo(3,2),5):bor(pbo(3,2),6) car_cao(3,3)];
131
               [car cao(3,3) bor(pbo(3,3),5):bor(pbo(3,3),6) car cao(3,4)];
132
               [car cao(5,2) bor(pbo(5,2),5):bor(pbo(5,2),6) car cao(5,3)];
133
               [car cao(5,4) bor(pbo(5,4),5):bor(pbo(5,4),6) car cao(5,1)];
               [car cao(1,3) bor(pbo(1,3),5):bor(pbo(1,3),6) car_cao(1,4)];
134
135
               [car_cao(1,4) bor(pbo(1,4),5):bor(pbo(1,4),6) car_cao(1,1)];
136
               [car cao(1,1) bor(pbo(1,1),5):bor(pbo(1,1),6) car cao(1,2)];
               [car_cao(4,4) bor(pbo(4,4),5):bor(pbo(4,4),6) car_cao(4,1)]];
137
         nec = (nci) * size(bt, 1);
138
                                           % Taking into account the conv elem.
139
         ncc = size(bt,1);he = ones(1,nec)*h;
140
              = [0 0 h/2 h 0 0 h h/2 0 0]; % hv = ones(1,ncc)*h;%
         hv
               disp(['L 160, Conv. c. p.s.: ',num2str(hv),' W/(m2K)'])
141
142
         lc = zeros(nec, 3); nco = 0;
                                       % Generation of the convective elements
                                          % Capacity of the fluid virtual node
         C(ndK,ndK)
                          = 1;
143
                          = 1:size(bt,1)
144
         for
                ic
                                                      % Loop on the conv edges
145
             for ie
                           = 1:nci
                                           % Loop on the nci elements of a side
                           = nco+1;
146
                 nco
                 lc(nco,1) = bt(ic,ie);
147
148
                 lc(nco,2) = bt(ic,ie+1);
149
                 lc(nco, 3) = ndK;
                 he (1, nco) = hv(ic);
150
151
             end
152
         end
153
         for i = 1:nec/2
154
             lc(i, 3) = ndK - 1; lc(nec/2 + i, 3) = ndK;
155
         end
         disp(['L 149, Num. conv el.: ',num2str(nco)])
156
                                                                % Stored in lc
     end % End option nnv = 2: 2 sides of the domain linked to 2 virtual nodes
157
158
     if nnv
                > 2 %..... Convection towards nnv virtual nodes
159
                 = zeros(nec*nnv,3);
         lc
160
                 = [car_cao car_cao(:,1)]; % patch + first node (N: 1 2 3 4 1)
         capet
         for ic = 1 : nnv % Vector nc contains the list of convective sides
161
162
                = [2 4]; % Left & right sides are convective % nc = [1 2 3 4]
             nc
163
             li = [caoet(1, nc(1, ic)) bor(pbo(1, nc(ic)), 5):...
164
                  bor(pbo(1,nc(ic)),6) caoet(1,nc(ic)+1)];
```

```
165
             nec = size(li, 2)-1;
166
             disp(['L 135,Num. conv. elem.: ',num2str(nec)])
167
              for i=1:nec
168
                 lc(i+(ic-1)*nec, 1) = li(i);
                 lc(i+(ic-1)*nec,2) = li(i+1);
169
                 lc(i+(ic-1)*nec,3) = no+ic;
170
171
             end
172
             lic((ic-1)*nec+1:ic*nec)=li(1:nec); % lic = list conv. sides nodes
173
         end
         if size(lic,2) < 12;disp(['L 167, Conv. nodes</pre>
                                                         : ',num2str(lic)]);end
174
           lic = [car_cao(2,2) bor(pbo(2,2),5):bor(pbo(2,2),6) car cao(2,3)];
175
     2
176
         nnc = nnv*(nci); % nec = number of nodes connected for convection
177
         disp(['L 150, Num. conv. elem.: ',num2str(nnc)])
178
     end
```

*Table 74: Data - Convection boundary conditions:* nnv = 1, 2, nnv > 2

# **8.6 Additional procedures**

In pure conduction problems, the solution of the heat transfer problems is independent of the geometric scale. However, in radiation as well as in convection, the size of the domain has to be given because the convective and radiative conduction matrices (1.43) and (1.58) depend on the size *L* of these elements.

As a convective element, a radiative element may have any orientation. Its length is L, its thickness e, and the Stefan-Boltzmann coefficient  $\sigma$  ( $Wm^{-2}K^{-4}$ ). The node sequence of an element starts with the two real nodes pertaining to the mesh and finishes with the virtual one. The function fem\_Kcr.m (Table 75) computes the radiation matrices of an element as pseudo convection matrices. The third argument of the function is the product of the Stefan-Boltzmann constant and the thickness. The temperatures are stored in the vector tca (argument 4). The xyz matrix contains the node coordinates and lc is the localization matrix of the element.

	Matlab <sup>©</sup> function <i>fem_Kcr.m</i> – radiative boundary element matrix	
1	<pre>function [K] = fem Kcr(xyz,lc,SBt,tca)%K is integrated on the bound. segm.</pre>	
2	Q = [xyz(lc(1), 1:3); xyz(lc(2), 1:3)]; % Vector of element extremities	
3	L = norm(Q(2,:)-Q(1,:));  % Length of the element	
4	T1 = (tca(lc(1))+tca(lc(2)))/2;	
5	tv = tca(lc(3));	
6	co = (T1^2+tv^2) * (T1+tv) *L*SBt;	
7	$K = [2 \ 1 \ -3; 1 \ 2 \ -3; -3 \ -3 \ 6] * co/6;$	
8	end	

Table 75: Matlab<sup>©</sup> function fem Kcr.m, radiative - conductive element matrix

Because radiative boundary conditions lead to a nonlinear system of equation, a new Matlab<sup> $\bigcirc$ </sup> function *fem\_snl.m* is needed to solve the system (*Table 76*).

Matlab<sup>©</sup> function *fem snl.m* - solution of the nonlinear radiative system function [tca] = fem snl(Kk,gh,lfi,fT,xyz,lK,lcont,nnr,nnv,nci,np,SB) 1 2 disp(['Ls 2, list f. nodes: ',num2str(lfi)])
disp(['Ls 3, Fix. temper. : ',num2str(fT),' K']) 3 4, N. fixed nod.: ',num2str(nfn)]) 4 nfn = size(lfi,2); disp(['Ls = size(lcont,1)-1;disp(['Ls 5, N. rad elem. : ',num2str(ner)]) 5 ner 6 dK = size(Kk,1); % Kk is the pure conductivity matrix % Number of unknowns of the system to solved 7 = dK - nnr - nnv; no 8 = zeros(nnr,round(sqrt(no))); % lic 9 % for ii=1:nnr % Loop on the sides involving radiation conditions = ii+2; if j==5; j=1; end 10 8 lic(ii,:) = [car cao(1,ii+1) bor(pbo(1,ii+1),5):bor(pbo(1,ii+1),6)... 11 ÷ % List of the DOF of the irradiated patch side 12 응 car cao(1,j)]; 13 % end 14 = zeros(ner,3); % Localization matrix of the radiative elements 1c 15 Κ = Kk; % Pure conductivity matrix 16 tcant = [ones(1,no)\*fT(1) fT]; % Initial temperature field for iter = 1 : 2 ;disp(['LS 17, Iteration N. : ',num2str(iter),' / 2']) 17 % Generation of cond. rad. element matrices 18 for n = 1:nnr 19 for i = 1:nerlc(i,1) = lcont(i,1); lc(i,2) = lcont(i+1,1); lc(i,3) = no+n;20 21 Ker = fem Kcr(xyz,lc(i,:),SB,tcant); % Elem cond rad matr. 22 for ii = 1:3

```
for jj = 1:3
23
                              K(lc(i,ii),lc(i,jj))=K(lc(i,ii),lc(i,jj))+Ker(ii,jj);
24
                         end
25
26
                    end % End assembling the conductive radiative element matrices
27
               end
28
          end
                  = size(lfi,2); N = zeros(nf,dK);
29
          nf
                                                             % Linear const. for fixations
30
          for i = 1:nf ; N(i,lfi(i))=1 ; gh(dK+i)=fT(i);end;
          A = [K N'; N zeros(nf,nf)] ; B = A\gh ;tca = B(1:dK);
disp(['Ls 32, Dissipation : ',num2str(-B'*gh,3),' WK'])
disp(['Ls 33, React. flows : ',num2str(B(dK+1:dK+nfn)',3),' W'])
31
32
33
34
                  = [min(tca), round((max(tca)-min(tca))/2)/10, max(tca)];
          gt
35
                 = nci*nci;figure;
          nc2
          for i = 1 : np
               i = 1 : np % ..... Loop on the np CAD patches
gra_ipa(nci,nci,lK((i-1)*nc2+1:i*nc2,:),tca,xyz,gt);
36
37
38
               colorbar; hold on
39
          end
40
          title(['Iteration: ',num2str(iter),', dissipation: ',...
               num2str(tca'*K*tca,3),' WK']);axis off
41
          disp(['Ls 42, Dissipation : ',num2str(tca'*K*tca,3),' WK'])
disp(['Ls 43, max - min tca: ',num2str(max(tca)-min(tca),3),' K'])
42
43
44
          tcant = [tca(1:no,1); fT']; % Store temp. of solid for next iteration
45
     end
                                                                          % End of iterations
46
     end
```

*Table 76: Matlab<sup>©</sup> function fem\_snl.m - solution of the nonlinear radiative system* 

The *fem\_snl.m* function performs the required iterations to take into account the non-linearity of the *"conduction"* - *"radiation"* problem. All the iterations may provide an isotherm drawing.

## 8.7 List of Matlab<sup>©</sup> procedures

Fiammetta_20210929.m	Table 58
Fiammetta_33_20210830.m	Table 1
cad_Dir.m	Table 17
cad_Neu.m	Table 18
cad_ban.m	Table 26
cad_bou.m	Table 9
cad_con.m	Table 19
cad_edg.m	Table 16
cad_gin.m	Table 71
cad_mes.m	Table 15
fem_Cae.m	Table 20
fem_Kco.m	Table 11
fem_Kcr.m	Table 75
fem_Kcv.m	Table 6
fem_Kra.m	Table 57
fem_caK.m	Table 51
fem_rsm.m	Table 52
fem_snl.m	Table 76
fem_til.m	Table 62
fem_tir.m	Table 63
fem_tit.m	Table 60
fem_tra.m	Table 25
geo_baf.m	Table 42
geo_stf.m	Table 38
geo_vfr.m	Table 29
geo_vfc.m	Table 27
gra_Hfl.m	
gra Tgr.m	

gra_ahf.m	Table 68
gra_atg.m	Table 67
gra_cob.m	Table 2
gra_hie.m	Table 23
gra_ipa.m	Table 69
gra_ist.m	Table 3
gra_lin.m	Table 70
gra_mel.m	Table 65
gra_mnl.m	Table 66
gra_tev.m	Table 22
mat_cok.m	Table 8

Table 77: Matlab<sup>©</sup> procedures and functions related to Fiammetta

### 8.8 Exercises proposed in 2020

#### 8.8.1 Steady State Conduction

#### Exercise 1: Playing with boundary conditions

Impose fluxes on the four sides, and a temperature on a single node. What happens if the fluxes are balanced (what comes in from the left and above is equal, respectively, to what comes out from the right and from below)? What happens if the fluxes are no longer in equilibrium (for example: incoming flow on all four sides)? In both cases, vary the imposed temperature, and observe the generalized fluxes around the area.

#### 8.8.2 Steady State Heat Transfer

#### Exercise 2: Building thermal bridges

Define a vertical strip of insulating material and a horizontal strip of highly conductive material, the intersection of which is at the center of the domain. This intersection will first be considered as insulating, then as very conductive. The boundary conditions are: a temperature of 273 K on the left and 298 K on the right, the upper and lower sides being considered adiabatic. Examine gradients and fluxes in the domain.

#### 8.8.3 Coons Patch Based Structured Mesh

#### Exercise 3: Free convection node in a cavity

We consider a square cavity two meters side surrounded by a wall 0.2 m thick. The outside air temperature is 273 K. The indoor air temperature is free. Play on the convection coefficients and on the conductivity of the wall. The lower side (the ground) is considered at temperature of 293 K; you can also apply a constant flux (heated floor). Note that the radiative aspects are not taken into account in this exercise.

#### 8.8.4 Transient Heat Transfer

#### Exercise 4: Balconies and cooling fins

A concrete slab crosses an exterior wall to form a balcony. The outside temperature varies according to a sinusoidal function (273 K at midnight, 288 K at noon). The interior temperature is left free. The initial temperature is equal to 273 K. Show how it varies, with a delay which depends, in particular, on thermal capacities. Note that the radiative aspects are not taken into account in this exercise.

#### 8.8.5 Gray Body Radiation

#### Exercise 5: Radiation through a cavity

A flow of heat passes through a concrete block in the center of which is a cavity. Show how the emissivity of the interior walls of the cavity affects the flows and temperatures in the concrete block. What happens for a zero or unitary emissivity?

# 8.9 Exercises proposed in 2021

#### 8.9.1 Steady state conduction

Exercise 1: Nodes, elements and Dirichlet boundary conditions

Using an explicit definition of the nodal coordinates, the mesh and the fixations, formulate a problem on a domain composed of more than 5 elements.

#### 8.9.2 Steady state heat transfer including conduction and convection

Exercise 2: Same problem as exercise 1, but convection elements are present on a part of the boundary and the Dirichlet boundary conditions are applied only on the virtual convective nodes so that all the nodes of the domain are free.

#### 8.9.3 Coons Patch Based Structured Mesh

#### Exercise 3: Utilization of the Matlab<sup>©</sup> procedure Fiammetta

Using the same domain shape as in the first exercise, it is asked to reproduce the same boundary conditions now applied on the patches sides and to study the convergence when the number of variables is increasing. Plot the convergence curve in logarithmic coordinates. A comment about the shape of this curve is welcome.

#### 8.9.4 Transient Heat Transfer

#### Exercise 4: Heating and cooling fins

A domain has the same shape as the capital letter E, with thick vertical part and very thin horizontal ones. These parts are immerged in three fluids with low temperature on the top and bottom parts. The middle part is immerged in a high temperature fluid. All the temperatures of the mesh are free and the boundaries of the vertical part are adiabatic. Both isotherm and heat flows graphics have to be computed and displayed, the first from a very fine mesh and the second with a relatively coarse mesh.

#### 8.9.5 Gray Body Radiation

#### Exercise 5: Radiation through a cavity

A heat flow is crossing a concrete block in the center of which is a cavity. Show how the emissivity of the interior walls of the cavity affects the heat flows and temperatures in the concrete block. What happens in extreme situations where the emissivity is zero or equal to one?

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